

CLC1020

General Purpose, Rail to Rail Output Amplifier Rail to Rail Amplifiers

FEATURES

- 127µA supply current
- 2.1MHz gain bandwidth
- Input voltage range with 5V supply: -0.4V to 4.3V
- Output voltage range with 5V supply: 0.01V to 4.99V
- 2.7V/µs slew rate
- 0.7pA bias current
- 0.1mV input offset voltage
- No crossover distortion
- Fully specified at 2.7V and 5V supplies
- Pb-free TSOT-5

APPLICATIONS

- Portable/battery-powered applications
- Mobile communications, cell phones, pagers
- ADC buffer
- Active filters
- Portable test instruments
- Medical Equipment
- Portable medical instrumentation

General Description

The COMLINEAR CLC1020 is a single channel, high-performance, voltage feedback amplifier. The CLC1020 provides 2.1MHz gain bandwidth product and 2.7V/µs slew rate making it well suited for high-performance battery powered-systems. This COMLINEAR high-performance amplifier also offers low input offset voltage and low bias current.

The COMLINEAR CLC1020 consumes only 127μ A supply current and is designed to operate from a supply range of 2.7V to 5.5V (± 1.35 to ± 2.75). The input voltage range extends 400mV below the negative rail and 700mV below the positive rail. The CLC1020 amplifier operates over the extended temperature range of -40°C to ± 125 °C.

The CLC1020 is packaged in the space saving TSOT-5 package. The TSOT-5 package is pin compatible with the SOT23-5 package.

Typical Performance Examples



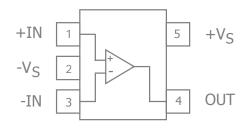
Ordering Information

| Part Number | Package | Pb-Free | RoHS Compliant | Operating Temperature Range | Packaging Method |
|--------------|---------|---------|----------------|-----------------------------|------------------|
| CLC1020IST5X | TSOT-5 | Yes | Yes | -40°C to +125°C | Reel |

Moisture sensitivity level for all parts is MSL-1.

CLC1020 Pin Configuration

CLC1020 Pin Assignments



| Pin No. | Pin Name | Description |
|---------|-----------------|-----------------|
| 1 | +IN | Output |
| 2 | -V _S | Negative supply |
| 3 | -IN | Positive input |
| 4 | OUT | Negative input |
| 5 | +V _S | Positive supply |

data she product (or products) hentioned in this ordered (OBS) actured

Absolute Maximum Ratings

The safety of the device is not guaranteed when it is operated above the "Absolute Maximum Ratings". The device should not be operated at these "absolute" limits. Adhere to the "Recommended Operating Conditions" for proper device function. The information contained in the Electrical Characteristics tables and Typical Performance plots reflect the operating conditions noted on the tables and plots.

| Parameter | Min | Max | Unit |
|---------------------------|-----------------------|------------------|--------------------|
| Supply Voltage | | 7 | V |
| Input Voltage Range | -V _S -0.4V | +V _S | V |
| Continuous Output Current | Output is protecte | ed against momen | tary short circuit |

Reliability Information

| Parameter | X . | Min | Тур | Max | Unit |
|---|-------------------------|------------------------------------|--------|-------------|------------|
| Junction Temperature | 5 _ | | | 150 | °C |
| Storage Temperature Range | .0 | -65 | | 150 | °C |
| Lead Temperature (Soldering, 10s) | | | | 260 | °C |
| Package Thermal Resistance | S/S 9/ | | | | |
| 5-Lead TSOT | 60 40" | | 221 | | °C/W |
| | TSOT-5 | Drodu- | | | |
| | TSOT 5 2kV 2kV | Droducts of h |) D | | |
| , , , | TSOT-5 2kV 2kV | Droducts Droep be | mens. | | |
| Product Human Body Model (HBM) Charged Device Model (CDM) | TSOT 5 2kV 2kV aditions | Droducts Popolicis Popolicis | Тур | Max | Unit |
| Product Human Body Model (HBM) Charged Device Model (CDM) Recommended Operating Cor | TSOT-5 2kV 2kV | | Тур | Max +125 | Unit °C |

| Product | TSOT-5 | | |
|--------------------------------|--------|--|--|
| Human Body Model (HBM) | 2kV | | |
| Charged Device Model (CDM) 2kV | | | |

| Parameter | Тур Мах | Unit |
|-----------------------------|--------------|------|
| Operating Temperature Range | -40 +125 | °C |
| Supply Voltage Range | 2.7 | V |
| | BS) POCIUTED | |

Electrical Characteristics at +2.7V

 $T_A=25^{\circ}\text{C},\,V_S=+2.7\text{V},\,R_f=10\text{k}\Omega,\,R_L=10\text{k}\Omega$ to $V_S/2,\,G=2;$ unless otherwise noted.

| Symbol | Parameter | Conditions | Min | Тур | Max | Units |
|---------------------------------|------------------------------|--|-----|-----------------|-----|--------|
| Frequency | Domain Response | | | | | |
| GBWP | Gain Bandwidth Product | $V_{OUT} = 0.2V_{pp}, C_L = 200 \text{ pF}, R_L = 10 \text{k}\Omega, G = 11$ | | 2 | | MHz |
| UGBW | Unity Gain Bandwidth | $V_{OUT} = 0.2V_{pp}, R_L = 10k\Omega, G=1$ | | 1.6 | | MHz |
| BW _{SS} | -3dB Bandwidth | $V_{OUT} = 0.2V_{pp}, R_L = 10k\Omega, G=2$ | | 836 | | kHz |
| BW _{LS} | Large Signal Bandwidth | $V_{OUT} = 2V_{pp}, R_L = 10k\Omega, G=2$ | | 540 | | kHz |
| G _m | Gain Margin | G=1 | | 22 | | dB |
| Фт | Phase Margin | G=1 | | 82 | | 0 |
| Time Doma | ain Response | | | | | |
| t _R , t _S | Rise and Fall Time | $V_{OUT} = 2V$ step, $R_L = 10k\Omega$ | | 840 | | ns |
| t _S | Settling Time to 0.1% | $V_{OUT} = 2V_{pp}$, $R_L = 10k\Omega$ | | 1.6 | | μs |
| OS | Overshoot | $V_{OUT}=2V_{pp}$, $R_{L}=10k\Omega$ | | 5.5 | | % |
| SR | Slew Rate | $V_{OUT}=2V_{pp}$, $R_{L}=10k\Omega$ | | 2.3 | | V/µs |
| Distortion/I | Noise Response | 1 2 | | | | |
| HD2 | 2nd Harmonic Distortion | $2V_{pp}$, 10kHz, R _L = 10kΩ | | -61 | | dBc |
| HD3 | 3rd Harmonic Distortion | $2V_{pp}$, 10kHz, $R_L = 10k\Omega$ | | -70 | | dBc |
| THD | Total Harmonic Distortion | $2V_{pp}$, 10kHz, G=1, R _L = 10k Ω | | 0.094 | | % |
| e _n | Input Voltage Noise | f=100Hz | | 54 | | nV/√Hz |
| | .0 | f=1kHz | | 30 | | nV/√Hz |
| | | f=10kHz | | 17 | | nV/√Hz |
| DC Perform | nance | y 6 94 | | | | |
| V _{IO} | Input Offset Voltage | Po Po Cx | | 0.53 | | mV |
| dV _{IO} | Average Drift | 7/ 4 00 · W) | | 2.1 | | μV/°C |
| I _b | Input Bias Current | 0 6 3 | | 0.5 | | рА |
| I _{os} | Input Offset Current | 0, 0, 0, | | 0.1 | | рА |
| PSRR | Power Supply Rejection Ratio | DC O | | 73 | | dB |
| I _S | Supply Current | DC Non-inverting Input Non-inverting | | 111 | | μΑ |
| Input Chara | acteristics | 0/ 10. | 200 | | | |
| R _{IN} | Input Resistance | Non-inverting Input | 1 | 29 | | GΩ |
| C _{IN} | Input Capacitance | Non-inverting | // | 2.4 | | pF |
| CMIR | Common Mode Input Range | For V _{CM} ≤50dB | | -0.4 to 2.0 | | V |
| CMRR | Common Mode Rejection Ratio | DC , V _{cm} =0V to 1.7V | 6 | 70.5 | | dB |
| Output Cha | aracteristics | | | | | |
| V _{OUT} | Output Voltage Swing | $R_L = 2k\Omega$ | | 0.02 to 2.63 | | V |
| | | $R_L = 10k\Omega$ | | 0.01 to 2.68 | | V |
| I _{SC} | Short-Circuit Output Current | Sourcing, V _{OUT} = 0V, G=1 | | 18 | | mA |
| | | Sinking, V _{OUT} = 2.7V, G=1 | | 58 | | mA |

Notes:

1. 100% tested at 25°C

Electrical Characteristics at +5V

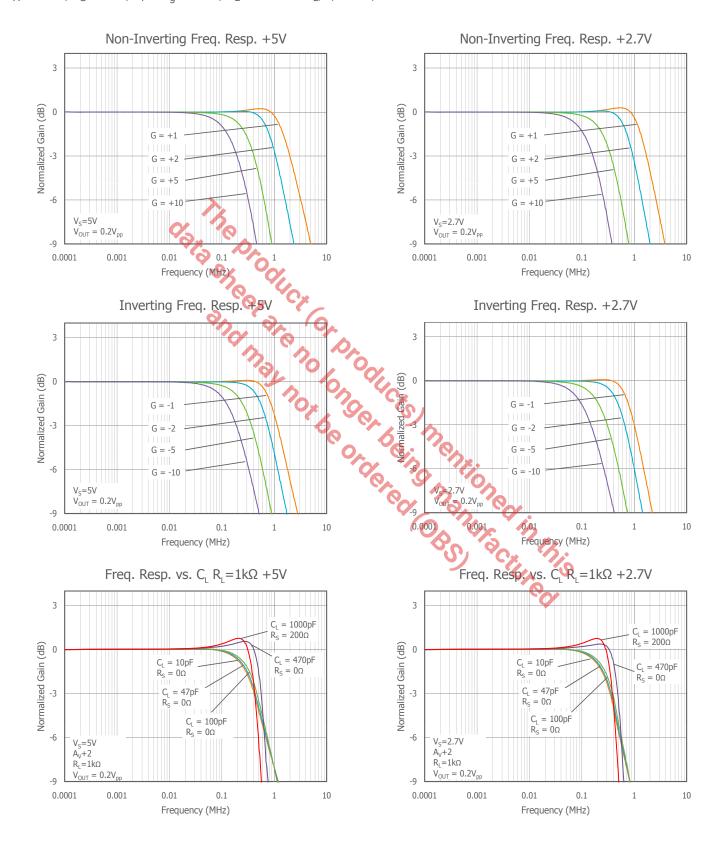
 $T_A=25^{\circ}\text{C},\,V_S=+5\text{V},\,R_f=10\text{k}\Omega,\,R_L=10\text{k}\Omega\,$ to $\,V_S/2,\,G=2;$ unless otherwise noted.

| Symbol | Parameter | Conditions | Min | Тур | Max | Units |
|--------------------------------|---------------------------------------|---|----------|-----------------|------|----------|
| Frequency D | omain Response | | | | | |
| GBWP | Gain Bandwidth Product | $V_{OUT} = 0.2V_{pp}$, $C_L = 200pF$, $R_L = 10k\Omega$, $G=11$ | | 2.1 | | MHz |
| UGBW | Unity Gain Bandwidth | $V_{OUT} = 0.2V_{pp}, R_L = 10k\Omega, G=1$ | | 1.8 | | MHz |
| BW _{SS} | -3dB Bandwidth | $V_{OUT} = 0.2V_{pp}, R_L = 10k\Omega, G=2$ | | 907 | | kHz |
| BW _{LS} | Large Signal Bandwidth | $V_{OUT} = 2V_{pp}$, $R_L = 10k\Omega$, $G=2$ | | 576 | | Hz |
| G _m | Gain Margin | G=1 | | 18 | | dB |
| Фт | Phase Margin | G=1 | | 90 | | 0 |
| Time Domair | n Response | | | | | |
| t _R ,t _S | Rise and Fall Time | V_{OUT} =2V step, R_L = 10kΩ | | 670 | | ns |
| t _S | Settling Time to 0.1% | $V_{OUT} = 2V_{pp}$, $R_L = 10k\Omega$ | | 1.6 | | μs |
| OS | Overshoot | $V_{OUT}=2V_{pp}$, $R_{L}=10k\Omega$ | | 5.9 | | % |
| SR | Slew Rate | $V_{OUT} = 4V_{pp}$, $R_L = 10k\Omega$ | | 2.7 | | V/µs |
| | oise Response | 1 22 17 | ' | | | ' |
| HD2 | 2nd Harmonic Distortion | $V_{OUT}=2V_{DD}$, 10kHz, $R_{L}=10k\Omega$ | | -67 | | dBc |
| HD3 | 3rd Harmonic Distortion | $V_{\text{QUT}} = 2V_{\text{pp}}$, 10kHz, $R_{\text{L}} = 10$ k Ω | | -68 | | dBc |
| THD | Total Harmonic Distortion | $V_{OUT} = 2V_{pp}$, 10kHz, $R_L = 10k\Omega$ | | 0.057 | | % |
| e _n | Input Voltage Noise | f=100Hz | | 57 | | nV/√Hz |
| | · · | f=1kHz | | 30 | | nV/√Hz |
| | 73 | f=100kHz | | 18 | | nV/√Hz |
| DC Performa | nce | 6 94 | ' | | | |
| V _{IO} | Input Offset Voltage(1) | Par Par Cx | | 0.1 | 6 | mV |
| dV _{IO} | Average Drift | 7 4 90. W) | | 1.1 | | μV/°C |
| I _b | Input Bias Current | 6 6 3 | | 0.7 | 250 | рА |
| I _{os} | Input Offset Current | 0, 0, 0 | | 0.1 | | рА |
| PSRR | Power Supply Rejection Ratio (1) | DC O/ PO | 60 | 73 | | dB |
| A _{OL} | Open-Loop Gain (1) | $V_{OUT} = V_S / 2$ | 70 | 122 | | dB |
| I _S | Supply Current (1) | 0/12. | 200 | 127 | 170 | μA |
| Input Charac | teristics | 6 71. | 1 | | | ' |
| R _{IN} | Input Resistance | Non-inverting Input | 7, | 40 | | GΩ |
| C _{IN} | Input Capacitance | Non-inverting Input | Cx | 2.2 | | pF |
| CMIR | Common Mode Input Range | For V _{CM} ≤50dB | 0.3 | 0.4 to 4.3 | 4.2 | V |
| CMRR | Common Mode Rejection Ratio (1) | DC , V _{cm} = 0V to 4V | 60 | 67 | | dB |
| Output Chara | · · · · · · · · · · · · · · · · · · · | | | | | |
| V _{OUT} | Output Voltage Swing | $R_L = 2k\Omega$ | 4.93 | 4.96 to 0.02 | 0.04 | V |
| | | $R_L = 10k\Omega^{(1)}$ | 4.97 | 4.99 to 0.01 | 0.02 | V |
| I _{SC} | Short-Circuit Output Current | Sourcing, V _{OUT} = 0V, G=1 | 30 | 69 | | mA |
|) JC | | Sinking, $V_{OUT} = 5V$, $G=1$ | 80 | 150 | | mA |

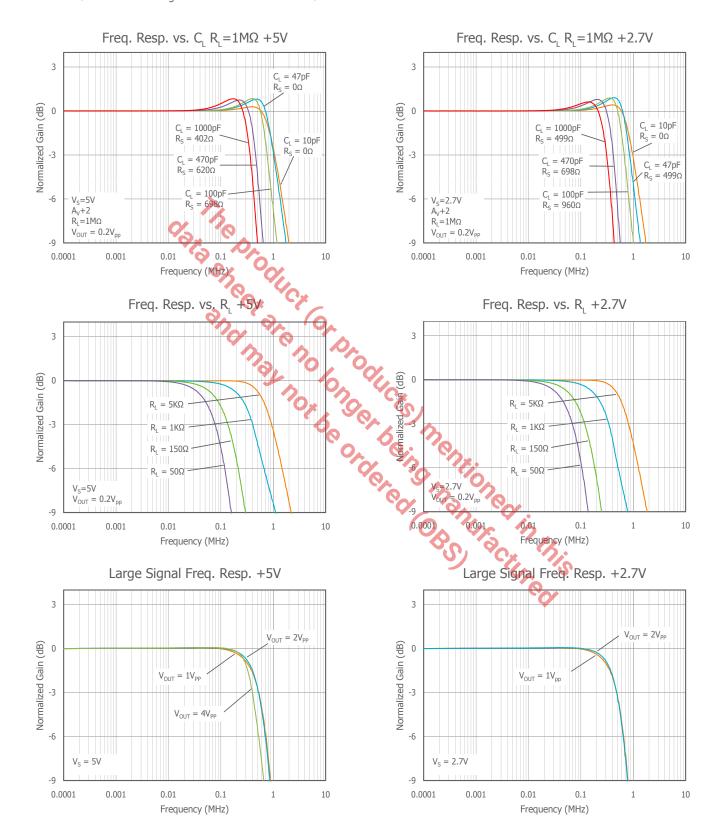
Notes:

1. 100% tested at 25°C

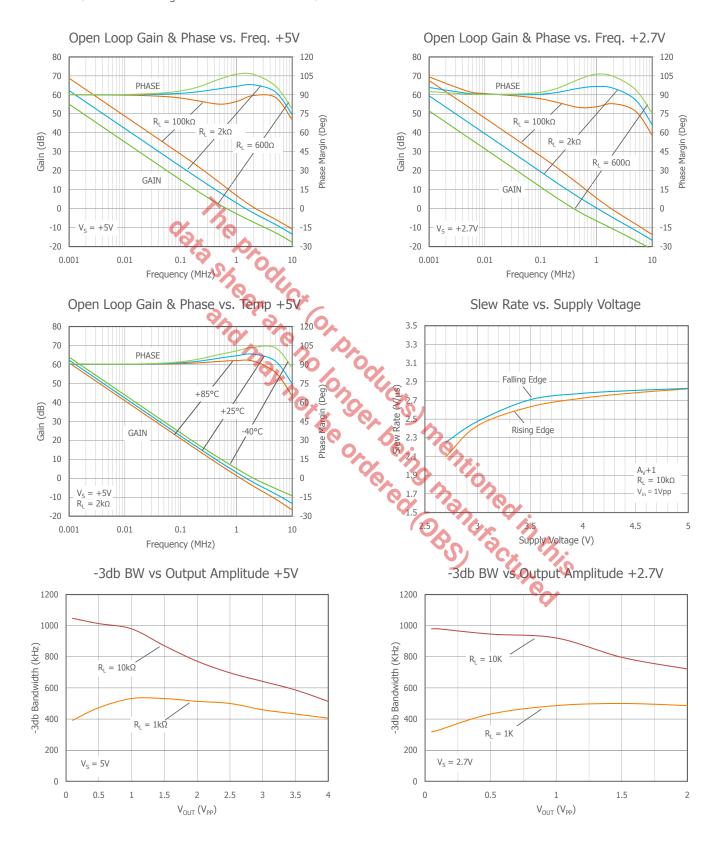
 $T_A=25$ °C, $V_S=+5V$, $R_f=R_q=10k\Omega$, $R_L=10k\Omega$ to $V_S/2$, G=2; unless otherwise noted.



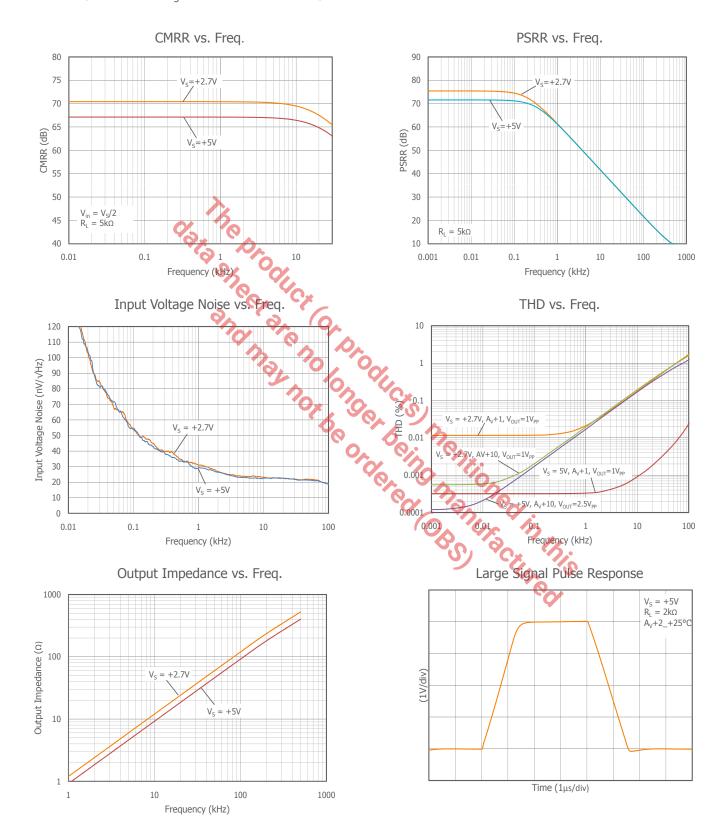
 $T_A = 25$ °C, $V_S = +5V$, $R_f = R_q = 10k\Omega$, $R_L = 10k\Omega$ to $V_S/2$, G = 2; unless otherwise noted.



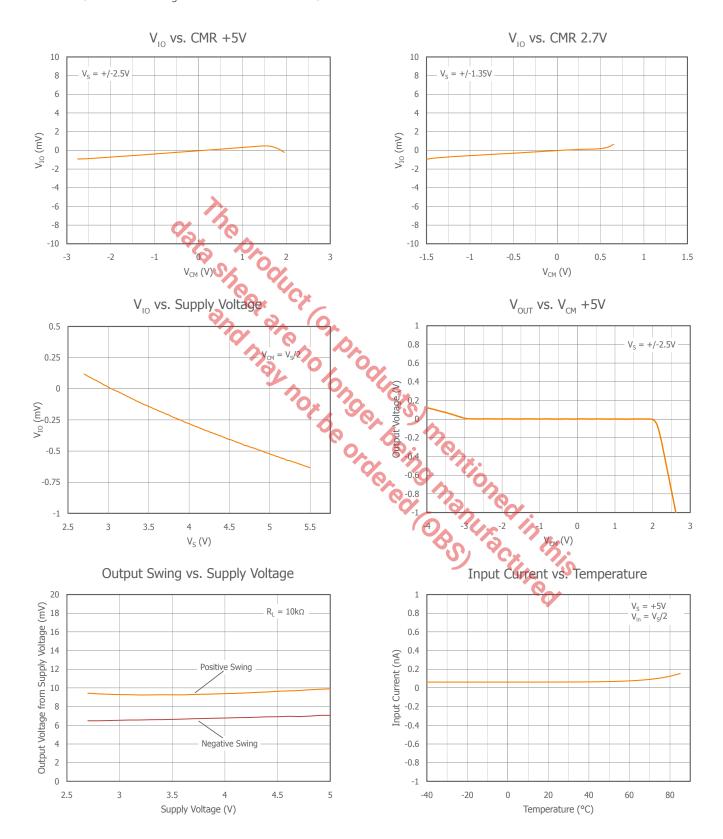
 $T_A = 25$ °C, $V_S = +5V$, $R_f = R_q = 10k\Omega$, $R_L = 10k\Omega$ to $V_S/2$, G = 2; unless otherwise noted.



 $T_A = 25$ °C, $V_S = +5V$, $R_f = R_q = 10k\Omega$, $R_L = 10k\Omega$ to $V_S/2$, G = 2; unless otherwise noted.



 $T_A = 25$ °C, $V_S = +5V$, $R_f = R_g = 10k\Omega$, $R_L = 10k\Omega$ to $V_S/2$, G = 2; unless otherwise noted.



Application Information

General Description

The CLC1020 is a single supply, general purpose, voltagefeedback amplifier fabricated on a CMOS process. The CLC1020 offers 2.1MHz gain bandwidth product, 2.7V/µs slew rate, and only 127µA supply current. It features a rail to rail output stage and is unity gain stable.

The common mode input range extends to 400mV below ground and to 700mV below Vs. Exceeding these values will not cause phase reversal. However, if the input voltage exceeds the rails by more than 0.5V, the input ESD devices will begin to conduct. The output will stay at the rail during this overdrive condition.

The output stage is short circuit protected and offers "soft" saturation protection that improves recovery time. Figures 1, 2, and 3 illustrate typical circuit configurations for noninverting, inverting, and unity gain topologies for dual supply applications. They show the recommended bypass capacitor values and overall closed loop gain equations. Figure 4 shows the typical non-inverting gain circuit for single supply applications

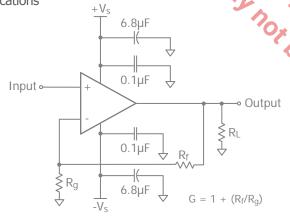


Figure 1. Typical Non-Inverting Gain Circuit

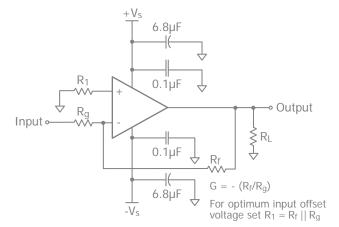


Figure 2. Typical Inverting Gain Circuit

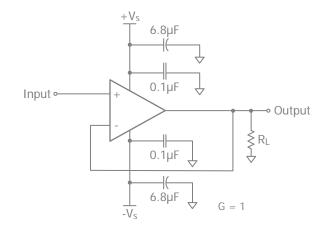
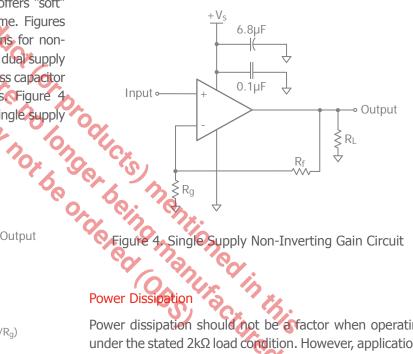


Figure 3. Unity Gain Circuit



Power dissipation should not be a factor when operating under the stated $2k\Omega$ load condition. However, applications with low impedance, DC coupled loads should be analyzed to ensure that maximum allowed junction temperature is not exceeded. Guidelines listed below can be used to verify that the particular application will not cause the device to operate beyond its intended operating range.

Maximum power levels are set by the absolute maximum junction rating of 150°C. To calculate the junction temperature, the package thermal resistance value ThetaJA (Θ_{1A}) is used along with the total die power dissipation.

$$T_{Junction} = T_{Ambient} + (\Theta_{JA} \times P_D)$$

Where T_{Ambient} is the temperature of the working environment. In order to determine P_D, the power dissipated in the load needs to be subtracted from the total power delivered by the supplies.

$$P_D = P_{supply} - P_{load}$$

Supply power is calculated by the standard power equation.

$$P_{\text{supply}} = V_{\text{supply}} \times I_{\text{RMS supply}}$$

$$V_{\text{supply}} = V_{\text{S+}} - V_{\text{S-}}$$

Power delivered to a purely resistive load is:

$$P_{load} = ((V_{l OAD})_{RMS^2})/Rload_{eff}$$

The effective load resistor (Rload_{eff}) will need to include the effect of the feedback network for instance,

Rloadeff in Figure 3 would be calculated as:

$$R_L \mid\mid (R_f + R_g)$$

These measurements are basic and are relatively easy to perform with standard lab equipment. For design purposes however, prior knowledge of actual signal levels and load impedance is needed to determine the dissipated power. Here, P_D can be found from

$$P_D = P_{Quiescent} + P_{Dynamic} - P_{Load}$$

Quiescent power can be derived from the specified I_S values along with known supply voltage, V_{SUPPLY}. Load power can be calculated as above with the desired signal amplitudes using:

$$(V_{LOAD})_{RMS} = V_{PEAK} / \sqrt{2}$$

$$(I_{LOAD})_{RMS} = (V_{LOAD})_{RMS} / Rload_{eff}$$

The dynamic power is focused primarily within the output stage driving the load. This value can be calculated as:

$$P_{DYNAMIC} = (V_{S+} - V_{IOAD})_{RMS} \times (I_{IOAD})_{RMS}$$

Assuming the load is referenced in the middle of the power rails or Vsupply/2.

The CLC1020 is short circuit protected. However, this may not guarantee that the maximum junction temperature (+150°C) is not exceeded under all conditions.

Driving Capacitive Loads

Increased phase delay at the output due to capacitive loading can cause ringing, peaking in the frequency response, and possible unstable behavior. Use a series resistance, R_S, between the amplifier and the load to help improve stability and settling performance. Refer to Figure 5.

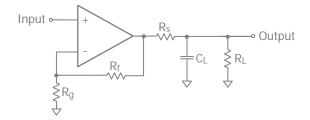


Figure 5. Addition of R_S for Driving Capacitive Loads

For a given load capacitance, adjust R_S to optimize the tradeoff between settling time and bandwidth. In general, reducing R_S will increase bandwidth at the expense of additional overshoot and ringing.

Overdrive Recovery

An overdrive condition is defined as the point when either one of the inputs or the output exceed their specified voltage range. Overdrive recovery is the time needed for the amplifier to return to its normal or linear operating point. The recovery time varies, based on whether the input or output is overdriven and by how much the range is exceeded. The CLC1020 and will typically recover in less than 50s from an overdrive condition. Figure 6 shows the CLC1020 in an overdriven condition.

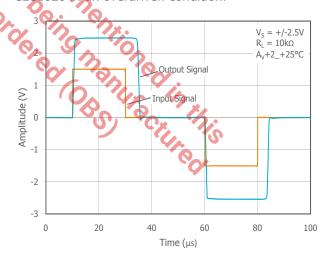


Figure 6. Overdrive Recovery

Layout Considerations

General layout and supply bypassing play major roles in high frequency performance. CADEKA has evaluation boards to use as a guide for high frequency layout and as an aid in device testing and characterization. Follow the steps below as a basis for high frequency layout:

■ Include 6.8µF and 0.1µF ceramic capacitors for power

supply decoupling

- Place the 6.8µF capacitor within 0.75 inches of the power pin
- Place the 0.1µF capacitor within 0.1 inches of the power pin
- Remove the ground plane under and around the part, especially near the input and output pins to reduce parasitic capacitance
- Minimize all trace lengths to reduce series inductances

Evaluation Board Information

The following evaluation boards are available to aid in the testing and layout of these devices:

| Evaluation Board | Products |
|------------------|-----------------|
| CEB004 | CLC1020 in TSOT |

Evaluation Board Schematics

Evaluation board schematics and layouts are shown in Figures 7-11. These evaluation boards are built for dual supply operation. Follow these steps to use the board in a single-supply application:

- 1. Short -Vs to ground.
- 2. Use C3 (6.8 μ F) and C4 (0.1 μ F), if the -V_S pin of the amplifier is not directly connected to the ground plane.

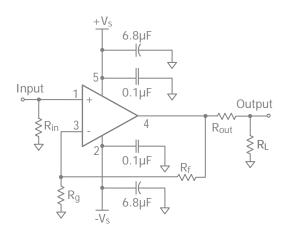


Figure 7. CEB004 Schematic

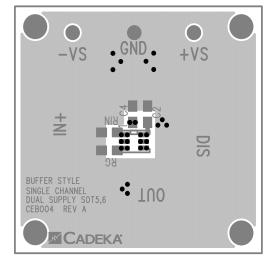


Figure 8. CEB004 Top View

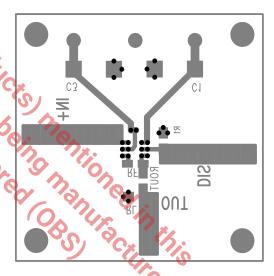
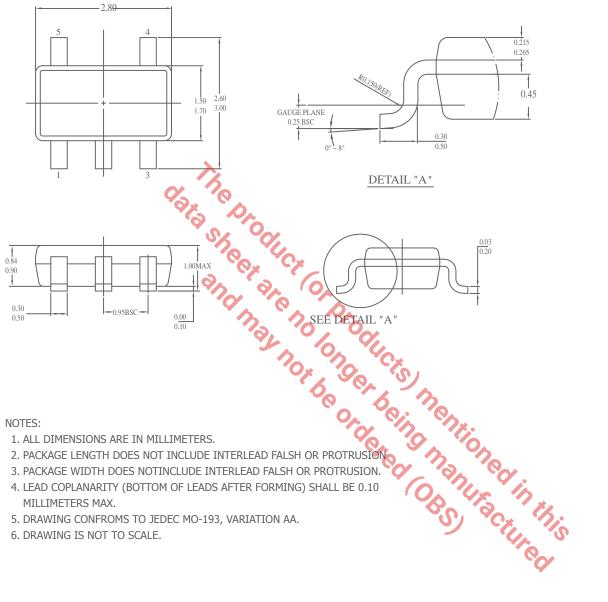


Figure 9. CEB004 Bottom View

Mechanical Dimensions

TSOT-5 Package



For Further Assistance:

Exar Corporation Headquarters and Sales Offices

48720 Kato Road Tel.: +1 (510) 668-7000 Fremont, CA 94538 - USA Fax: +1 (510) 668-7001

www.exar.com



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