

## CLC2011, CLC4011

## Low Power, Low Cost, Rail-to-Rail I/O Amplifiers

## **General Description**

The CLC2011 (dual) and CLC4011 (quad) are ultra-low cost, low power, voltage feedback amplifiers. At 2.7V, the CLCx011 family uses only 136µA of supply current per amplifier and are designed to operate from a supply range of 2.5V to 5.5V (±1.25 to ±2.75). The input voltage range exceeds the negative and positive rails.

The CLCx011 family of amplifiers offer high bipolar performance at a low CMOS prices. They offer superior dynamic performance with 4.9MHz small signal bandwidths and 5.3V/ps slew rates. The combination of low power, high bandwidth, and rail-to-rail performance make the CLCx011 amplifiers well suited for battery-powered communication/computing systems.

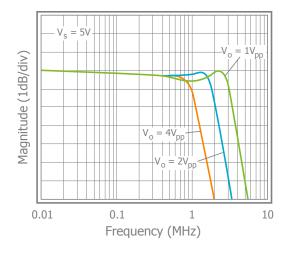
#### **FEATURES**

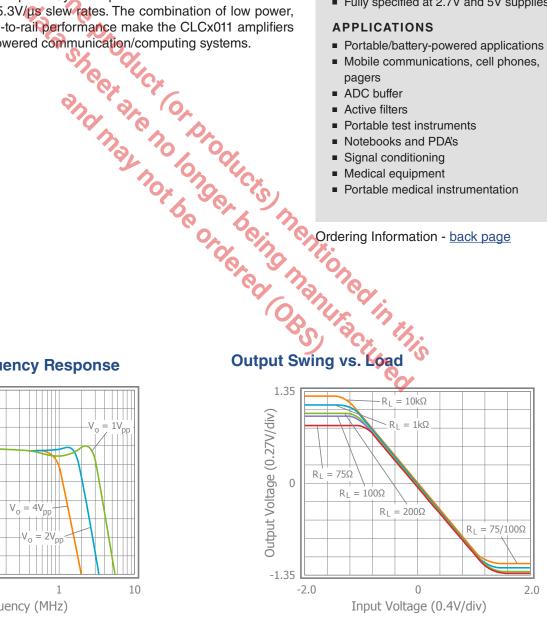
- 136µA supply current
- 4.9MHz bandwidth
- Output swings to within 20mV of either rail
- Input voltage range exceeds the rail by >250mV
- 5.3V/µs slew rate
- 21nV/√Hz input voltage noise
- ±35mA linear output current
- Fully specified at 2.7V and 5V supplies

#### **APPLICATIONS**

- Portable/battery-powered applications
- Mobile communications, cell phones,

## **Large Signal Frequency Response**





### **Absolute Maximum Ratings**

Stresses beyond the limits listed below may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

V <sub>S</sub>	0V to 6V
V <sub>IN</sub>	$V_S$ - 0.5V to + $V_S$ +0.5V
Continuous Output Current	40mA to +40mA

### **Operating Conditions**

Supply Voltage Range	2.5 to 5.5V
Operating Temperature Range	40°C to 125°C
Junction Temperature	150°C
Storage Temperature Range	65°C to 150°C
Lead Temperature (Soldering, 10s)	260°C

### **Package Thermal Resistance**

rent40mA to +40mA	θ <sub>JA</sub> (SOIC-8)	150°C/W
	θ <sub>JA</sub> (MSOP-8)	200°C/W
	θ <sub>JA</sub> (SOIC-14)	90°C/W
<b>&gt;</b>	θ <sub>JA</sub> (TSSOP-14)	100°C/W
dan po	Package thermal resistance ( $\theta_{\text{JA}}$ ), JEDEC stest boards, still air.	standard, multi-layer
Shoot	ESD Protection	
Ox Cx	CLC2011, CLC4011 (HBM)	2kV
8h 8. 6.	ESD Rating for HBM (Human Body Model).	
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CLC2011, CLC4011 (HBM)	2kV
ESD Rating for HBM (Human Body Model).	

## **Electrical Characteristics at +2.7V**

 $T_A=25^{\circ}C,\,V_S=+2.7V,\,R_f=R_g=5k\Omega,\,R_L=10k\Omega\;to\;V_S/2;\,G=2;\,unless\;otherwise\;noted.$ 

Symbol	Parameter	Conditions	Min	Тур	Max	Units		
Frequency D	Frequency Domain Response							
UGBW <sub>SS</sub>	Unity Gain -3dB Bandwidth	$G = +1, V_{OUT} = 0.02V_{pp}$		4.9		MHz		
BW <sub>SS</sub>	-3dB Bandwidth	G = +2, V <sub>OUT</sub> = 0.2V <sub>pp</sub>		3.2		MHz		
BW <sub>LS</sub>	Large Signal Bandwidth	G = +2, V <sub>OUT</sub> = 2V <sub>pp</sub>		1.4		MHz		
GBWP	Gain Bandwidth Product	$G = +11, V_{OUT} = 0.2V_{pp}$		2.5		MHz		
Time Domaii	n Response							
t <sub>R</sub> , t <sub>F</sub>	Rise and Fall Time	V <sub>OUT</sub> = 1V step; (10% to 90%)		163		ns		
t <sub>S</sub>	Settling Time to 0.1%	V <sub>OUT</sub> = 1V step		500		ns		
OS	Overshoot	V <sub>OUT</sub> = 1V step		<1		%		
SR	Slew Rate	1V step		5.3		V/µs		
Distortion/No	pise Response	·						
HD2	2nd Harmonic Distortion	10kHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		-72		dBc		
HD3	3rd Harmonic Distortion	10kHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		-72		dBc		
THD	Total Harmonic Distortion	10kHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		0.03		%		
e <sub>n</sub>	Input Voltage Noise	>10kHz		21		nV/√Hz		
	8/2 8	Channel to Channel, V <sub>OUT</sub> = 2V <sub>pp</sub> , f = 10kHz		82		dB		
X <sub>TALK</sub>	Crosstalk	Channel to Channel, V <sub>OUT</sub> = 2V <sub>pp</sub> , f = 50kHz		74		dB		
DC Performa	ance	70 70						
V <sub>IO</sub>	Input Offset Voltage	/ 0/		0.5		mV		
d <sub>VIO</sub>	Average Drift	12 0h 40"		5		μV/°C		
I <sub>B</sub>	Input Bias Current	(1) (1) (1) (1)		90		nA		
dl <sub>B</sub>	Average Drift	00 00		32		pA/°C		
PSRR	Power Supply Rejection Ratio	DC OO	55	83		dB		
A <sub>OL</sub>	Open Loop Gain	V <sub>OUT</sub> = V <sub>S</sub> / 2		90		dB		
I <sub>S</sub>	Supply Current	per channel		136		μΑ		
Input Charac	cteristics	(ex 12 10						
R <sub>IN</sub>	Input Resistance	Non-inverting	•	12		ΜΩ		
C <sub>IN</sub>	Input Capacitance	100 05	<b>?</b>	2		pF		
CMIR	Common Mode Input Range	10 SCH	This	-0.25 to 2.95		V		
CMRR	Common Mode Rejection Ratio	DC	6	81		dB		
Output Char			0					
		$R_L = 10k\Omega$ to $V_S / 2$		0.02 to 2.68		V		
V <sub>OUT</sub>	Output Voltage Swing	$R_L = 1k\Omega$ to $V_S/2$		0.05 to 2.63		V		
		$R_L = 200\Omega$ to $V_S / 2$		0.11 to 2.52		V		
I <sub>OUT</sub>	Output Current			±30		mA		

## **Electrical Characteristics at +5V**

 $T_A=25^{\circ}C,\,V_S=+5V,\,R_f=R_g=5k\Omega,\,R_L=10k\Omega\;to\;V_S/2;\,G=2;unless\;otherwise\;noted.$ 

Symbol	Parameter	Conditions	Min	Тур	Max	Units		
Frequency [	Frequency Domain Response							
UGBW <sub>SS</sub>	Unity Gain -3dB Bandwidth	G = +1, V <sub>OUT</sub> = 0.02V <sub>pp</sub>		4.3		MHz		
BW <sub>SS</sub>	-3dB Bandwidth	G = +2, V <sub>OUT</sub> = 0.2V <sub>pp</sub>		3.0		MHz		
BW <sub>LS</sub>	Large Signal Bandwidth	$G = +2$ , $V_{OUT} = 2V_{pp}$		2.3		MHz		
GBWP	Gain Bandwidth Product	$G = +11, V_{OUT} = 0.2V_{pp}$		2.5		MHz		
Time Doma	in Response							
t <sub>R</sub> , t <sub>F</sub>	Rise and Fall Time	V <sub>OUT</sub> = 1V step; (10% to 90%)		110		ns		
t <sub>S</sub>	Settling Time to 0.1%	V <sub>OUT</sub> = 2V step		470		ns		
OS	Overshoot	V <sub>OUT</sub> = 1V step		<1		%		
SR	Slew Rate	2V step		9		V/µs		
Distortion/N	loise Response							
HD2	2nd Harmonic Distortion	10kHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		-73		dBc		
HD3	3rd Harmonic Distortion	10kHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		-75		dBc		
THD	Total Harmonic Distortion	10kHz, V <sub>OUT</sub> = 1V <sub>pp</sub>		0.03		%		
e <sub>n</sub>	Input Voltage Noise	>10kHz		22		nV/√Hz		
V	O	Channel to Channel, V <sub>OUT</sub> = 2V <sub>pp</sub> , f = 10kHz		82		dB		
X <sub>TALK</sub>	Crosstalk	Channel to Channel, V <sub>OUT</sub> = 2V <sub>pp</sub> , f = 50kHz		74		dB		
DC Perform	ance	70 70						
V <sub>IO</sub>	Input Offset Voltage	6 %	-8	1.5	8	mV		
d <sub>VIO</sub>	Average Drift	2- 20 40*		15		μV/°C		
I <sub>B</sub>	Input Bias Current	0, 0		90	450	nA		
dl <sub>B</sub>	Average Drift	00 1/2		40		pA/°C		
PSRR	Power Supply Rejection Ratio	DC O	55	85		dB		
A <sub>OL</sub>	Open Loop Gain	V <sub>OUT</sub> = V <sub>S</sub> / 2		80		dB		
I <sub>S</sub>	Supply Current	per channel		160	235	μΑ		
Input Chara	cteristics	PO 12 102						
R <sub>IN</sub>	Input Resistance	Non-inverting	•	12		MΩ		
C <sub>IN</sub>	Input Capacitance	100 VE	?*	2		рF		
CMIR	Common Mode Input Range	S. 80%		-0.25 to 5.25		V		
CMRR	Common Mode Rejection Ratio	DC	58	80		dB		
Output Cha	racteristics		0/					
		$R_L = 10k\Omega$ to $V_S / 2$	0.08 to 4.92	0.04 to 4.96		V		
V <sub>OUT</sub>	Output Voltage Swing	$R_L = 1k\Omega$ to $V_S/2$		0.07 to 4.9		V		
		$R_L = 200\Omega$ to $V_S / 2$		0.14 to 4.67		V		
I <sub>OUT</sub>	Output Current			±35		mA		

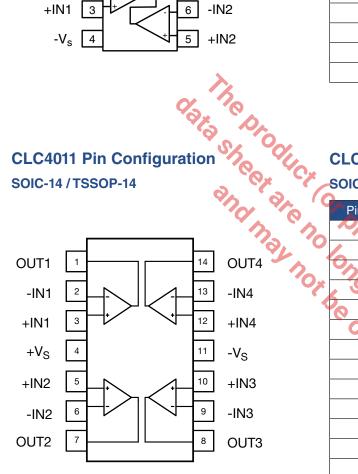
## **CLC2011 Pin Configurations** SOIC-8 / MSOP-8

#### OUT1 1 8 +V<sub>s</sub> -IN1 7 OUT2 2 +IN1 6 -IN2 3

## **CLC2011 Pin Assignments**

SOIC-8 / MSOP-8

Pin No.	Pin Name	Description	
1	OUT1	Output, channel 1	
2	-IN1	Negative input, channel 1	
3	+IN1	Positive input, channel 1	
4	-V <sub>S</sub>	Negative supply	
5	+IN2	Positive input, channel 2	
6	-IN2	Negative input, channel 2	
7	OUT2	Output, channel 2	
8	+V <sub>S</sub>	Positive supply	



## **CLC4011 Pin Assignments**

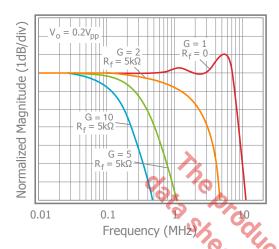
SOIC-14 / TSSOP-14

Pin No.	Pin Name	Description		
	OUT1 Output, channel 1			
2 0/	-IN1	Negative input, channel 1		
3	+IN1	Positive input, channel 1		
40	+V <sub>S</sub>	Positive supply		
5 6	+IN2	Positive input, channel 2		
06	-IN2	Negative input, channel 2		
70	OUT2	Output, channel 2		
8	OUT3	Output, channel 3		
9	-IN3	Negative input, channel 3		
10	+lN3	Positive input, channel 3		
11	-Vs	Negative supply		
12	+IN4	Positive input, channel 4		
13	-IN4	Negative input, channel 4		
14	OUT4	Output, channel 4		

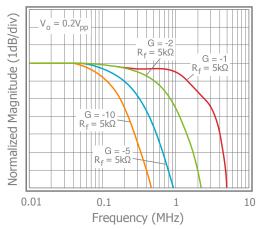
### **Typical Performance Characteristics**

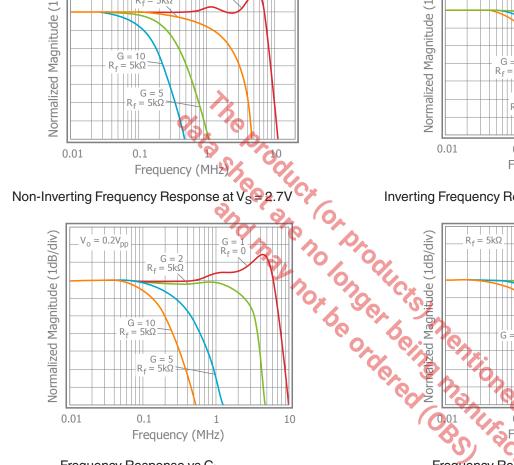
 $T_A$  = 25°C,  $V_S$  = +2.7V,  $R_f$  =  $R_g$  = 5k $\Omega$ ,  $R_L$  = 10k $\Omega$  to  $V_S$ /2; G = 2; unless otherwise noted.

Non-Inverting Frequency Response at  $V_S = 5V$ 

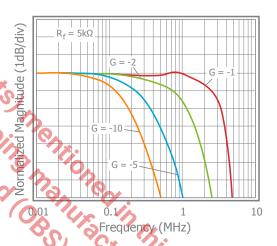


Inverting Frequency Response at  $V_S = 5V$ 

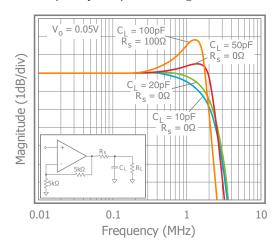




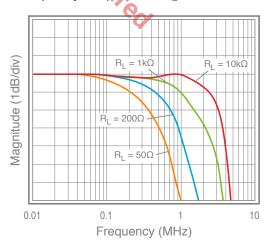
Inverting Frequency Response at V<sub>S</sub> = 2.7V



#### Frequency Response vs CL



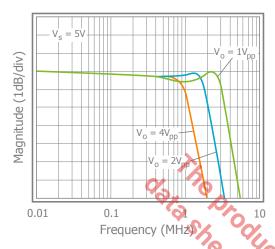
Frequency Response vs RL



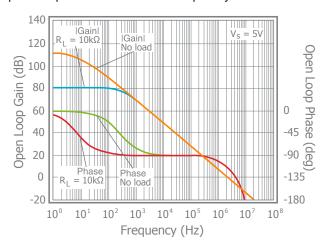
## **Typical Performance Characteristics**

 $T_A = 25^{\circ}C$ ,  $V_S = +2.7V$ ,  $R_f = R_g = 5k\Omega$ ,  $R_L = 10k\Omega$  to  $V_S/2$ ; G = 2; unless otherwise noted.

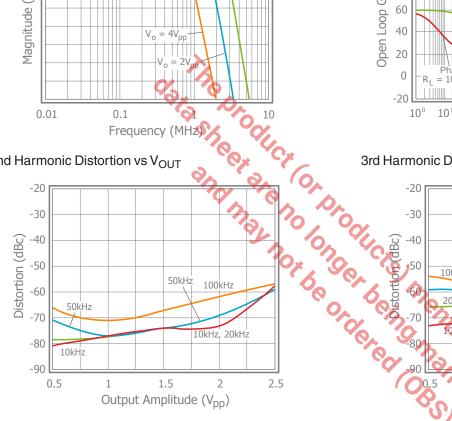
#### Frequency Response vs. VOUT



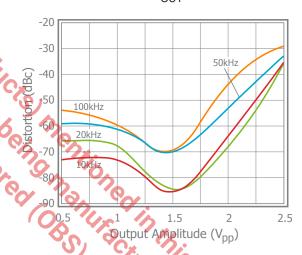
#### Open Loop Gain & Phase vs. Frequency



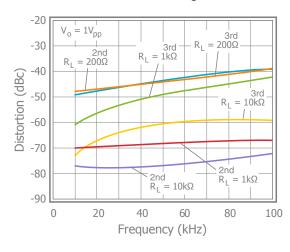
## 2nd Harmonic Distortion vs $V_{OUT}$



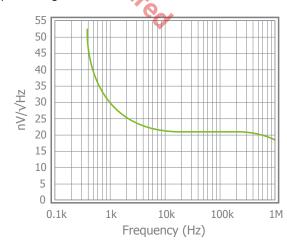
3rd Harmonic Distortion vs VOUT



### 2nd & 3rd Harmonic Distortion at $V_S = 2.7V$



### Input Voltage Noise



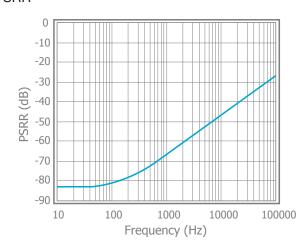
## **Typical Performance Characteristics**

 $T_A$  = 25°C,  $V_S$  = +2.7V,  $R_f$  =  $R_g$  = 5k $\Omega$ ,  $R_L$  = 10k $\Omega$  to  $V_S$ /2; G = 2; unless otherwise noted.

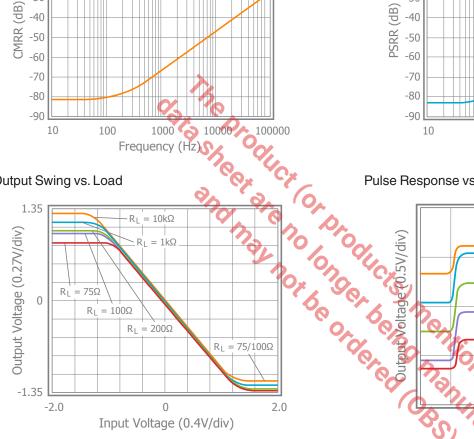
#### **CMRR**



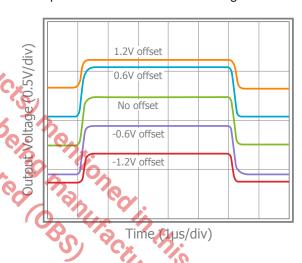
#### **PSRR**



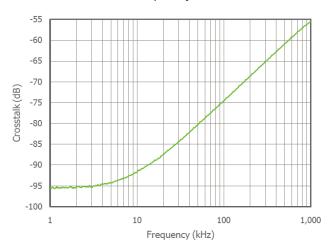
## Output Swing vs. Load



#### Pulse Response vs. Common Mode Voltage



#### Crosstalk vs. Frequency



#### **Application Information**

#### **General Description**

The CLCx011 family of amplifiers are single supply, general purpose, voltage-feedback amplifiers. They are fabricated on a complimentary bipolar process, feature a rail-to-rail input and output, and are unity gain stable.

#### **Basic Operation**

Figures 1, 2, and 3 illustrate typical circuit configurations for non-inverting, inverting, and unity gain topologies for dual supply applications. They show the recommended bypass capacitor values and overall closed loop gain equations. Figure 4 shows the typical non-inverting gain circuit for single supply applications.

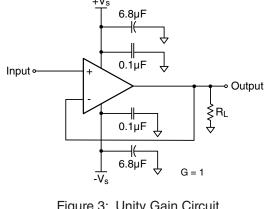


Figure 3: Unity Gain Circuit

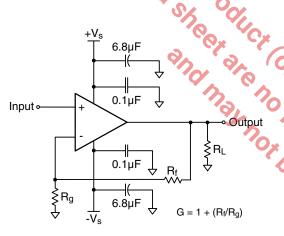
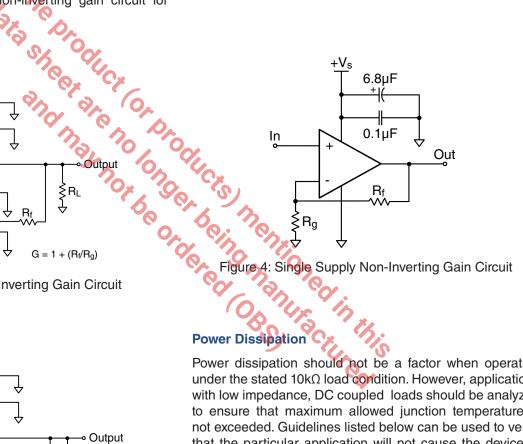


Figure 1: Typical Non-Inverting Gain Circuit



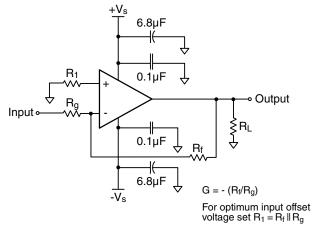


Figure 2: Typical Inverting Gain Circuit

Power dissipation should not be a factor when operating under the stated  $10k\Omega$  load condition. However, applications with low impedance, DC coupled loads should be analyzed to ensure that maximum allowed junction temperature is not exceeded. Guidelines listed below can be used to verify that the particular application will not cause the device to operate beyond it's intended operating range.

Maximum power levels are set by the absolute maximum junction rating of 150°C. To calculate the junction temperature, the package thermal resistance value Theta, IA  $(\theta_{AA})$  is used along with the total die power dissipation.

$$T_{Junction} = T_{Ambient} + (\theta_{JA} \times P_D)$$

Where T<sub>Ambient</sub> is the temperature of the working environment.

In order to determine  $P_D$ , the power dissipated in the load needs to be subtracted from the total power delivered by the supplies.

$$P_D = P_{supply} - P_{load}$$

Supply power is calculated by the standard power equation.

$$P_{\text{supply}} = V_{\text{supply}} \times I_{\text{RMSsupply}}$$

$$V_{\text{supply}} = V_{\text{S-}} + V_{\text{S-}}$$

Power delivered to a purely resistive load is:

$$P_{load} = ((V_{load})_{RMS^2})/Rload_{eff}$$

The effective load resistor (Rload<sub>eff</sub>) will need to include the effect of the feedback network. For instance, Rload<sub>eff</sub> in Figure 3 would be calculated as:

These measurements are basic and are relatively easy to perform with standard lab equipment. For design purposes however, prior knowledge of actual signal levels and load impedance is needed to determine the dissipated power. Here,  $P_D$  can be found from

Quiescent power can be derived from the specified  $I_{\rm S}$  values along with known supply voltage,  $V_{\text{supply}}$ . Load power can be calculated as above with the desired signal amplitudes using:

$$(V_{load})_{RMS} = V_{peak} / \sqrt{2}$$

$$(I_{load})_{BMS} = (V_{load})_{BMS} / Rload_{eff}$$

The dynamic power is focused primarily within the output stage driving the load. This value can be calculated as:

$$P_{Dvnamic} = (V_{S+} - V_{load})_{RMS} \times (I_{load})_{RMS}$$

Assuming the load is referenced in the middle of the power rails or  $V_{\text{supply}}/2$ .

The CLC2011 is short circuit protected. However, this may not guarantee that the maximum junction temperature (+150°C) is not exceeded under all conditions. Figure 5 shows the maximum safe power dissipation in the package vs. the ambient temperature for the packages available.

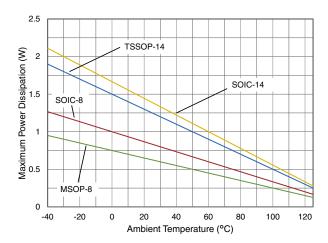


Figure 5. Maximum Power Derating

#### **Input Common Mode Voltage**

The common mode input range extends to 250mV below ground and to 250mV above Vs, in single supply operation. Exceeding these values will not cause phase reversal. However, if the input voltage exceeds the rails by more than 0.5V, the input ESD devices will begin to conduct. The output will stay at the rail during this overdrive condition. If the absolute maximum input voltage (700mV beyond either rail) is exceeded, externally limit the input current to  $\pm 5$ mA as shown in Figure 6.

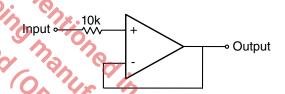


Figure 6. Circuit for Input Current Protection

#### **Driving Capacitive Loads**

Increased phase delay at the output due to capacitive loading can cause ringing, peaking in the frequency response, and possible unstable behavior. Use a series resistance,  $R_S$ , between the amplifier and the load to help improve stability and settling performance. Refer to Figure 7.

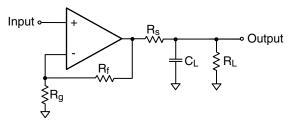


Figure 7. Addition of RS for Driving Capacitive Loads

Table 1 provides the recommended  $R_{\rm S}$  for various capacitive loads. The recommended  $R_{\rm S}$  values result in approximately <1dB peaking in the frequency response. The Frequency Response vs. CL plot, on page 6, illustrates the response of the CLCx011.

C <sub>L</sub> (pF)	R <sub>S</sub> (Ω)	-3dB BW (MHz)
10pF	0	2.2
20pF	0	2.4
50pF	0	2.5
100pF	100	2

Table 1: Recommended Rs vs. C<sub>I</sub>

For a given load capacitance, adjust R<sub>S</sub> to optimize the tradeoff between settling time and bandwidth. In general, reducing R<sub>S</sub> will increase bandwidth at the expense of additional overshoot and ringing.

#### **Overdrive Recovery**

An overdrive condition is defined as the point when either one of the inputs or the output exceed their specified voltage range. Overdrive recovery is the time needed for the amplifier to return to its normal or linear operating point. The recovery time varies, based on whether the input or output is overdriven and by how much the range is exceeded. The CLCx011 will typically recover in less than 50ns from an overdrive condition. Figure 8 shows the CLC2011 in an overdriven condition.

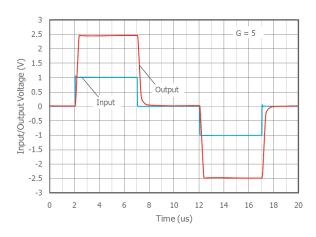


Figure 8: Overdrive Recovery

#### **Layout Considerations**

General layout and supply bypassing play major roles in high frequency performance. Exar has evaluation boards to use as a guide for high frequency layout and as an aid in device testing and characterization. Follow the steps below as a basis for high frequency layout:

- Include 6.8μF and 0.1μF ceramic capacitors for power supply decoupling
- Place the 6.8µF capacitor within 0.75 inches of the power pin
- Place the 0.1µF capacitor within 0.1 inches of the power pin
- Remove the ground plane under and around the part, especially near the input and output pins to reduce parasitic capacitance
- Minimize all trace lengths to reduce series inductances

Refer to the evaluation board layouts below for more information.

#### **Evaluation Board Information**

The following evaluation boards are available to aid in the testing and layout of these devices:

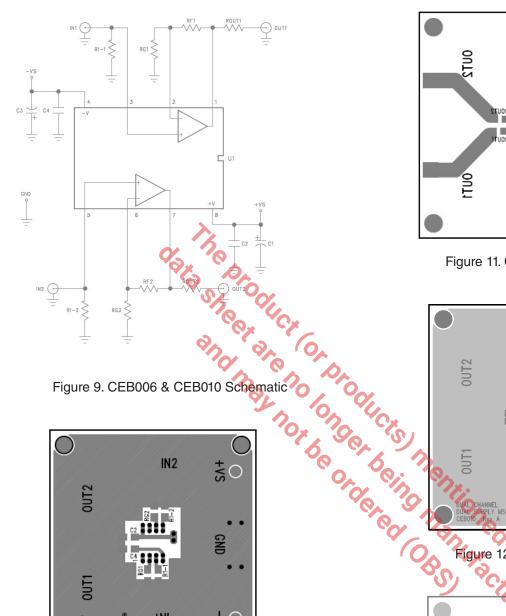
Evaluation Board #	Products
CEB006	CLC2011 in SOIC
CEB010	CLC2011 in MSOP
CEB019	CLC4011 in TSSOP
CEB018	CLC4011 in SOIC

#### **Evaluation Board Schematics**

Evaluation board schematics and layouts are shown in Figures 9-16 These evaluation boards are built for dual-supply operation. Follow these steps to use the board in a single-supply application:

- 1. Short -V<sub>S</sub> to ground.
- Use C3 and C4, if the -V<sub>S</sub> pin of the amplifier is not directly connected to the ground plane.

exar.com/CLC2011



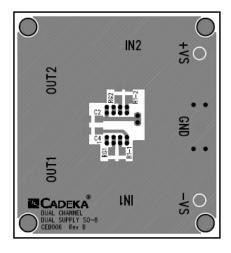


Figure 10. CEB006 Top View

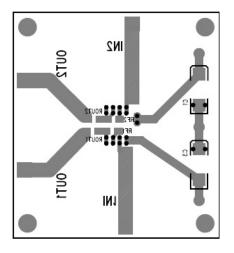


Figure 11. CEB006 Bottom View

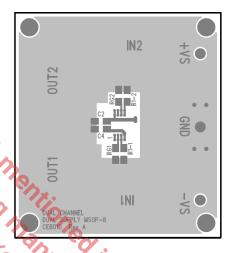


Figure 12, CEB010 Top View

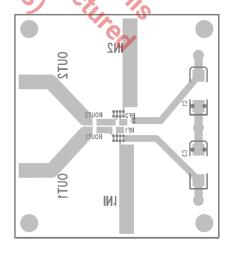
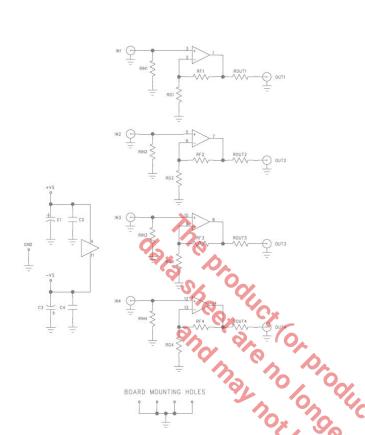


Figure 13. CEB010 Bottom View



238 238

Figure 16. CEB018 Bottom View

Figure 14. CEB018 Schematic

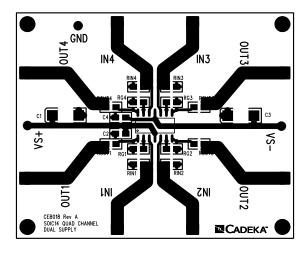
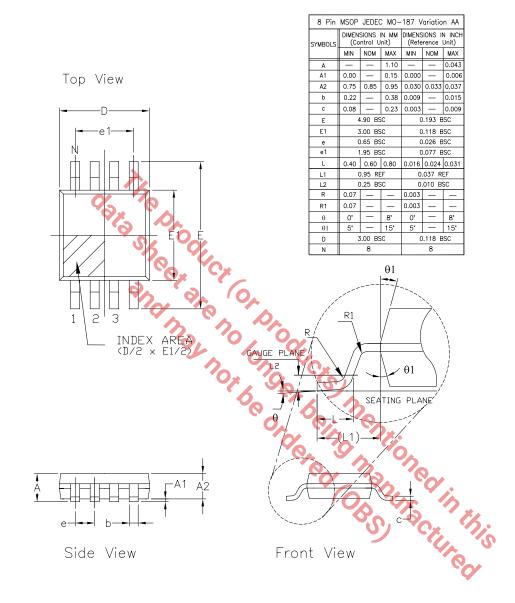


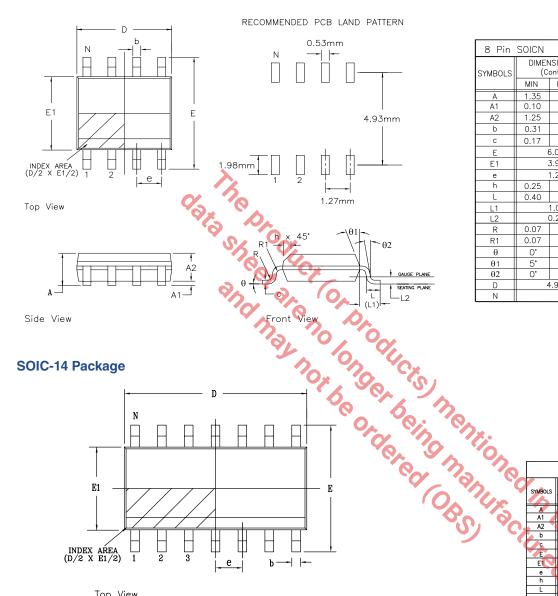
Figure 15. CEB018 Top View

# **Mechanical Dimensions MSOP-8**



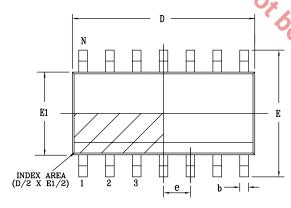
### **Mechanical Dimensions**

#### **SOIC-8 Package**

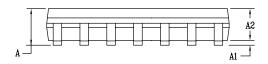


8 Pin SOICN JEDEC MS-012 Variation AA						
SYMBOLS	DIMENSIONS IN MM (Control Unit)			DIMENSIONS IN INCH (Reference Unit)		
	MIN	NOM	MAX	MIN	NOM	MAX
Α	1.35	_	1.75	0.053	_	0.069
A1	0.10	_	0.25	0.004	_	0.010
A2	1.25	_	1.65	0.049	_	0.065
b	0.31	_	0.51	0.012	_	0.020
С	0.17	_	0.25	0.007	_	0.010
E	- 6	5.00 BSC	)	C	.236 BS	С
E1		3.90 BSC	)	C	).154 BS	C
е		1.27 BSC	)	C	.050 BS	С
h	0.25	_	0.50	0.010	_	0.020
L	0.40	_	1.27	0.016	_	0.050
L1	1.04 REF			0	.041 REF	-
L2	0.25 BSC			0	.010 BS	)
R	0.07	_	_	0.003	_	_
R1	0.07	_	_	0.003	_	_
θ	0,		8°	0,		8*
θ1	5°	_	15°	5°	_	15°
θ2	0,			0°		_
D	4	1.90 BSC	:	0.193 BSC		
N		8		8		

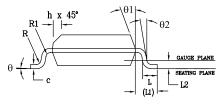
### **SOIC-14 Package**



Top View



Side View

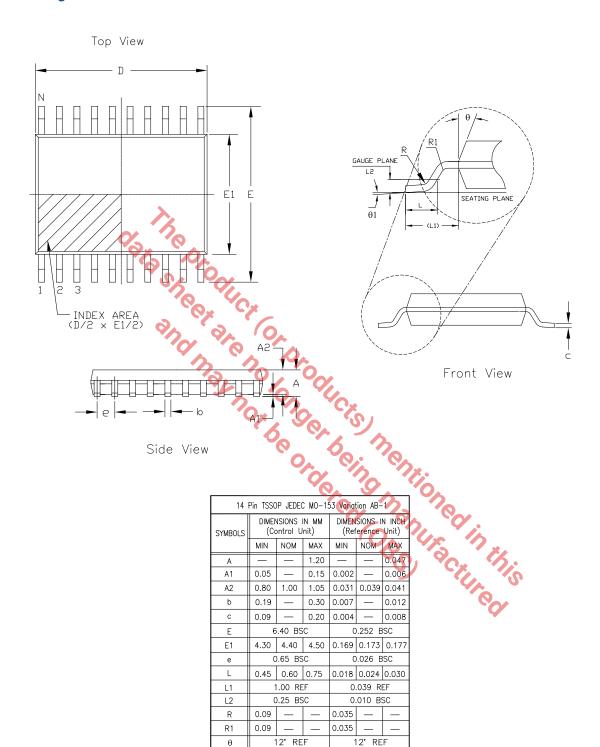


Front View

	PACKAGE OUTLINE NSOIC .150" BODY JEDEC MS-012						
2	SYMBOLS		DIMENSION entrol Unit)		COMMON (Refer	DIMENSION ence Unit	
		MIN	NOM	MAX	MIN	MAX	
	A	1.35		1.75	0.053	I	0.069
	A1 🥒	0.10	_	0.25	0.004		0.010
) ,	A2	1.25	_	1.65	0.049		0.065
	b	0.31		0.51	0.012	_	0.020
ľ	С	0.17	_	0.25	0.007	_	0.010
	E	- 6	3.00 BSC		C	.236 BS	С
	E1		3.90 BSC	;	C	.154 BS	С
	e (		1.27 BSC	;	0.050 BSC		
	h	0.25		0.50	0.010	_	0.020
	٦	0.40		1.27	0.016		0.050
	L1		1.04 REF		0	.041 REI	-
	L2		0.25 BSC			.010 BS	
	R	0.07	_	_	0.003	_	_
	R1	0.07	_	_	0.003	_	_
	θ	0,		8.	0,	l	8.
	θ1	5*	_	15°	5*	-	15°
	θ2	0,	_	_	0,	_	_
	D	SEE VARIATIONS					
	N	N SEE VARIATIONS					

	VARIATION D									
VARIATI	VARIATIONS	DIMENSIONS IN MM (Control Unit)			DIMENSIONS IN INCH (Reference Unit)			N		
S		MIN	NOM	MAX	MIN	NOM	MAX			
AA		4.90 BSC			0.193 BSC			8		
AB	I	8.65 BSC			0.341 BSC			14		
AC		9.90 BSC			0	.390 BS	SC .	16		

#### **TSSOP-14 Package**



8°

14

0°

4.90 5.00 5.10 0.193 0.197 0.200

8°

14

θ1

D N 0\*

### **Ordering Information**

Part Number	Package	Green	Operating Temperature Range	Packaging					
CLC2011 Ordering Information									
CLC2011ISO8X	SOIC-8	Yes	-40°C to +125°C	Tape & Reel					
CLC2011ISO8MTR	SOIC-8	Yes	-40°C to +125°C	Mini Tape & Reel					
CLC2011ISO8EVB	Evaluation Board	N/A	N/A	N/A					
CLC2011IMP8X	MSOP-8	Yes	-40°C to +125°C	Tape & Reel					
CLC2011IMP8MTR	MSOP-8	Yes	-40°C to +125°C	Mini Tape & Reel					
CLC2011IMP8EVB	Evaluation Board	N/A	N/A	N/A					
CLC4011 Ordering Information	n								
CLC4011ISO14X	SOIC-14	Yes	-40°C to +125°C	Tape & Reel					
CLC4011ISO14MTR	SOIC-14	Yes	-40°C to +125°C	Mini Tape & Reel					
CLC4011ISO14EVB	Evaluation Board	N/A	N/A	N/A					
CLC4011ITP14X	TSSOP-14	Yes	-40°C to +125°C	Tape & Reel					
CLC4011ITP14MTR	TSSOP-14	Yes	-40°C to +125°C	Mini Tape & Reel					
CLC4011ITP14EVB	Evaluation Board	N/A	N/A	N/A					
Noisture sensitivity level for all parts  Revision History	is MSL-1. Mini tape and reel quan	ntity is 250.							

Revision	Date	Description Open Control of the Cont					
1D (ECN 1504-01)	January 19, 2015	Reformat into Exar data sheet template. Updated PODs and thermal resistance numbers. Updated ordering information table to include MTR and EVB part numbers. Increased operating temperature to +125°C.					
ered than oned							
		OBS PROPERTY.					
For Further Assistance:							

#### For Further Assistance:

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Exar Technical Documentation: http://www.exar.com/techdoc/

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