

SEPTEMBER 2006

GENERAL DESCRIPTION

The XRT83SH38 is a fully integrated 8-channel shorthaul line interface unit (LIU) that operates from a single 3.3V power supply. Using internal termination, the LIU provides one bill of materials to operate in T1, E1, or J1 mode with minimum external components. The LIU features are programmed through a standard microprocessor interface, serial interface or controlled through Hardware mode. EXAR's LIU has patented high impedance circuits that allow the transmitter outputs and receiver inputs to be high impedance when experiencing a power failure or when the LIU is powered off. Key design features within the LIU optimize 1:1 or 1+1 redundancy and non-intrusive monitoring applications to ensure reliability without using relays.

The on-chip clock synthesizer generates T1/E1/J1 clock rates from a selectable external clock frequency and outputs a clock reference of the line rate chosen.

Additional features include RLOS, a 16-bit LCV counter for each channel, AIS, QRSS generation/ detection, TAOS, DMO, and diagnostic loopback modes.

APPLICATIONS

- T1 Digital Cross-Connects (DSX-1)
- ISDN Primary Rate Interface
- CSU/DSU E1/T1/J1 Interface
- T1/E1/J1 LAN/WAN Routers
- Public switching Systems and PBX Interfaces
- T1/E1/J1 Multiplexer and Channel Banks

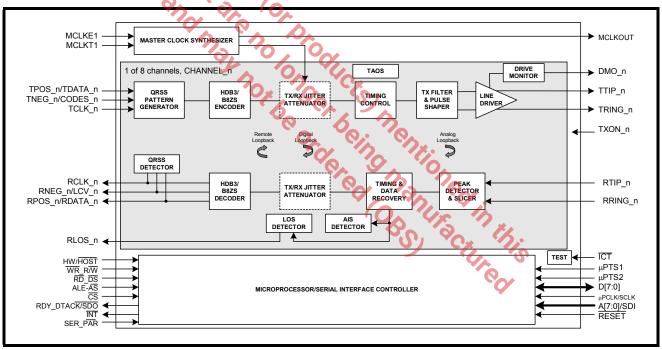
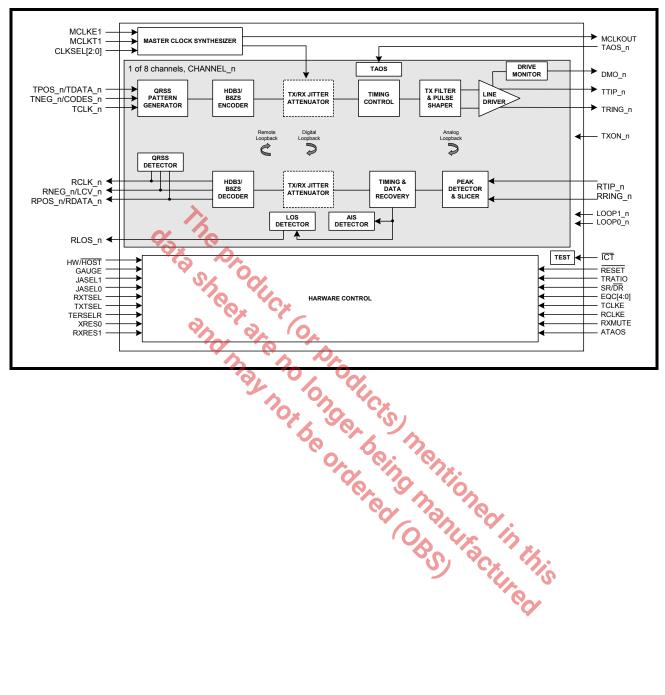


FIGURE 1. BLOCK DIAGRAM OF THE XRT83SH38 T1/E1/J1 LIU (HOST MODE)

REV. 1.0.7

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

FIGURE 2. BLOCK DIAGRAM OF THE XRT83SH38 T1/E1/J1 LIU (HARDWARE MODE)





FEATURES

- Fully integrated eight channel short-haul transceivers for E1,T1 or J1 applications
- Programable Transmit Pulse Shaper for E1,T1 or J1 short-haul interfaces
- Five fixed transmit pulse settings for T1 short-haul applications
- Receive monitor mode handles 0 to 29dB resistive attenuation along with 0 to 6dB of cable attenuation for E1 and 0 to 3dB of cable attenuation for T1 modes
- Internal impedance matching for 75 Ω , 100 Ω , 110 Ω and 120 Ω
- Tri-State transmit output and receive input capability for redundancy applications
- Provides High Impedance for Tx and Rx during power off
- Transmit return loss meets or exceeds ETSI 300-166 standard
- On-chip digital clock recovery circuit for high input jitter tolerance
- Crystal-less digital itter attenuator with 32-bit or 64-bit FIFO selectable either in transmit or receive path
- On-chip frequency multiplier generates T1 or E1 Master clocks from variety of external clock sources
- High receiver interference immunity
- On-chip transmit short-circuit protection and limiting, and driver fail monitor output (DMO)
- Receive loss of signal (RLOS) output
- On-chip HDB3/B8ZS/AMI encoder/decoder functions
- QRSS pattern generator and detection for testing and monitoring
- Error and Bipolar Violation Insertion and Detection
- Transmit All Ones (TAOS) Generators and Detectors
- Supports Local Analog, Remote, Digital and Dual Loop-Back Modes
- Meets or exceeds T1 and E1 short-haul network access specifications in ITU G.703, G.775, G.736 and G.823; TR-TSY-000499; ANSI T1.403 and T1.408; ETSI 300-166 and AT&T Pub 62411
- Supports both Hardware and Host (parallel Microprocessor or Serial) interface for programming Rectured
- JTAG Support
- Programmable Interrupt
- Low power dissipation
- Logic inputs accept either 3.3V or 5V levels
- Single 3.3V Supply Operation
- 225 ball BGA package
- -40°C to +85°C Temperature Range

ORDERING INFORMATION

PART NUMBER	PACKAGE	OPERATING TEMPERATURE RANGE
XRT83SH38IB	225 Ball BGA	-40°C to +85°C

¥	12	с, 133	G_3	11	G_2	2	G_2	GE	٩η	9	G_6	10	ő	G_7	۲_	D_7	ñ	
NC4	NC12	RTIP_3	RRING_3	NC11	RRING_2	RTIP_2	RNEG_2	s GAUGE	מע_מסטטם ג	RTIP_6	RRING_6	NC10	NC9	RRING_7	RTIP_7	RVDD_7	NC3	18
RCLK_3	RPOS_3	TGND_3	RGND_3	TVDD_3	TTIP_2	RGND_2	DGND_JIP	AGND_BIAS	AVDD_BIAS	RPOS_6	RGND_6	RVDD_6	TRING_7	RGND_7	RPOS_7	DMO_6	RNEG_7	17
RLOS_3	RNEG_3	TTIP_3	RVDDD_3	TRING_3	TVDD_2	RVDD_2	RCLK_2	PTS1	RXON	INT	RNEG_6	TTIP_6	TTIP_7	TGND_7	TGND_6	RCLK_7	TCLK_6	16
TCLK_2	TNEG_3	DM0_2	RPOS_2	TGND_2	TRING_2	DGND_DR	RLOS_2	RLOS_6	סעסם	PTS2	RCLK_6	TVDD_6	TVDD_7	TRING_6	RLOS_7	TCLK_7	TPOS_6	15
JASEL0	TPOS_2	TCLK_3	TPOS_3		7									TNEG_7	TPOS_7	TXON_5 TNEG_6	DM0_7	14
TXON_0 JASELO	JASEL1	DMO_3	TNEG_2		~	°D,								TXON_7	hPCLK	TXON_5	TXON_4	13
A[7]	TX0N_3	TXON_2	TXON_1		Ċ.	500	qu	Dat						TXON_6	RXMUTE	TEST	ICT	12
A[3]	A[6]	A[5]	A[4]		Ø	2	9, 9,	6	~					TERSELO	TERSEL1	RXTSEL	TXTSEL	1
A[1]	A[2]	A[0]	DVDD_PDR			1	2	H38		BGA				RXRES1	HW_HOST	DVDD_PDR RXTSEL	RXRES0	10
DVDD	DGND	DGND_PDR	סעסם_סמע					RT83S	(Top Vie	25 Ball F				DVDD_DR	DGND_DR	D[1]	D[3]	6
CLKSELO	CLKSEL1	CLKSEL2	DGND_DR					×	0,	20	ng		0,	JGND_PDR	RESET	D[2]	D[4]	80
ALE_AS	cs	<u>RD_DS</u>	<u>wr</u> _r.w	-							7 ()	31	9 17	Diol	D[7]	D[6]	D[5]	7
RDY_DTACK ALE_AS	TAOS_1	TAOS_3	DMO_0 TAOS_0 WR_R/W DGND_DR DVDD_DR DVDD_PDR A(4) TXON_1 TNEG_2 TPOS_3 RPOS									s S	Q Q	TAOS_7	TAOS_4	TAOS_5	TAOS_6	9
TAOS_2	TNEG_1	TPOS_0		RVDD_1										DMO_4	TCLK_5	TPOS_5	TNEG_5	5
TPOS_1	TCLK_0	TNEG_0	DMO_1	TVDD_0	TVDD_1	TTIP_1	RLOS_1	סעסבסטמ	sr_dr	GNDPLL_2	RNEG_5	TRING_5	DMO_5	TVDD_4	RNEG_4	TNEG_4	TPOS_4	4
TCLK_1	RCLK_0	RLOS_0	TGND_0		TRING_1	RGND_1	RCLK_1		GNDPLL_1	RCLK_5	RPOS_5	RVDD_5	TGND_5	TGND_4	TCLK_4	RCLK_4	RLOS_4	с
RNEG_0	RPOS_0	RVDD_0	RGND_0	TRING_O	TGND_1	RPOS_1	RNEG_1	VDDPLL_2 VDDPLL_1	DGND_DR GNDPLL_1	RLOS_5	RGND_5	TTIP_5	TRING_4	TTIP_4	RGND_4	RPOS_4	RVDD_4	2
NC1	NC5	RTIP_0	RRING_0	NC6	RRING_1	RTIP_1	MCLKOUT	MCLKE1	MCLKT1	RTIP_5	RRING_5	NC7	TVDD_5	NC8	RRING_4	RTIP_4	NC2	-
∢	Ш	C	Ω	Ш	L –	Ċ	_∠ T	_ ٦	×		Σ	z	₽.	Ľ	⊢ –	⊃	>	



TABLE OF CONTENTS

GENERAL DESCRIPTION	1
Applications	
FIGURE 1. BLOCK DIAGRAM OF THE XRT83SH38 T1/E1/J1 LIU (HOST MODE)	
FIGURE 2. BLOCK DIAGRAM OF THE XRT83SH38 T1/E1/J1 LIU (HARDWARE MODE)	
Features	
ORDERING INFORMATION	3
PIN DESCRIPTION BY FUNCTION	5
Receive Section	
TRANSMIT SECTION	
MICROPROCESSOR INTERFACE	
JITTER ATTENUATOR	
CLOCK SYNTHESIZER	
Alarm Functions/Redundancy Support	
Serial Port and Jtag	
Power and Ground	
FUNCTIONAL DESCRIPTION	
1.0 HARDWARE MODE VS HOST MODE	
1.1 FEATURE DIFFERENCES IN HARDWARE MODE	
1.1 FEATURE DIFFERENCES IN HARDWARE MODE	
2.0 MASTER CLOCK GENERATOR	
FIGURE 3. TWO INPUT CLOCK SOURCE	20
FIGURE 3. TWO INFUT CLOCK SOURCE	20
Table 2: Master Clock Generator	20
3.0 RECEIVE PATH LINE INTERFACE	
FIGURE 5. SIMPLIFIED BLOCK DIAGRAM OF THE RECEIVE PATH	
3.1 LINE TERMINATION (RTIP/RRING)	
3.1.1 CASE 1: INTERNAL TERMINATION	21
TABLE 3: SELECTING THE INTERNAL IMPEDANCE	
FIGURE 6. TYPICAL CONNECTION DIAGRAM USING INTERNAL TERMINATION	
3.1.2 CASE 2: INTERNAL TERMINATION WITH ONE EXTERNAL FIXED RESISTOR FOR ALL MODES	
TABLE 4: SELECTING THE VALUE OF THE EXTERNAL FIXED RESISTOR	
FIGURE 7. TYPICAL CONNECTION DIAGRAM USING ONE EXTERNAL FIXED RESISTOR	
FIGURE 8. RECEIVE DATA UPDATED ON THE RISING EDGE OF RCLK	
FIGURE 8. RECEIVE DATA OPDATED ON THE RISING EDGE OF RCLK	23
TABLE 5: TIMING SPECIFICATIONS FOR RCLK/RPOS/RNEG	23
3.2.1 RECEIVE SENSITIVITY	23
Figure 10. Test Configuration for Measuring Receive Sensitivity	24
3.2.2 INTERFERENCE MARGIN	
FIGURE 11. TEST CONFIGURATION FOR MEASURING INTERFERENCE MARGIN	
3.2.3 GENERAL ALARM DETECTION AND INTERRUPT GENERATION	
3.2.3.1 RLOS (RECEIVER LOSS OF SIGNAL)	24
TABLE 6: ANALOG RECEIVE LOS OF SIGNAL FOR TITE INFINITIATION TO A STREAM AND AND A STREAM AND A STREAM AND AND A STREAM AND A STREAM AND A STREAM AND A STREAM AND	25
3.2.3.2 EXLOS (EXTENDED LOSS OF SIGNAL)	
3.2.3.3 AIS (ALARM INDICATION SIGNAL)	
3.2.3.4 FLSD (FIFO LIMIT STATUS DETECTION)	25
3.2.3.5 LCVD (LINE CODE VIOLATION DETECTION)	
3.3 RECEIVE JITTER ATTENUATOR	
3.4 HDB3/B8ZS DECODER	
3.5 RPOS/RNEG/RCLK	
FIGURE 13. SINGLE RAIL MODE WITH A FIXED REPEATING "0011" PATTERN	
FIGURE 14. DUAL RAIL MODE WITH A FIXED REPEATING "0011" PATTERN	
3.6 RXMUTE (RECEIVER LOS WITH DATA MUTING) FIGURE 15. SIMPLIFIED BLOCK DIAGRAM OF THE RXMUTE FUNCTION	
4.0 TRANSMIT PATH LINE INTERFACE	
4.0 TRANSMIT PATH LINE INTERFACE	
4.1 TCLK/TPOS/TNEG DIGITAL INPUTS	
4.1 TOLK/TPOS/TNEG DIGITAL INFOTS	
FIGURE 18. TRANSMIT DATA SAMPLED ON FALLING EDGE OF TOEK	

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

4.2 HDB3/B8ZS ENCODER	
TABLE 8: EXAMPLES OF HDB3 ENCODING	29
TABLE 9: EXAMPLES OF B8ZS ENCODING	29
4.3 TRANSMIT JITTER ATTENUATOR	30
TABLE 10: MAXIMUM GAP WIDTH FOR MULTIPLEXER/MAPPER APPLICATIONS	30
4.4 TAOS (TRANSMIT ALL ONES)	
Figure 19. TAOS (TRANSMIT ALL ONES)	
4.5 TRANSMIT DIAGNOSTIC FEATURES	
4.5.1 ATAOS (AUTOMATIC TRANSMIT ALL ONES)	31
FIGURE 20. SIMPLIFIED BLOCK DIAGRAM OF THE ATAOS FUNCTION	31
4.5.2 QRSS GENERATION	
Table 11: Random Bit Sequence Polynomials	31
4.5.3 T1 SHORT HAUL LINE BUILD OUT (LBO)	
TABLE 12: SHORT HAUL LINE BUILD OUT	
4.5.4 ARBITRARY PULSE GENERATOR FOR T1 AND E1	22
FIGURE 21. ARBITRARY PULSE SEGMENT ASSIGNMENT	
4.6 DMO (DIGITAL MONITOR OUTPUT)	
4.7 LINE TERMINATION (TTIP/TRING)	33
FIGURE 22. TYPICAL CONNECTION DIAGRAM USING INTERNAL TERMINATION	33
5.0 T1/E1 APPLICATIONS	34
5.1 LOOPBACK DIAGNOSTICS	24
5.1.1 LOCAL ANALOG LOOPBACK	34
FIGURE 23. SIMPLIFIED BLOCK DIAGRAM OF LOCAL ANALOG LOOPBACK	34
5.1.2 REMOTE LOOPBACK	
FIGURE 24. SIMPLIFIED BLOCK DIAGRAM OF REMOTE LOOPBACK	34
5.1.3 DIGITAL LOOPBACK	35
Figure 25. Simplified Block Diagram of Digital Loopback	35
5.1.4 DUAL LOOPBACK	35
FIGURE 26. SIMPLIFIED BLOCK DIAGRAM OF DUAL LOOPBACK	35
5.2 LINE CARD REDUNDANCY	26
5.2.1 1:1 AND 1+1 REDUNDANCY WITHOUT RELAYS	30
5.2.1 1:1 AND 1+1 REDUNDANCY WITHOUT RELATS	30
5.2.2 TRANSMIT INTERFACE WITH 1:1 AND 1+1 REDUNDANCY	
FIGURE 27. SIMPLIFIED BLOCK DIAGRAM OF THE TRANSMIT INTERFACE FOR 11 AND 1+1 REDUNDANCY	
5.2.3 RECEIVE INTERFACE WITH 1:1 AND 1+1 REDUNDANCY	
FIGURE 28. SIMPLIFIED BLOCK DIAGRAM OF THE RECEIVE INTERFACE FOR 1:1 AND 1+1 REDUNDANCY	
5.2.4 N+1 REDUNDANCY USING EXTERNAL RELAYS	38
5.2.5 TRANSMIT INTERFACE WITH N+1 REDUNDANCY	38
FIGURE 29. SIMPLIFIED BLOCK DIAGRAM OF THE TRANSMIT INTERFACE FOR N+1 REDUNDANCY	38
5.2.6 RECEIVE INTERFACE WITH N+1 REDUNDANCY	39
FIGURE 30. SIMPLIFIED BLOCK DIAGRAM OF THE RECEIVE INTERFACE FOR N+1 REDUNDANCY	
5.3 POWER FAILURE PROTECTION	40
	40
5.4 OVERVOLTAGE AND OVERCURRENT PROTECTION	40
5.5 NON-INTRUSIVE MONITORING	
Figure 31. Simplified Block Diagram of a Non-Intrusive Monitoring Application	40
6.0 MICROPROCESSOR INTERFACE	41
6.1 SERIAL MICROPROCESSOR INTERFACE BLOCK	
Figure 32. Simplified Block Diagram of the Serial Microprocessor Interface	
6.1.1 SERIAL TIMING INFORMATION	
FIGURE 33. TIMING DIAGRAM FOR THE SERIAL MICROPROCESSOR INTERFACE	
6.1.2 24-BIT SERIAL DATA INPUT DESCRITPTION	
6.1.3 ADDR[7:0] (SCLK1 - SCLK8)	
6.1.4 R/W (SCLK9)	
6.1.5 DUMMY BITS (SCLK10 - SCLK16)	42
6.1.6 DATA[7:0] (SCLK17 - SCLK24)	
6.1.7 8-BIT SERIAL DATA OUTPUT DESCRIPTION	
Figure 34. Timing Diagram for the Microprocessor Serial Interface	
TABLE 13: MICROPROCESSOR SERIAL INTERFACE TIMINGS (TA = 250C, VDD=3.3V± 5% AND LOAD = 10PF)	
6.2 PARALLEL MICROPROCESSOR SERIAL INTERFACE TIMINGS (TA = 250C, VDD=3.3VE 5% AND LOAD = TOPP)	
TABLE 14: Selecting the Microprocessor Interface Mode	
FIGURE 35. SIMPLIFIED BLOCK DIAGRAM OF THE MICROPROCESSOR INTERFACE BLOCK	
6.3 THE MICROPROCESSOR INTERFACE BLOCK SIGNALS	
TABLE 15: XRT83SH38 MICROPROCESSOR INTERFACE SIGNALS THAT EXHIBIT CONSTANT ROLES IN BOTH INTEL AND MOTOROLA MODE	s45
TABLE 16: INTEL MODE: MICROPROCESSOR INTERFACE SIGNALS	
TABLE 17: MOTOROLA MODE: MICROPROCESSOR INTERFACE SIGNALS	
	-





8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

6.4 INTEL MODE PROGRAMMED I/O ACCESS (ASYNCHRONOUS)	
Figure 36. Intel µP Interface Signals During Programmed I/O Read and Write Operations	48
TABLE 18: INTEL MICROPROCESSOR INTERFACE TIMING SPECIFICATIONS	48
6.5 MOTOROLA MODE PROGRAMMED I/O ACCESS (ASYNCHRONOUS)	
Figure 37. Motorola 68K μ P Interface Signals During Programmed I/O Read and Write Operations	49 50
TABLE 19: MOTOROLA 68K MICROPROCESSOR INTERFACE TIMING PROGRAMMED TO READ AND WRITE OPERATIONS	
REGISTER INFORMATION	
TABLE 20: MICROPROCESSOR REGISTER ADDRESS (ADDR[7:0])	
TABLE 21: MICROPROCESSOR REGISTER CHANNEL DESCRIPTION	
TABLE 22: MICROPROCESSOR REGISTER 0x00H BIT DESCRIPTION	
TABLE 23: EQUALIZER CONTROL AND TRANSMIT LINE BUILD OUT	
TABLE 24: MICROPROCESSOR REGISTER 0x01H BIT Description	••••••
TABLE 25: MICROPROCESSOR REGISTER 0x02H BIT DESCRIPTION Table 20: MicroProcessor Register 0x02H BIT Description	
TABLE 26: MICROPROCESSOR REGISTER 0x03h Bit Description Table 27: Microprocessor Register 0x03h Bit Description	
TABLE 27: MICROPROCESSOR REGISTER 0x04H BIT DESCRIPTION Table 20: MicroProcessor Register 0x04H BIT Description	
TABLE 28: MICROPROCESSOR REGISTER 0x05h Bit Description	
TABLE 29: Microprocessor Register 0x06h Bit Description Table 20: Microprocessor Register 0x06h Bit Description	
TABLE 30: MICROPROCESSOR Register 0.208 Bit Description	
TABLE 31: Microprocessor Register 0x09H Bit Description Table 30: Microprocessor Register 0x09H Bit Description	
TABLE 32: MICROPROCESSOR REGISTER 0x0AH BIT DESCRIPTION TABLE 30: MICROPROCESSOR REGISTER 0x0AH BIT DESCRIPTION	
TABLE 33: Microprocessor Register 0x0BH Bit Description Table 34: Microprocessor Register 0x0BH Bit Description	
TABLE 34: MICROPROCESSOR Register 0x0CH Bit Description Table 34: MICROPROCESSOR Register 0x0CH Bit Description	
TABLE 35: MICROPROCESSOR REGISTER 0X0DH BIT Description Table 30: MicroProcessor Register 0x0DH Bit Description	
TABLE 36: MICROPROCESSOR Register 0x0EH Bit Description	
TABLE 37: MICROPROCESSOR REGISTER 0x0FH BIT DESCRIPTION TABLE 38: MICROPROCESSOR REGISTER 0x80H, BIT DESCRIPTION	
CLOCK SELECT REGISTER	
Figure 38. Register 0x81h Sub Registers	
TABLE 39: MICROPROCESSOR REGISTER 0x81H, BIT DESCRIPTION	
TABLE 40: MICROPROCESSOR REGISTER 0x82H BIT Description Image: Comparison of the second se	
TABLE 41: MICROPROCESSOR Register 0x8CH Bit Description	
TABLE 42: MICROPROCESSOR REGISTER 0x8DH BIT Description 10: MICROPROCESSOR REGISTER 0x8DH BIT Description	
TABLE 43: MICROPROCESSOR REGISTER 0x8EH BIT DESCRIPTION	
TABLE 44: MICROPROCESSOR REGISTER 0xC0H BIT DESCRIPTION	
TABLE 45: MICROPROCESSOR REGISTER 0xFEH BIT DESCRIPTION	
TABLE 46: MICROPROCESSOR REGISTER 0xFFH BIT DESCRIPTION	
ELECTRICAL CHARACTERISTICS	70
TABLE 47: ABSOLUTE MAXIMUM RATINGS	
TABLE 48: DC DIGITAL INPUT AND OUTPUT ELECTRICAL CHARACTERISTICS	
TABLE 49: AC ELECTRICAL CHARACTERISTICS	70
TABLE 50: POWER CONSUMPTION	
TABLE 51: E1 RECEIVER ELECTRICAL CHARACTERISTICS	
Table 52: T1 Receiver Electrical Characteristics	
TABLE 53: E1 TRANSMITTER ELECTRICAL CHARACTERISTICS	
TABLE 54: T1 TRANSMITTER ELECTRICAL CHARACTERISTICS	
PACKAGE DIMENSIONS	74
	75
REVISIONS	



PIN DESCRIPTION BY FUNCTION

RECEIVE SECTION

SIGNAL NAME	BGA Lead #	Түре	DESCRIPTION
RXON	K16	I	Receiver On
			Hardware Mode Only
			This pin is used to enable the receivers for all channels. By default, the receivers are turned on in hardware mode. To turn the receivers off, this "Low".
			Note: Internally pulled "High" with 50k Ω resistor.
RLOS0	C3	0	Receive Loss of Signal
RLOS1	H4		When a receive loss of signal occurs according to ITU-T G.775, the RLOS pin will go
RLOS2	H15		"High" for a minimum of one RCLK cycle. RLOS will remain "High" until the loss of
RLOS3	A16 🔇	2	signal condition clears. See the Receive Loss of Signal section of this datasheet for
RLOS4	V3	46	more details.
RLOS5	L2	- Y (Note This pin can be used for redundancy applications to initiate an automatic switch to a backup card.
RLOS6	J15		
RLOS7	T15		Cr.
RCLK0	B3	0 💡	Receive Clock Output
RCLK1	H3		RCLK is the recovered clock from the incoming data stream. If the incoming signal
RCLK2	H16		is absent or RTIP/RRING are in "High-Z", RCLK maintains its timing by using an
RCLK3	A17		internal master clock as its reference. RPOS/RNEG data can be updated on either edge of RCLK selected by RCLKE.
RCLK4	U3		
RCLK5	L3		NOTE: RCLKE is a global setting that applies to all 8 channels.
RCLK6	M15		
RCLK7	U16		
RNEG/LCV0	A2	0	RNEG/LCV_OF Output
RNEG/LCV1	H2		In dual rail mode, this pin is the receive negative data output. In single rail mode,
RNEG/LCV2	H18		this pin is a Line Code Violation Counter Overflow indicator. If LCV is selected by
RNEG/LCV3	B16		programming the appropriate global register and if a line code violation, a bi-polar violation, or excessive zeros occur, the LCV pin will pull "High" for a minimum of one
RNEG/LCV4	T4		RCLK cycle. LCV will remain "High" until there are no more violations. However, if
RNEG/LCV5	M4		OF (Overflow) is selected the LCV pin will pull "High" if the internal LCV counter is
RNEG/LCV6	M16		saturated. The LCV pin will remain "High" until the LCV counter is reset.
RNEG/LCV7	V17		
RPOS0	B2	0	RPOS/RDATA Output
RPOS1	G2		Receive digital output pin. In dual rail mode, this pin is the receive positive data out-
RPOS2	D15		put. In single rail mode, this pin is the receive non-return to zero (NRZ) data output.
RPOS3	B17		
RPOS4	U2		
RPOS5	M3		
RPOS6	L17		
RPOS7	T17		



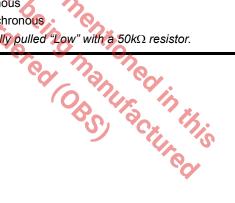
8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

SIGNAL NAME	BGA Lead #	Түре	DESCRIPTION
RTIP0	C1	I	Receive Differential Tip Input
RTIP1	G1		RTIP is the positive differential input from the line interface. Along with the RRING
RTIP2	G18		signal, these pins should be coupled to a 1:1 transformer for proper operation.
RTIP3	C18		
RTIP4	U1		
RTIP5	L1		
RTIP6	L18		
RTIP7	T18		
RRING0	D1	I	Receive Differential Ring Input
RRING1	F1		RRING is the negative differential input from the line interface. Along with the RTIP
RRING2	F18	1	signal, these pins should be coupled to a 1:1 transformer for proper operation.
RRING3	D18	0	
RRING4	T1 💙	5 1	
RRING5	M1	.0.	
RRING6	M18	2	
RRING7	R18	9	Op Cr
RXMUTE	T12	80	Receive Data Muting
		· Q	Hardware Mode Only
			This pin is AND-ed with each of the RLOS functions on a per channel basis. There-
			fore, if this pin is pulled "High" and a given channel experiences a loss of signal, then
			the RPOS/RNEG output pins are automatically pulled "Low" to prevent data chatter- ing. To disable this feature, the RxMUTE pin must be pulled "Low".
			Note: This pin is internally pulled "High" with a 50k Ω resistor

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT



SIGNAL NAME	BGA LEAD #	Түре	DESCRIPTION
RXRES1	R10	Ι	Receive External Resistor Control Pins
RXRES0	V10		Hardware mode Only
			These pins are used in the Receive Internal Impedance mode for unique applica- tions where an accurate resistor can be used to achieve optimal return loss. When RxRES[1:0] are used, the LIU automatically sets the internal impedance to match the line build out. For example: if 240Ω is selected, the LIU chooses an internal impedance such that the parallel combination equals the impedance chosen by TERSEL[1:0]. "00" = No External Fixed Resistor "01" = 240Ω "10" = 210Ω "11" = 150Ω
	•	3.	NOTE: These pins are internally pulled "Low" with a $50k\Omega$ resistor. This feature is available in Host mode by programming the appropriate channel register.
RCLKE/ µPTS1	J16	8 8	Receive Clock Edge Hardware Mode This pin is used to select which edge of the recovered clock is used to update data to the receiver on the RPOS/RNEG outputs. By default, data is updated on the risinge edge. To udpdate data on the falling edge, this pin must be pulled "High". Host Mode µPTS[2.1] pins are used to select the type of microprocessor to be used for Host communication. "00" = 8051 Intel Asynchronous "01" = 68K Motorola Asynchronous "10" = x86 Intel Synchronous "11" = 860 Motorola Synchronous Mote: This pin is internally pulled "Low" with a 50kΩ resistor.





8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

TRANSMIT SECTION

SIGNAL NAME	BGA Lead #	Түре	DESCRIPTION
TCLKE/µPTS2	L15	I	Transmit Clock Edge
			Hardware Mode
			This pin is used to select which edge of the transmit clock is used to sample data
			on the transmitter on the TPOS/TNEG inputs. By default, data is sampled on the
			falling edge. To sample data on the rising edge, this pin must be pulled "High". Host Mode
			μ PTS[2:1] pins are used to select the type of microprocessor to be used for Host
			communication.
			"00" = 8051 Intel Asynchronous
			"01" = 68K Motorola Asynchronous
	Q'	10	"10" = x86 Intel Synchronous
	97	0	"11" = 860 Motorola Synchronous
		.0.	NOTE: This pin is internally pulled "Low" with a 50k Ω resistor.
TTIP0	E3	0	Transmit Differential Tip Output
TTIP1	G4	5	TTIP is the positive differential output to the line interface. Along with the TRING
TTIP2	F17	8	signal, these pins should be coupled to a 1:2 step up transformer for proper opera-
TTIP3	C16	9	
TTIP4	R2		
TTIP5	N2		QL / Q
TTIP6	N16		
TTIP7	P16		signal, these pins should be coupled to a 1:2 step up transformer for proper opera- tion. Transmit Differential Ring Output
TRING0	E2	0	Transmit Differential Ring Output
TRING1	F3		TRING is the negative differential output to the line interface. Along with the TTIP
TRING2	F15		signal, these pins should be coupled to a 1:2 step up transformer for proper opera-
TRING3	E16		tion.
TRING4	P2		Ser 13. Ser
TRING5	N4		
TRING6	R15		
TRING7	P17		signal, these pins should be coupled to a 1:2 step up transformer for proper opera- tion.
TPOS0	C5	I	
TPOS1	A4		Transmit digital input pin. In dual rail mode, this pin is the transmit positive data
TPOS2	B14		input. In single rail mode, this pin is the transmit non-return to zero (NRZ) data
TPOS3	D14		input.
TPOS4	V4		Note: Internally pulled "Low" with a 50K Ω resistor.
TPOS5	U5		
TPOS6	V15		
TPOS7	T14		
TNEG0	C4	I	Transmitter Negative NRZ Data Input
TNEG1	B5		In dual rail mode, this signal is the negative-rail input data for the transmitter. In
TNEG2	D13		single rail mode, this pin can be left unconnected while in Host mode. However, in
TNEG3	B15		Hardware mode, this pin is used to select the type of encoding/decoding for the E1/
TNEG4	U4		T1 data format. Connecting this pin "Low" enables HDB3 in E1 or B8ZS in T1. Connecting this pin "High" selects AMI data format.
TNEG5	V5		Note: Internally pulled "Low" with a $50k\Omega$ resistor.
TNEG6	U14		Note. Internany punce Low with a Sons2 (ESIStor.
TNEG7	R14		

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

SIGNAL NAME	BGA LEAD #	Түре	DESCRIPTION
TCLK0	B4	I	Transmit Clock Input
TCLK1	A3		TCLK is the input facility clock used to sample the incoming TPOS/TNEG data. If
TCLK2	A15		TCLK is absent, pulled "Low", or pulled "High", the transmitter outputs at TTIP/
TCLK3	C14		TRING sends an all zero signal to the line. TPOS/TNEG data can be sampled on
TCLK4	Т3		either edge of TCLK selected by TCLKE.
TCLK5	T5		NOTE: TCLKE is a global setting that applies to all 8 channels.
TCLK6	V16		
TCLK7	U15		
TAOS0	D6	I	Transmit All Ones for Channel
TAOS1	B6		Hardware Mode Only
TAOS2	A5		Setting this pin "High" enables the transmission of an all ones pattern to the line
TAOS3	C6 🔇	X 7	from TTIP/TRING. If this pin is pulled "Low", the transmitters operate in normal
TAOS4	Т6	97	throughput mode.
TAOS5	U6	.0.	NOTE: Internally pulled "Low" with a 50k Ω resistor for all channels. This feature is
TAOS6	V6		<i>Cavailable in Host mode by programming the appropriate channel register.</i>
TAOS7	R6		Cex Cx
TXON0	A13	I N	Transmit On/Off Input
TXON1	D12		Upon power up, the transmitters are powered off. Turning the transmitters On or
TXON2	C12		Off is selected through the microprocessor interface by programming the appropri-
TXON3	B12		ate channel register while in Host mode. However, if TxONCNTL is set "High" in
TXON4	V13		the appropriate global register or if in Hardware mode, the activity of the transmitter outputs is controlled by the TxON pins.
TXON5	U13		
TXON6	R12		NOTE: TXON is ideal for redundancy applications. See the Redundancy Applications Section of this datasheet for more details. Internally pulled
TXON7	R13		"Low" with a 50K Ω resistor.





MICROPROCESSOR INTERFACE

SIGNAL NAME	BGA LEAD #	Түре	DESCRIPTION
HW/HOST	T10	I	Mode Control Input This pin is used to select Host mode or Hardware mode. By default, the LIU is set in Hardware mode. To use Host mode, this pin must be pulled "Low". Note: Internally pulled "High" with a $50k\Omega$ resistor.
WR_R/W/EQC0	D7	- the sh	Write Input(R/W)/Equalizer Control Signal 0 Host Mode This pin is used to communicate a Read or Write operation according to the which microprocessor is chosen. See the Microprocessor Section of this datasheet for details. Hardware Mode EQC[4:0] are used to set the Receiver Gain, Receiver Impedance and the Transmit Line Build Out. See Table 22 for more details. Note: Internally pulled "Low" with a 50kΩ resistor.
RD_DS/EQC1	C7	and	Read Input (Data Strobe)/Equalizer Control Signal 1 Host Mode
ALE/EQC2	A7	I	Address Latch Input (Address Strobe) Host Mode This pin is used to latch the address contents into the internal registers within the LIU device. See the Microprocessor Section of this datasheet for details. Hardware Mode EQC[4:0] are used to set the Receiver Gain, Receiver Impedance and the Transmit Line Build Out. See Table 22 for more details. Note: Internally pulled "Low" with a 50kΩ resistor.
CS/EQC3	B7	I	Chip Select Input - Host mode: Host Mode This pin is used to initiate communication with the microprocessor interface. See the Microprocessor Section of this datasheet for details. Hardware Mode EQC[4:0] are used to set the Receiver Gain, Receiver Impedance and the Transmit Line Build Out. See Table 22 for more details. Note: Internally pulled "Low" with a 50kΩ resistor.

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT



SIGNAL NAME	BGA Lead #	Түре	DESCRIPTION
RDY/EQC4	A6		Ready Output (Data Transfer Acknowledge) Host Mode (Parallel Microprocessor) If Pin SER_PAR is pulled "Low", this output pin from the microprocessor block is used to inform the local μP that the Read or Write operation has been completed and is waiting for the next command. See the Microprocessor Section of this datasheet for details. Host Mode (Serial Interface) If Pin SER_PAR is pulled "High", this output pin from the serial interface is used to read back the regsiter contents. See the Microprocessor Section of this datasheet for details. Hardware Mode EQC[4:0] are used to set the Receiver Gain, Receiver Impedance and the Transmit Line Build Out. See Table 22 for more details. Nore: Internally pulled "Low" with a 50kΩ resistor.
D[7]/Loop14 D[6]/Loop04 D[5]/Loop15 D[4]/Loop05 D[3]/Loop16 D[2]/Loop06 D[1]/Loop17 D[0]/Loop07	T7 U7 V8 V9 U8 U9 R7	1/0	Bi-Directional Data Bus/Loopback Mode Select Host Mode These pins are used for the 8-bit bi-directional data bus to allow data transfer to and from the microprocessor interface. Hardware Mode (Channels 4 through 7) These pins are used to select the loopback mode. Each channel has two loopback pins Loop[1:0]. "00" = No Loopback "01" = Analog Local Loopback "10" = Remote Loopback "11" = Digital Loopback Note: Internally pulled "Low" with a 50kΩ resistor.
A[7]/Loop13 A[6]/Loop03 A[5]/Loop12 A[4]/Loop02 A[3]/Loop11 A[2]/Loop10 A[0]/Loop00	A12 B11 C11 D11 A11 B10 A10 C10	I	Direct Address Bus/Loopback Mode Select <u>Host Mode</u> These pins are used for the 8-bit direct address bus to allow access to the internal registers within the microprocessor interface. <u>Hardware Mode (Channels 0 through 3)</u> These pins are used to select the loopback mode. Each channel has two loopback pins Loop[1:0]. "00" = No Loopback "01" = Analog Local Loopback "10" = Remote Loopback "11" = Digital Loopback <i>Note: Internally pulled "Low" with a 50kΩ resistor.</i>



REV. 1.0.7

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

XRT83SH38

SIGNAL NAME	BGA LEAD #	Түре	DESCRIPTION
µPCLK/ATAOS	T13	I	Synchronous Microprocessor Clock/Automatic Transmit All Ones Host Mode This synchronous input clock is used as the internal master clock to the microprocessor interface when configured for in a synchronous mode. Hardware Mode This pin is used select an all ones signal to the line interface through TTIP/TRING any time that a loss of signal occurs. This feature is available in Host mode by programming the appropriate global register. Note: Internally pulled "Low" with a 50kΩ resistor.
ĪNT	L16	Phe She and	Interrupt Output/Turns Ratio Select (External Impedance Mode) Host Mode This signal is asserted "Low" when a change in alarm status occurs. Once the status registers have been read, the interrupt pin will return "High". GIE (Global Interrupt Enable) must be set "High" in the appropriate global register to enable interrupt generation. Notes: 1. This pin is an open-drain output that requires an external 10KΩ pull-up resistor. 2. Internally pulled "Low" with a 50kΩ resistor.

JITTER ATTENUATOR

SIGNAL NAME	BGA LEAD #	Түре				DES	CRIPTION			
JASEL0	A14	I	Jitte	litter Attenuator Select Pins Hardware Mode						
JASEL1	B13					o place the jitt	er attenu	ator in the	e transmit patl	n, the rece
			path	path or to disable it.						
				JASEL1	JASEL0	JA Path	JA B T1	W Hz E1	FIFO Size	
				0	0	Disabled	y	·		
				0	1	Transmit	3	10	32/32	
				1 0 Receive 3 10 32/32						
				1 1 Receive 3 1.5 64/64						

CLOCK SYNTHESIZER

Signal Name	BGA Lead #	Түре	DESCRIPTION
MCLKOUT	H1	0	Synthesized Master Clock Output
			This signal is the output of the Master Clock Synthesizer PLL which is at T1 or E1 rate based upon the mode of operation.

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT



SIGNAL NAME	BGA Lead #	Түре	DESCRIPTION							
MCLKT1	K1	I	T1 Master	T1 Master Clock Input						
				This signal is an independent 1.544MHz clock for T1 systems with accuracy better than ±50ppm and duty cycle within 40% to 60%. MCLKT1 is used in the T1 mode.						
			Note: All	channels	must oper	ate at the	same cloc	k rate, eithe	r T1, E1 oi	r J1. This
			pii	n is interna	ally pulled '	"Low" with	a 50k Ω res	sistor.		
MCLKE1	J1	Ι	E1 Master	-						
								nan ±50ppm s that have o		
								connected to		
			MCLKT1 i							
								perated at t		
		0	0			-		lled "Low" w	IIII a SUKU	resisior.
CLKSEL0	A8		Clock Sel	-		er Clock S	ynthesize	r		
CLKSEL1 CLKSEL2	B8 C8		Hardware	•	_	to a progra	ammahla fi	equency syr	nthosizor th	nat can he
OLIVOLLZ	00							curate clock		
					/ICLKRATE	E is auton	natically g	enerated fro	om the sta	ate of the
		*	EQC[4:0]		•		1	1		
			MCLKE1 kHz	MCLKT1 kHz	CLKSEL2	CLKSEL1	CLKSEL0	MCLKRATE	CLKOUT/ kHz	
			2048	2048	00	0	0	0	2048	
			2048	2048	0	0	0	1	1544	
			2048	1544	CO	S	0	0	2048	
			1544	1544	0	0	1	1	1544	
			1544	1544	0	0	1 1	0	2048	
			2048 8	1544 X	0		0	0	1544 2048	
			8	x	0	R	0	0 1	1544	
			16	х	0	10		0	2048	
			16	х	0	1	1	1	1544	
			56	х	1	0	0	0	2048	
			56	Х	1	0	0	1	1544	
			64	Х	1	0	1	0	2048	
			64	X	1	0	1	1	1544	
			128	x x	1	1	0	0	2048 1544	
			256	×	1	1	1	0	2048	
			256	X	1	1	1	1	1544	
			Note: Th			y pulled "L	ow" with a	$50k\Omega$ resist	or.	



ALARM FUNCTIONS/REDUNDANCY SUPPORT

SIGNAL NAME	BGA LEAD #	Түре	DESCRIPTION
GAUGE	J18	I	Twisted Pair Cable Wire Gauge SelectHardware Mode OnlyThis pin is used to match the frequency characteristics according to the gauge of wire used in Telecom circuits. By default, the LIU is matched to 22 gauge or 24 gauge wire. To select 26 gauge, this pin must be pulled "High".Note: Internally pulled "Low" with a 50kΩ resistor.
DMO0 DMO1 DMO2 DMO3 DMO4 DMO5 DMO6 DMO7 RESET	D5 D4 C15 C13 R5 P4 U17 V14 T8	o The she ashe and	 Digital Monitor Output When no transmit output pulse is detected for more than 128 TCLK cycles within the transmit output buffer, the DMO pin will go "High" for a minimum of one TCLK cycle. DMO will remain "High" until the transmitter sends a valid pulse. Note: This pin can be used for redundancy applications to initiate an automatic switch to a backup card. Hardware Reset Input Active low signal. When this pin is pulled "Low" for more than 10µS, the internal registers are set to their default state. See the register description for the default values. Note: Internally pulled "High" with a 50KΩ resistor.
SR/DR	K4	I	Single-Rail/Dual-Rail Data Format <u>Hardware Mode Only</u> This pin is used to control the data format on the facility side of the LIU to interface to a Framer or Mapper/ASIC device. By default, dual rail mode is selected which relies upon the Framer to handle the encoding/decoding functions. To select single rail mode, this pin must be pulled "High". If single rail mode is selected, the LIU can encode/decode AMI or B8ZS/HDB3 data formats. Note: Internally pulled "Low" with a 50kΩ resistor.
RXTSEL	U11	I	Receiver Termination SelectHardware ModeThis pin is used to select between the internal and external impedance modes for the receive path. By default, the receivers are configured for external impedance mode, which is ideal for redundancy applications without relays. To select internal impedance, this pin must be pulled "HIgh".Host ModeInternal/External impedance can be selected by programming the appropriate chan- nel registers. However, to assist in redundancy applications, this pin can be used for a hard switch if the RxTCNTL bit is set "High" in the appropriate global register. If RxTCNTL is set "High", the individual RxTSEL register bits are ignored.Note:This pin is internally pulled "Low" with a 50kΩ resistor.
TXTSEL	V11	I	Transmitter Termination Select Hardware Mode This pin is used to select between the internal and external impedance modes for the transmit path. By default, the receivers are configured for external impedance mode, which is ideal for redundancy applications without relays. To select internal impedance, this pin must be pulled "High". Note: This pin is internally pulled "Low".

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT



SIGNAL NAME	BGA Lead #	Түре	DESCRIPTION
TERSEL1	T11	I	Termination Impedance Select
TERSEL0	R11		Hardware Mode Only
			These pins are used to select the transmitter and receiver impedance. By default, the impedance is set to 100Ω .
			"00" = 100Ω
			"01" = 110Ω
			"10" = 75Ω
			"11" = 120Ω
			Note: These pins are internally pulled "Low" with a $50k\Omega$ resistor.
TEST	U12	Ι.	Factory Test Mode
			For normal operation, the TEST pin should be tied to ground.
		°., `	ROTE: Internally pulled "Low" with a 50k Ω resistor.
ICT	V12	B	In Circuit Testing
		3	When this pin is tied "Low", all output pins are forced to "High" impedance for in cir-
			cuit testing.
		Q	Note: Internally pulled "High" with a 50K Ω resistor.



SERIAL PORT AND JTAG

SIGNAL NAME	BGA LEAD #	Түре	DESCRIPTION
SER_PAR	P18	I	Serial/Parallel Select Input (Host Mode Only) This pin is used in the Host mode to select between the parallel microprocessor or serial interface. By default, the Host mode operates in the parallel micropro- cessor mode. To configure the device for a serial interface, this pin must be pulled "HIgh". Note: Internally pulled "Low" with a 50k Ω resistor.
SCLK	T13	I	Serial Clock Input (Host Mode Only) If Pin SER_PAR is pulled "High", this input pin is used the timing reference for the serial microprocessor interface. See the Microprocessor Section of this datasheet for details.
SDI	C10		Serial Data Input (Host Mode Only) If Pin SER_PAR is pulled "High", this input pin from the serial interface is used to input the serial data for Read and Write operations. See the Microprocessor Section of this datasheet for details.
SDO	R7	0,	Serial Data Output (Host Mode Only) If Pin SER, PAR is pulled "High", this output pin from the serial interface is used to read back the regsiter contents. See the Microprocessor Section of this datasheet for details.
JTAGtip	E18	9	Analog JTAG Positive Pin
JTAGring	B18		Analog JTAG Negative Pin
TDO	B1		Test Data Out This pin is used as the output data pin for the boundary scan chain.
TDI	R1		Test Data In This pin is used as the input data pin for the boundary scan chain.
ТСК	N1		Test Clock Input This pin is used as the input clock source for the boundary scan chain.
TMS	E1		Test Mode Select This pin is used as the input mode select for the boundary scan chain.
NC	A1 A18 N18 P18 V1 V18	****	No Connect Pins

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT



POWER AND GROUND

TGND0D3****Transmitter Analog GroundTGND1F2It's recommended that all ground pins of this device be tied togethTGND2E15It's recommended that all ground pins of this device be tied togethTGND3C17TGND4R3	her.
TGND2 E15 TGND3 C17	ner.
TGND3 C17	
TGND5 P3	
TGND6 T16	
TGND7 R16	
TVDD1 F4 TVDD can be shared with DVDD. However, it is recommended isolated from the analog power supply RVDD. For best results, u	
Annual plane for inclution. If an internal neuror plane is not evol	
head can be used. Each power supply pin should be bypass	
TVDD4 R4 through an external 0.1µE capacitor	
TVDD5 P1	
TVDD6 N15	
TVDD7 P15	
RVDD0 C2 **** Receive Analog Power Supply (3.3V ±5%)	
RVDD1 E5 RVDD should not be shared with other power supplies. It is record	
RVDD2 G16 RVDD be isolated from the digital power supply DVDD and the	
RVDD3 D16 supply TVDD. For best results, use an internal power plane for it	
RVDD4 V2 internal power plane is not available, a ferrite bead can be used	
RVDD4 V2 supply pin should be bypassed to ground through an external 0.1 RVDD5 N3	
RVDD6 N17 O O O	
RVDD6 N17 RVDD7 U18	
RGND0D2Receiver Analog GroundRGND1G3RGND2G17RGND3D17RGND4T2RGND5M2RGND6M17	her.
RGND2 G17	
RGND3 D17	
RGND4 T2	
RGND5 M2	
RGND6 M17	
RGND7 R17	
AVDD K17 **** Analog Power Supply (3.3V ±5%)	
J3 AVDD should be isolated from the digital power supplies. For be	st results. use
J2 an internal power plane for isolation. If an internal power plane is	not available,
a ferrite bead can be used. Each power supply pin should be	e bypassed to
ground through at least one 0.1µF capacitor.	
AGND J17 **** Analog Ground	
K3 It's recommended that all ground pins of this device be tied toget	her.
L4	



8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

BGA LEAD #	Түре	DESCRIPTION
R9	****	Digital Power Supply (3.3V ±5%)
U10		DVDD should be isolated from the analog power supplies. For best results, use
K18		an internal power plane for isolation. If an internal power plane is not available,
D9		a ferrite bead can be used. Every two DVDD power supply pins should be bypassed to ground through at least one 0.1µF capacitor.
D10		bypassed to ground through at least one of the capacitor.
K15		
A9		
J4		
R8	****	Digital Ground
Т9		It's recommended that all ground pins of this device be tied together.
H17		
В9	0	
D8	Dr	
	, '0	
	2	4
K2	°Q*	
	LEAD # R9 U10 K18 D9 D10 K15 A9 J4 R8 T9 H17 B9	LEAD # IYPE R9 ***** U10 **** U10 K18 D9 D10 K15 A9 J4 ***** T9 ***** B9 D8 C9 G15

Droubler eer are no products vd may no longer be mentioned in the ordered manufactured in this Sy actured

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT



FUNCTIONAL DESCRIPTION

The XRT83SH38 is a fully integrated 8-channel short-haul line interface unit (LIU) that operates from a single 3.3V power supply. Using internal termination, the LIU provides one bill of materials to operate in T1, E1, or J1 mode with minimum external components. The LIU features are programmed through a standard microprocessor interface or controlled through Hardware mode. EXAR's LIU has patented high impedance circuits that allow the transmitter outputs and receiver inputs to be high impedance when experiencing a power failure or when the LIU is powered off. Key design features within the LIU optimize 1:1 or 1+1 redundancy and non-intrusive monitoring applications to ensure reliability without using relays. The on-chip clock synthesizer generates T1/E1/J1 clock rates from a selectable external clock frequency and outputs a clock reference of the line rate chosen. Additional features include RLOS, a 16-bit LCV counter for each channel, AIS, QRSS generation/detection, Network Loop Code generation/detection, TAOS, DMO, and diagnostic loopback modes.

1.0 HARDWARE MODE VS HOST MODE

The LIU supports a parallel or (serial) microprocessor interface (Host mode) for programming the internal features, or a Hardware mode that can be used to configure the device.

1.1 Feature Differences in Hardware Mode

Some features within the Hardware mode are not supported on a per channel basis. The differences between Hardware mode and Host mode are described below in Table 1.

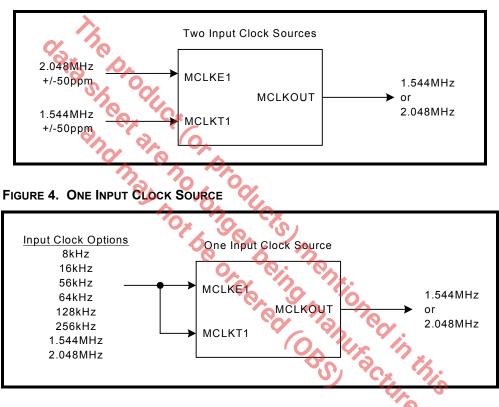
FEATURE	HOST MODE 🚫	HARDWARE MODE
Tx Test Patterns	Fully Supported	QRSS diagnostic patterns are not available in Hardware mode. The TAOS feature is available.
RxRES[1:0]	Per Channel	In Hardware mode, RxRES[1:0] is a global setting that applies to all channels.
TERSEL[1:0]	Per Channel	In Hardware mode, TERSEL[1:0] is a global setting that applies to all channels.
EQC[4:0]	Per Channel	In Hardware mode, the EQC[4:0] is a global setting that applies to all channels. Note: In Host mode, all channels have to operate at one line rate T1 or E1, however each channel can have an individual line build out.
Dual Loopback	Fully Supported	In Hardware mode, dual loopback mode is not supported. Remote, Analog local, and digital loopback modes are available.
JASEL[1:0]	Per Channel	In Hardware mode, the jitter attenuator selection is a global setting that applies to all channels.
RxTSEL	Per Channel	In Hardware mode, the receive termination select is a global set- ting that applies to all channels.
TxTSEL	Per Channel	In Hardware mode, the transmit termination select is a global set- ting that applies to all channels.

TABLE 1: DIFFERENCES BETWEEN HARDWARE MODE AND HOST MODE



2.0 MASTER CLOCK GENERATOR

Using a variety of external clock sources, the on-chip frequency synthesizer generates the T1 (1.544MHz) or E1 (2.048MHz) master clocks necessary for the transmit pulse shaping and receive clock recovery circuit. There are two master clock inputs MCLKE1 and MCLKT1. In systems where both T1 and E1 master clocks are available these clocks can be connected to the respective pins. All channels of a given XRT83SH38 must be operated at the same clock rate, either T1, E1 or J1 modes. In systems that have only one master clock source available (E1 or T1), that clock should be connected to both MCLKE1 and MCLKT1 inputs for proper operation. T1 or E1 master clocks can be generated from 8kHz, 16kHz, 56kHz, 64kHz, 128kHz and 256kHz external clocks under the control of CLKSEL[2:0] inputs according to EQC[4:0] determine the T1/E1 operating mode. See for details.







MCLKE1 ĸHz	MCLKT1 ĸHz	CLKSEL2	CLKSEL1	CLKSEL0	MCLKRATE	MASTER CLOCK KHZ
2048	2048	0	0	0	0	2048
2048	2048	0	0	0	1	1544
2048	1544	0	0	0	0	2048
1544	1544	0	0	1	1	1544
1544	1544	0	0	1	0	2048
2048	1544	0	0	1	1	1544
8	х	0	1	0	0	2048
8	x	0	1	0	1	1544

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

MCLKE1 ĸHz	MCLKT1 ĸHz	CLKSEL2	CLKSEL1	CLKSEL0	MCLKRATE	MASTER CLOCK KHZ
16	х	0	1	1	0	2048
16	x	0	1	1	1	1544
56	x	1	0	0	0	2048
56	x	1	0	0	1	1544
64	x	1	0	1	0	2048
64	x	1	0	1	1	1544
128	x	1	1	0	0	2048
128	x	0 1	1	0	1	1544
256	x		1	1	0	2048
256	x		1	1	1	1544

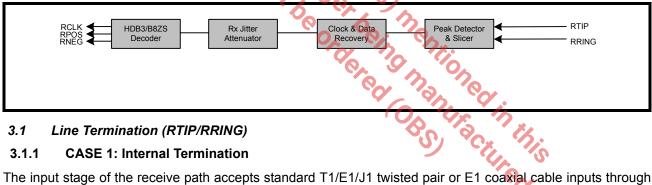
TABLE 2: MASTER CLOCK GENERATOR

3.0 RECEIVE PATH LINE INTERFACE

The receive path of the XRT83SH38 LIU consists of 8 independent T1/E1/J1 receivers. The following section describes the complete receive path from RTP/RRING inputs to RCLK/RPOS/RNEG outputs. A simplified block diagram of the receive path is shown in Figure

0

FIGURE 5. SIMPLIFIED BLOCK DIAGRAM OF THE RECEIVE PATH



3.1.1 **CASE 1: Internal Termination**

The input stage of the receive path accepts standard T1/E1/J1 twisted pair or E1 coaxial cable inputs through RTIP and RRING. The physical interface is optimized by placing the terminating impedance inside the LIU. This allows one bill of materials for all modes of operation reducing the number of external components necessary in system design. The receive termination impedance is selected by programming TERSEL[1:0] to match the line impedance. Selecting the internal impedance is shown in Table 3.

TERSEL[1:0]	RECEIVE TERMINATION
0h (00)	100Ω
1h (01)	110Ω
2h (10)	75Ω
3h (11)	120Ω

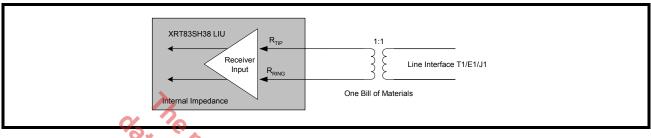
TABLE 3: SELECTING THE INTERNAL IMPEDANCE





The XRT83SH38 has the ability to switch the internal termination to "High" impedance by programming RxTSEL in the appropriate channel register. For internal termination, set RxTSEL to "1". By default, RxTSEL is set to "0" ("High" impedance). For redundancy applications, a dedicated hardware pin (RxTSEL) is also available to control the receive termination for all channels simultaneously. This hardware pin takes priority over the register setting if RxTCNTL is set to "1" in the appropriate global register. If RxTCNTL is set to "0", the state of this pin is ignored. See Figure 6 for a typical connection diagram using the internal termination.





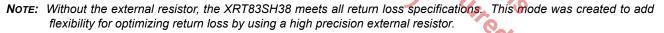
3.1.2 CASE 2: Internal Termination With One External Fixed Resistor for All Modes

Along with the internal termination, a high precision external fixed resistor can be used to optimize the return loss. This external resistor can be used for all modes of operation ensuring one bill of materials. There are three resistor values that can be used by setting the RxRES[1:0] bits in the appropriate channel register. Selecting the value for the external fixed resistor is shown in Table 4.

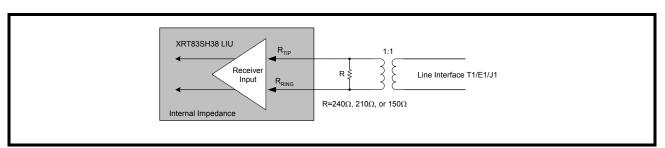
TABLE 4. SELECTING THE VALUE OF THE EXTERNAL TIXED RESISTON		
RxRES[1:0]	EXTERNAL FIXED RESISTOR	
0h (00)	None	
1h (01)	240Ω	
2h (10)	210Ω	
3h (11)	150Ω.	

TABLE 4: SELECTING THE VALUE OF THE EXTERNAL FIXED RESISTOR

By default, RxRES[1:0] is set to "None" for no external fixed resistor. If an external fixed resistor is used, the XRT83SH38 uses the parallel combination of the external fixed resistor and the internal termination as the input impedance. See Figure 7 for a typical connection diagram using the external fixed resistor.







3.2 Clock and Data Recovery

The receive clock (RCLK) is recovered by the clock and data recovery circuitry. An internal PLL locks on the incoming data stream and outputs a clock that's in phase with the incoming signal. This allows for multi-channel T1/E1/J1 signals to arrive from different timing sources and remain independent. In the absence of an incoming signal, RCLK maintains its timing by using the internal master clock as its reference. The recovered



8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

data can be updated on either edge of RCLK. By default, data is updated on the rising edge of RCLK. To update data on the falling edge of RCLK, set RCLKE to "1" in the appropriate global register. Figure 8 is a timing diagram of the receive data updated on the rising edge of RCLK. Figure 9 is a timing diagram of the receive data updated on the falling edge of RCLK. The timing specifications are shown in Table 5.

FIGURE 8. RECEIVE DATA UPDATED ON THE RISING EDGE OF RCLK

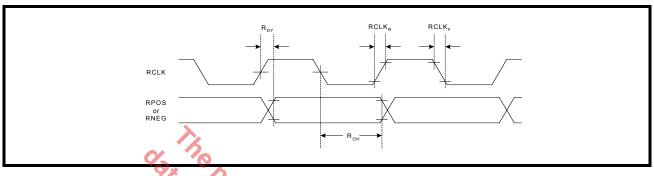
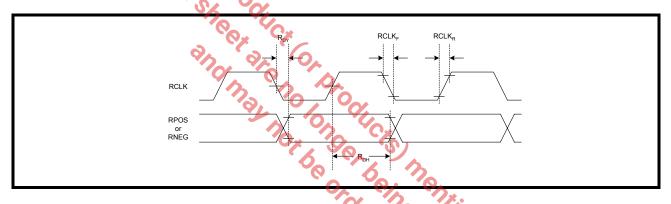


FIGURE 9. RECEIVE DATA UPDATED ON THE FALLING EDGE OF RCLK



PARAMETER	SYMBOL	Min	Түр	Мах	Units
RCLK Duty Cycle	R _{CDU}	45	50	55	%
Receive Data Setup Time	R _{SU}	150		- S	ns
Receive Data Hold Time	R _{HO}	150	-	60	ns
RCLK to Data Delay	R _{DY}	-	-	40	ns
RCLK Rise Time (10% to 90%) with 25pF Loading	RCLK _R	-	-	40	ns
RCLK Fall Time (90% to 10%) with 25pF Loading	RCLK _F	-	-	40	ns

TABLE 5: TIMING SPECIFICATIONS FOR RCLK/RPOS/RNEG

NOTE: VDD=3.3V ±5%, T_A=25°C, Unless Otherwise Specified

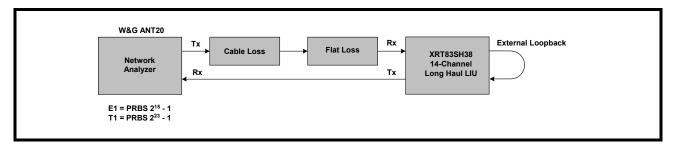
3.2.1 Receive Sensitivity

To meet short haul requirements, the XRT83SH38 can accept T1/E1/J1 signals that have been attenuated by 12dB of flat loss in E1 mode or by 655 feet of cable loss along with 6dB of flat loss in T1 mode. However, the XRT83SH38 can tolerate cable loss and flat loss beyond the industry specifications. The receive sensitivity in the short haul mode is approximately 4,000 feet without experiencing bit errors, LOF, pattern synchronization, etc. Although data integrity is maintained, the RLOS function (if enabled) will report an RLOS condition



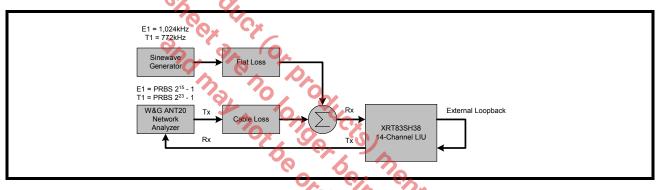
according to the receiver loss of signal section in this datasheet. The test configuration for measuring the receive sensitivity is shown in Figure 10.

FIGURE 10. TEST CONFIGURATION FOR MEASURING RECEIVE SENSITIVITY



3.2.2 Interference Margin

The interference margin for the XRT83SH38 will be added when the first revision of silicon arrives. The test configuration for measuring the interference margin is shown in Figure 11.





3.2.3 General Alarm Detection and Interrupt Generation

The receive path detects RLOS, AIS, QRPD and FLS. These alarms can be individually masked to prevent the alarm from triggering an interrupt. To enable interrupt generation, the Global Interrupt Enable (GIE) bit must be set "High" in the appropriate global register. Any time a change in status occurs (it the alarms are enabled), the interrupt pin will pull "Low" to indicate an alarm has occurred. Once the status registers have been read, the INT pin will return "High". The status registers are Reset Upon Read (RUR). The interrupts are categorized in a hierarchical process block. Figure is a simplified block diagram of the interrupt generation process.

NOTE: The interrupt pin is an open-drain output that requires a $10k\Omega$ external pull-up resistor.

3.2.3.1 RLOS (Receiver Loss of Signal)

In T1 mode, RLOS is declared if an incoming signal has no transitions over a period of 175 +/-75 contiguous pulse intervals. However, the XRT83SH38 LIU has a built in analog RLOS so that the user can be notified when the amplitude of the incoming signal has been attenuated -9dB below the equalizer gain setting. For example: In T1 or E1 short haul mode, the equalizer gain setting is 15dB. Once the input reaches an amplitude of -24dB below nominal, the LIU will declare RLOS. The RLOS circuitry clears when the input reaches +3dB relative to where it was declared. This +3dB value is a pre-determined hysteresis so that transients will not cause the RLOS to clear. In E1 mode, RLOS is declared if an incoming signal has no transitions for N consecutive pulse intervals, where $10 \le N \le 255$. According to G.775, no transitions in E1 mode is defined between -9dB and -35dB below nominal. Figure 12 is a simplified block diagram of the analog RLOS function. Table 6 summarizes the analog RLOS values for the different equalizer gain settings.



8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

FIGURE 12. ANALOG RECEIVE LOS OF SIGNAL FOR T1/E1/J1

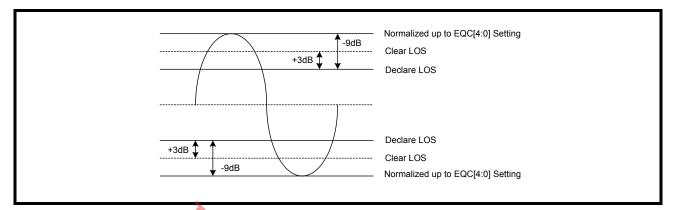


TABLE 6: ANALOG RLOS DECLARE/CLEAR (TYPICAL VALUES) FOR T1/E1

	DECLARE	CLEAR
15dB (Short Haul Mode)	-24dB	-21dB
29dB (Monitoring Gain Mode)	-38dB	-35dB

NOTE: For programming the equalizer gain setting on a per channel basis, see the microprocessor register map for details. **3.2.3.2 EXLOS (Extended Loss of Signal)**

By enabling the extended loss of signal by programming the appropriate channel register, the digital RLOS is extended to count 4,096 consecutive zeros before declaring RLOS in T1 and E1 mode. By default, EXLOS is disabled and RLOS operates in normal mode.

3.2.3.3 AIS (Alarm Indication Signal)

The XRT83SH38 adheres to the ITU-T G.775 specification for an all ones pattern. The alarm indication signal is set to "1" if an all ones pattern (at least 99.9% ones density) is present for T, where T is 3ms to 75ms in T1 mode. AIS will clear when the ones density is not met within the same time period T. In E1 mode, the AIS is set to "1" if the incoming signal has 2 or less zeros in a 512-bit window. AIS will clear when the incoming signal has 3 or more zeros in the 512-bit window.

3.2.3.4 FLSD (FIFO Limit Status Detection)

The purpose of the FIFO limit status is to indicate when the Read and Write FIFO pointers are within a predetermined range (over-flow or under-flow indication). The FLSD is set to "1" if the FIFO Read and Write Pointers are within ±3-Bits.

3.2.3.5 LCVD (Line Code Violation Detection)

The LIU contains 8 independent, 16-bit LCV counters. When the counters reach full-scale, they remain saturated at FFFFh until they are reset globally or on a per channel basis. For performance monitoring, the counters can be updated globally or on a per channel basis to place the contents of the counters into holding registers. The LIU uses an indirect address bus to access a counter for a given channel. Once the contents of the counters have been placed in holding registers, they can be individually read out 8-bits at a time according to the BYTEsel bit in the appropriate global register. By default, the LSB is placed in the holding register until the BYTEsel is pulled "High" where upon the MSB will be placed in the holding register for read back. Once both bytes have been read, the next channel may be selected for read back.

By default, the LVC/OFD will be set to a "1" if the receiver is currently detecting line code violations or excessive zeros for HDB3 (E1 mode) or B8ZS (T1 mode). In AMI mode, the LCVD will be set to a "1" if the receiver is currently detecting bipolar violations or excessive zeros. However, if the LIU is configured to



XRT83SH38

monitor the 16-bit LCV counter by programming the appropriate global register, the LCV/OFD will be set to a "1" if the counter saturates.

3.3 Receive Jitter Attenuator

The receive path has a dedicated jitter attenuator that reduces phase and frequency jitter in the recovered clock. The jitter attenuator uses a data FIFO (First In First Out) with a programmable depth of 32-bit or 64-bit. If the LIU is used for line synchronization (loop timing systems), the JA should be enabled. When the Read and Write pointers of the FIFO are within 2-Bits of over-flowing or under-flowing, the bandwidth of the jitter attenuator is widened to track the short term input jitter, thereby avoiding data corruption. When this condition occurs, the jitter attenuator will not attenuate input jitter until the Read/Write pointer's position is outside the 2-Bit window. In T1 mode, the bandwidth of the JA is always set to 3Hz. In E1 mode, the bandwidth is programmable to either 10Hz or 1.5Hz (1.5Hz automatically selects the 64-Bit FIFO depth). The JA has a clock delay equal to ½ of the FIFO bit depth.

NOTE: If the LIU is used in a multiplexer/mapper application where stuffing bits are typically removed, the transmit path has a dedicated jitter attenuator to smooth out the gapped clock. See the Transmit Section of this datasheet.

3.4 HDB3/B8ZS Decoder

In single rail mode, RPOS can decode AMI or HDB3/B8ZS signals. For E1 mode, HDB3 is defined as any block of 4 successive zeros replaced with OOOV or BOOV, so that two successive V pulses are of opposite polarity to prevent a DC component. In T1 mode, 8 successive zeros are replaced with OOOVBOVB. If the HDB3/B8ZS decoder is selected, the receive path removes the V and B pulses so that the original data is output to RPOS.

3.5 RPOS/RNEG/RCLK

The digital output data can be programmed to either single rail or dual rail formats. Figure 13 is a timing diagram of a repeating "0011" pattern in single rail mode. Figure 14 is a timing diagram of the same fixed pattern in dual rail mode.

FIGURE 13. SINGLE RAIL MODE WITH A FIXED REPEATING "0011" PATTERN

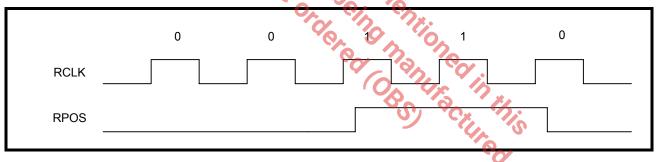
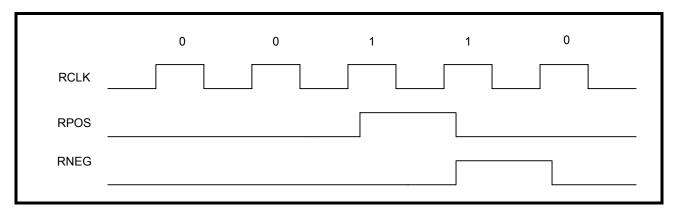


FIGURE 14. DUAL RAIL MODE WITH A FIXED REPEATING "0011" PATTERN

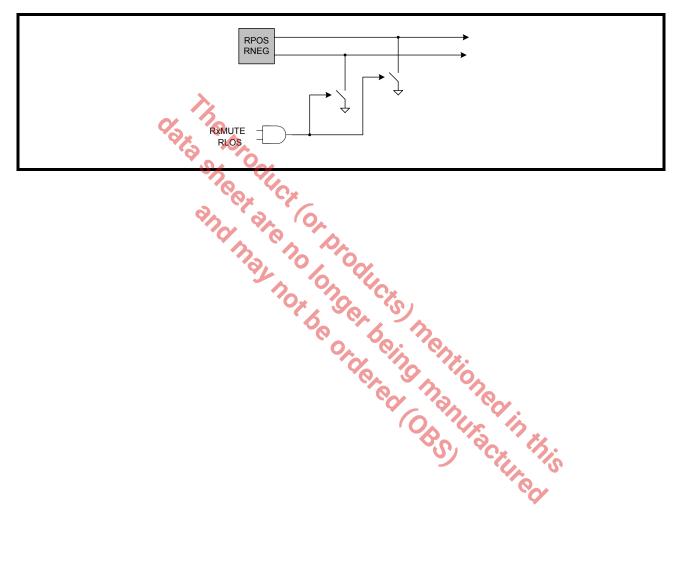


8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

3.6 RxMUTE (Receiver LOS with Data Muting)

The receive muting function can be selected by setting RxMUTE to "1" in the appropriate global register. If selected, any channel that experiences an RLOS condition will automatically pull RPOS and RNEG "Low" to prevent data chattering. If RLOS does not occur, the RxMUTE will remain inactive until an RLOS on a given channel occurs. The default setting for RxMUTE is "0" which is disabled. A simplified block diagram of the RxMUTE function is shown in Figure 15.

FIGURE 15. SIMPLIFIED BLOCK DIAGRAM OF THE RXMUTE FUNCTION



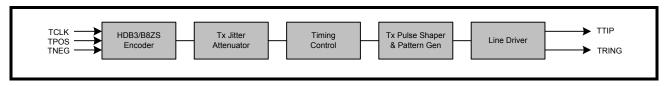




4.0 TRANSMIT PATH LINE INTERFACE

The transmit path of the XRT83SH38 LIU consists of 8 independent T1/E1/J1 transmitters. The following section describes the complete transmit path from TCLK/TPOS/TNEG inputs to TTIP/TRING outputs. A simplified block diagram of the transmit path is shown in Figure 16.

FIGURE 16. SIMPLIFIED BLOCK DIAGRAM OF THE TRANSMIT PATH



4.1 TCLK/TPOS/TNEG Digital Inputs

In dual rail mode, TPOS and TNEG are the digital inputs for the transmit path. In single rail mode, TNEG has no function and can be left unconnected. The XRT83SH38 can be programmed to sample the inputs on either edge of TCLK. By default, data is sampled on the falling edge of TCLK. To sample data on the rising edge of TCLK, set TCLKE to "1" in the appropriate global register. Figure 17 is a timing diagram of the transmit input data sampled on the falling edge of TCLK. Figure 18 is a timing diagram of the transmit input data sampled on the rising edge of TCLK. The timing specifications are shown in Table 7.



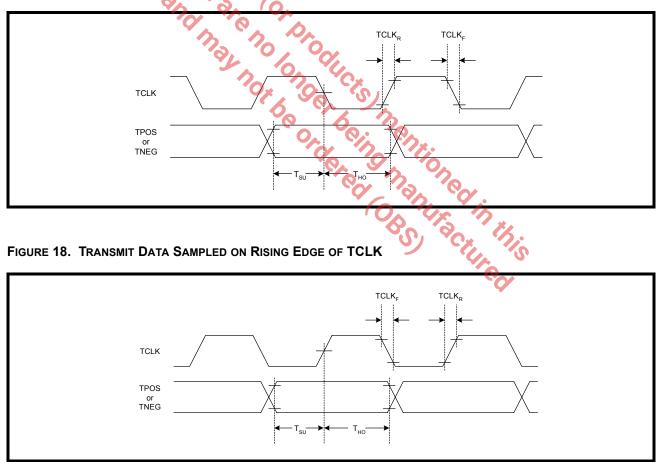




TABLE 7: TIMING SPECIFICATIONS FOR TCLK/TPOS/TNEG

PARAMETER	SYMBOL	Min	Түр	ΜΑΧ	Units
TCLK Duty Cycle	T _{CDU}	30	50	70	%
Transmit Data Setup Time	T _{SU}	50	-	-	ns
Transmit Data Hold Time	Т _{НО}	30	-	-	ns
TCLK Rise Time (10% to 90%)	TCLK _R	-	-	40	ns
TCLK Fall Time (90% to 10%)	TCLK _F	-	-	40	ns

NOTE: VDD=3.3V \pm 5%, T_A =25°C Unless Otherwise Specified

4.2 HDB3/B8ZS Encoder

In single rail mode, the LIU can encode the TPOS input signal to AMI or HDB3/B8ZS data. In E1 mode and HDB3 encoding selected, any sequence with four or more consecutive zeros in the input will be replaced with 000V or B00V, where "B" indicates a pulse conforming to the bipolar rule and "V" representing a pulse violating the rule. An example of HDB3 encoding is shown in Table 8. In T1 mode and B8ZS encoding selected, an input data sequence with eight or more consecutive zeros will be replaced using the B8ZS encoding rule. An example with Bipolar with 8 Zero Substitution is shown in Table 9.

TABLE 8: EXAMPLES OF HDB3 ENCODING

	NUMBER OF PULSES BEFORE NEXT 4 ZEROS	
Input	0 6 7	0000
HDB3 (Case 1)	Odd	000V
HDB3 (Case 2)	Even	B00V

TABLE 5. EXAMPLES OF BOZS ENCOUND			
Case 1	PRECEDING PULSE	NEXT 8 BITS	
Input	+	0000000	
B8ZS		000VB0VB	
AMI Output	+	000+-0-+	
Case 2			
Input	-	0000000	
B8ZS		000VB0VB	
AMI Output	-	000-+0+-	

TABLE 9: EXAMPLES OF B8ZS ENCODING



4.3 Transmit Jitter Attenuator

The XRT83SH38 LIU is ideal for multiplexer or mapper applications where the network data crosses multiple timing domains. As the higher data rates are de-multiplexed down to T1 or E1 data, stuffing bits are typically removed which can leave gaps in the incoming data stream. The transmit path has a dedicated jitter attenuator with a 32-Bit or 64-Bit FIFO that is used to smooth the gapped clock into a steady T1 or E1 output. The maximum gap width of the 8-Channel LIU is shown in Table 10.

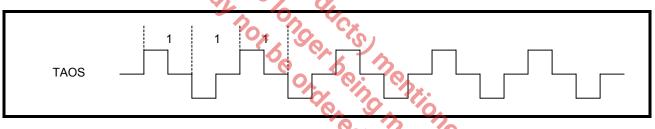
FIFO DEPTH	MAXIMUM GAP WIDTH
32-Bit	20 UI
64-Bit	50 UI

NOTE: If the LIU is used in a loop timing system, the receive path has a dedicated jitter attenuator. See the Receive Section of this datasheet.

4.4 TAOS (Transmit All Ones)

The XRT83SH38 has the ability to transmit all ones on a per channel basis by programming the appropriate channel register. This function takes priority over the digital data present on the TPOS/TNEG inputs. For example: If a fixed "0011" pattern is present on TPOS in single rail mode and TAOS is enabled, the transmitter will output all ones. In addition, if digital or dual loopback is selected, the data on the RPOS output will be equal to the data on the TPOS input. Figure 19 is a diagram showing the all ones signal at TTIP and TRING.

FIGURE 19. TAOS (TRANSMIT ALL ONES)



4.5 Transmit Diagnostic Features

In addition to TAOS, the XRT83SH38 offers diagnostic features for analyzing network integrity such as ATAOS and QRSS on a per channel basis by programming the appropriate registers. These diagnostic features take priority over the digital data present on TPOS/TNEG inputs. The transmitters will send the diagnostic code to the line and will be maintained in the digital loopback if selected. When the LIU is responsible for sending diagnostic patterns, the LIU is automatically placed in the single rail mode.

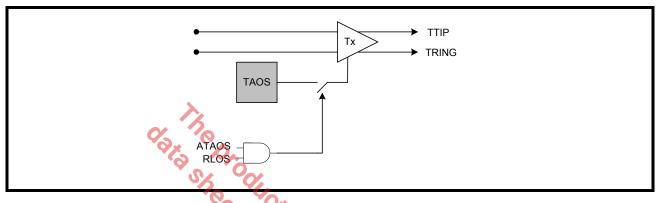
8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

Experience Our Connectivity. REV. 1.0.7

4.5.1 ATAOS (Automatic Transmit All Ones)

If ATAOS is selected by programming the appropriate global register, an AMI all ones signal will be transmitted for each channel that experiences an RLOS condition. If RLOS does not occur, the ATAOS will remain inactive until an RLOS on a given channel occurs. A simplified block diagram of the ATAOS function is shown in Figure 20.

FIGURE 20. SIMPLIFIED BLOCK DIAGRAM OF THE ATAOS FUNCTION



4.5.2 QRSS Generation

The XRT83SH38 can transmit a QRSS random sequence to a remote location from TTIP/TRING. The polynomial is shown in Table 11.

TABLE 11: RANDOM BIT SEQUENCE POLYNOMIALS

RANDOM PATTERN	Or The Car	E1
QRSS	2 ²⁰ - 1	2 ¹⁵ - 1
		10

4.5.3 T1 Short Haul Line Build Out (LBO)

The short haul transmitter output pulses are generated using a 7-Bit internal DAC (6-Bit plus the MSB sign bit). The line build out can be set to interface to five different ranges of cable attenuation by programming the appropriate channel register. The pulse shape is divided into eight discrete time segments which are set to fixed values to comply with the pulse template. To program the eight segments individually to optimize a special line build out, see the arbitrary pulse section of this datasheet. The short haul LBO settings are shown in Table 12.

TABLE 12: SHORT HAUL LINE BUILD OUT		
LBO SETTING EQC[4:0]	RANGE OF CABLE ATTENUATION	
08h (01000)	0 - 133 Feet	
09h (01001)	133 - 266 Feet	
0Ah (01010)	266 - 399 Feet	
0Bh (01011)	399 - 533 Feet	
0Ch (01100)	533 - 655 Feet	

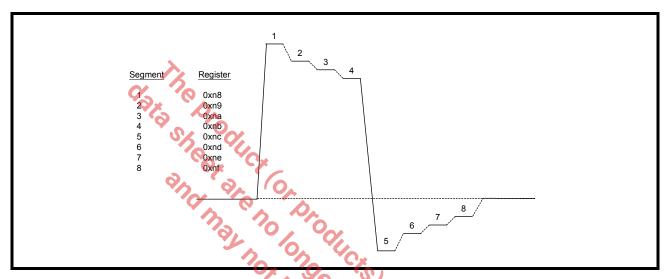


XRT83SH38

4.5.4 Arbitrary Pulse Generator For T1 and E1

The arbitrary pulse generator divides the pulse into eight individual segments. Each segment is set by a 7-Bit binary word by programming the appropriate channel register. This allows the system designer to set the overshoot, amplitude, and undershoot for a unique line build out. The MSB (bit 7) is a sign-bit. If the sign-bit is set to "0", the segment will move in a positive direction relative to a flat line (zero) condition. If this sign-bit is set to "1", the segment will move in a negative direction relative to a flat line condition. The resolution of the DAC is typically 60mV per LSB. Thus, writing 7-bit = 111111 will clamp the output at either voltage rail corresponding to a maximum amplitude. A pulse with numbered segments is shown in Figure 21.

FIGURE 21. ARBITRARY PULSE SEGMENT ASSIGNMENT



NOTE: By default, the arbitrary segments are programmed to 0x00h. The transmitter outputs will result in an all zero pattern to the line interface.

4.6 DMO (Digital Monitor Output)

The driver monitor circuit is used to detect transmit driver failures by monitoring the activities at TTIP/TRING outputs. Driver failure may be caused by a short circuit in the primary transformer or system problems at the transmit inputs. If the transmitter of a channel has no output for more than 128 clock cycles, DMO goes "High" until a valid transmit pulse is detected. If the DMO interrupt is enabled, the change in status of DMO will cause the interrupt pin to go "Low". Once the status register is read, the interrupt pin will return "High" and the status register will be reset (RUR).

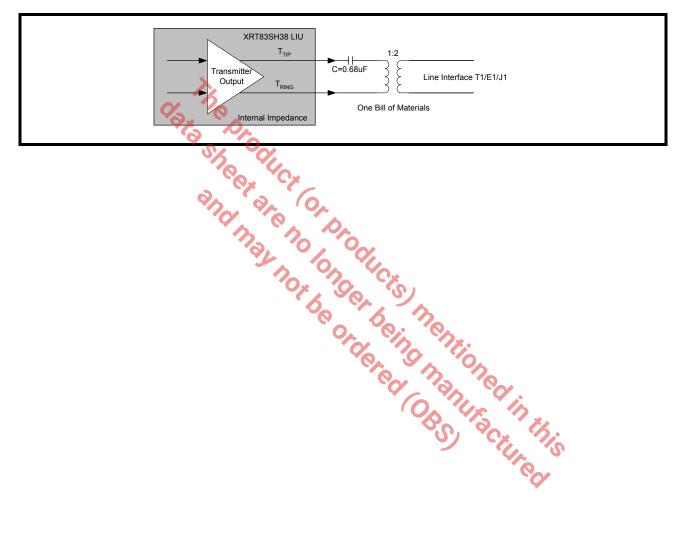
8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT



4.7 Line Termination (TTIP/TRING)

The output stage of the transmit path generates standard return-to-zero (RZ) signals to the line interface for T1/ E1/J1 twisted pair or E1 coaxial cable. The physical interface is optimized by placing the terminating impedance inside the LIU. This allows one bill of materials for all modes of operation reducing the number of external components necessary in system design. The transmitter outputs only require one DC blocking capacitor of 0.68μ F. For redundancy applications (or simply to tri-state the transmitters), set TxTSEL to a "1" in the appropriate channel register. A typical transmit interface is shown in Figure 22.

FIGURE 22. TYPICAL CONNECTION DIAGRAM USING INTERNAL TERMINATION





5.0 T1/E1 APPLICATIONS

This applications section describes common T1/E1 system considerations along with references to application notes available for reference where applicable.

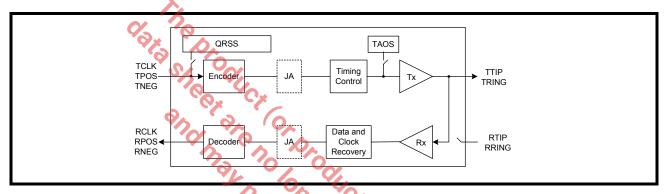
5.1 Loopback Diagnostics

The XRT83SH38 supports several loopback modes for diagnostic testing. The following section describes the local analog loopback, remote loopback, digital loopback, and dual loopback modes.

5.1.1 Local Analog Loopback

With local analog loopback activated, the transmit output data at TTIP/TRING is internally looped back to the analog inputs at RTIP/RRING. External inputs at RTIP/RRING are ignored while valid transmit output data continues to be sent to the line. A simplified block diagram of local analog loopback is shown in Figure 23.

FIGURE 23. SIMPLIFIED BLOCK DIAGRAM OF LOCAL ANALOG LOOPBACK

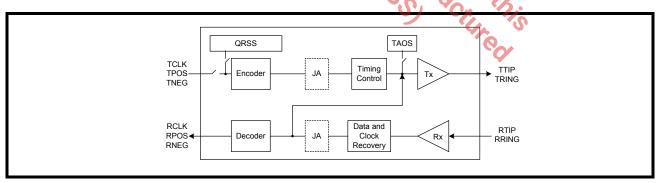


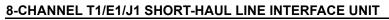
NOTE: The transmit diagnostic features such as TAOS and QRSS take priority over the transmit input data at TCLK/TPOS/ TNEG.

5.1.2 Remote Loopback

With remote loopback activated, the receive input data at RTIP/RRING is internally looped back to the transmit output data at TTIP/TRING. The remote loopback includes the Receive JA (if enabled). The transmit input data at TCLK/TPOS/TNEG are ignored while valid receive output data continues to be sent to the system. A simplified block diagram of remote loopback is shown in Figure 24.





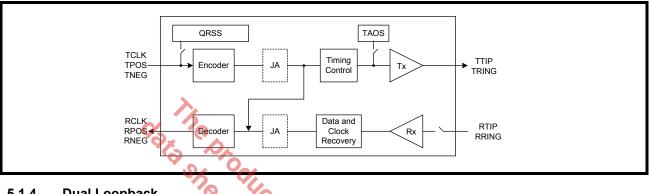




5.1.3 **Digital Loopback**

With digital loopback activated, the transmit input data at TCLK/TPOS/TNEG is looped back to the receive output data at RCLK/RPOS/RNEG. The digital loopback mode includes the Transmit JA (if enabled). The receive input data at RTIP/RRING is ignored while valid transmit output data continues to be sent to the line. A simplified block diagram of digital loopback is shown in Figure 25.

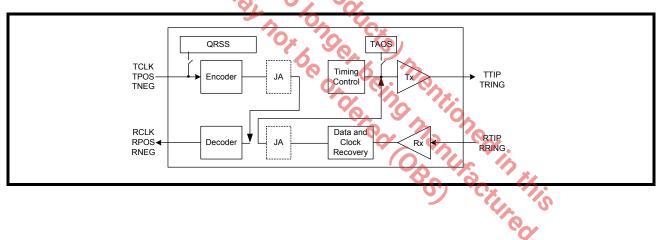




5.1.4 **Dual Loopback**

With dual loopback activated, the remote loopback is combined with the digital loopback. A simplified block diagram of dual loopback is shown in Figure 26.

FIGURE 26. SIMPLIFIED BLOCK DIAGRAM OF DUAL LOOPBACK





5.2 Line Card Redundancy

Telecommunication system design requires signal integrity and reliability. When a T1/E1 primary line card has a failure, it must be swapped with a backup line card while maintaining connectivity to a backplane without losing data. System designers can achieve this by implementing common redundancy schemes with the XRT83SH38 LIU. EXAR offers features that are tailored to redundancy applications while reducing the number of components and providing system designers with solid reference designs.

RLOS and DMO

If an RLOS or DMO condition occurs, the XRT83SH38 reports the alarm to the individual status registers on a per channel basis. However, for redundancy applications, an RLOS or DMO alarm can be used to initiate an automatic switch to the back up card. For this application, two global pins RLOS and DMO are used to indicate that one of the 8-channels has an RLOS or DMO condition.

Typical Redundancy Schemes

- 1:1 One backup card for every primary card (Facility Protection)
- 1+1 One backup card for every primary card (Line Protection)
- N+1 One backup card for N primary cards

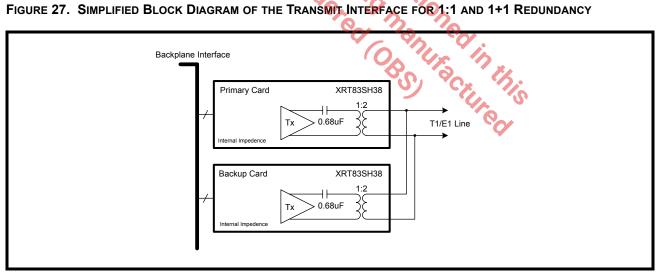
5.2.1 1:1 and 1+1 Redundancy Without Relays

The 1:1 facility protection and 1+1 line protection have one backup card for every primary card. When using 1:1 or 1+1 redundancy, the backup card has its transmitters tri-stated and its receivers in high impedance. This eliminates the need for external relays and provides one bill of materials for all interface modes of operation. For 1+1 line protection, the receiver inputs on the backup card have the ability to monitor the line for bit errors while in high impedance. The transmit and receive sections of the LIU device are described separately.

5.2.2 Transmit Interface with 1:1 and 1+1 Redundancy

The transmitters on the backup card should be tri-stated. Select the appropriate impedance for the desired mode of operation, T1/E1/J1. A 0.68uF capacitor is used in series with TTIP for blocking DC bias. See Figure 27. for a simplified block diagram of the transmit section for a 1:1 and 1+1 redundancy.

FIGURE 27. SIMPLIFIED BLOCK DIAGRAM OF THE TRANSMIT INTERFACE FOR 1:1 AND 1+1 REDUNDANCY

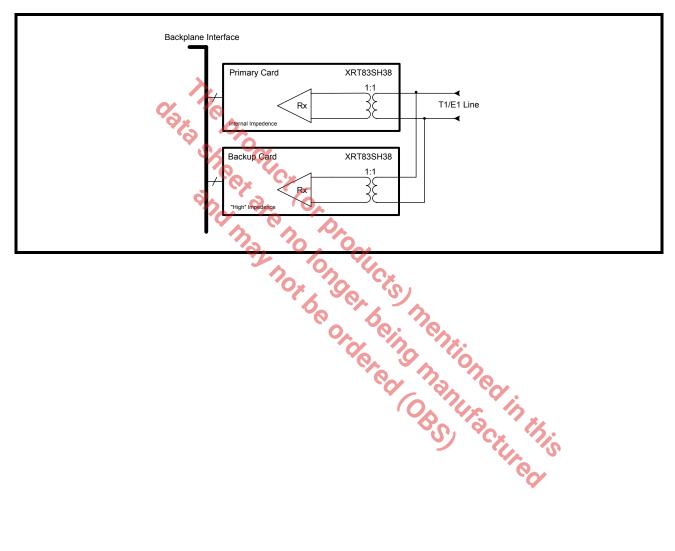


8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

5.2.3 Receive Interface with 1:1 and 1+1 Redundancy

The receivers on the backup card should be programmed for "High" impedance. Since there is no external resistor in the circuit, the receivers on the backup card will not load down the line interface. This key design feature eliminates the need for relays and provides one bill of materials for all interface modes of operation. Select the impedance for the desired mode of operation, T1/E1/J1. To swap the primary card, set the backup card to internal impedance, then the primary card to "High" impedance. See Figure 28. for a simplified block diagram of the receive section for a 1:1 redundancy scheme.

FIGURE 28. SIMPLIFIED BLOCK DIAGRAM OF THE RECEIVE INTERFACE FOR 1:1 AND 1+1 REDUNDANCY



37





5.2.4 N+1 Redundancy Using External Relays

N+1 redundancy has one backup card for N primary cards. Due to impedance mismatch and signal contention, external relays are necessary when using this redundancy scheme. The relays create complete isolation between the primary cards and the backup card. This allows all transmitters and receivers on the primary cards to be configured in internal impedance, providing one bill of materials for all interface modes of operation. The transmit and receive sections of the LIU device are described separately.

5.2.5 Transmit Interface with N+1 Redundancy

For N+1 redundancy, the transmitters on all cards should be programmed for internal impedance. The transmitters on the backup card do not have to be tri-stated. To swap the primary card, close the desired relays, and tri-state the transmitters on the failed primary card. A 0.68uF capacitor is used in series with TTIP for blocking DC bias. See Figure 29 for a simplified block diagram of the transmit section for an N+1 redundancy scheme.

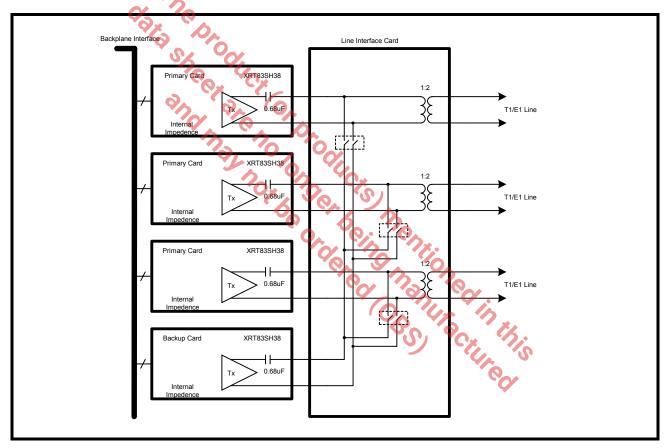


FIGURE 29. SIMPLIFIED BLOCK DIAGRAM OF THE TRANSMIT INTERFACE FOR N+1 REDUNDANCY

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

Experience Our Connectivity. REV. 1.0.7

5.2.6 Receive Interface with N+1 Redundancy

For N+1 redundancy, the receivers on the primary cards should be programmed for internal impedance. The receivers on the backup card should be programmed for "High" impedance mode. To swap the primary card, set the backup card to internal impedance, then the primary card to "High" impedance. See **Figure 30** for a simplified block diagram of the receive section for a N+1 redundancy scheme.

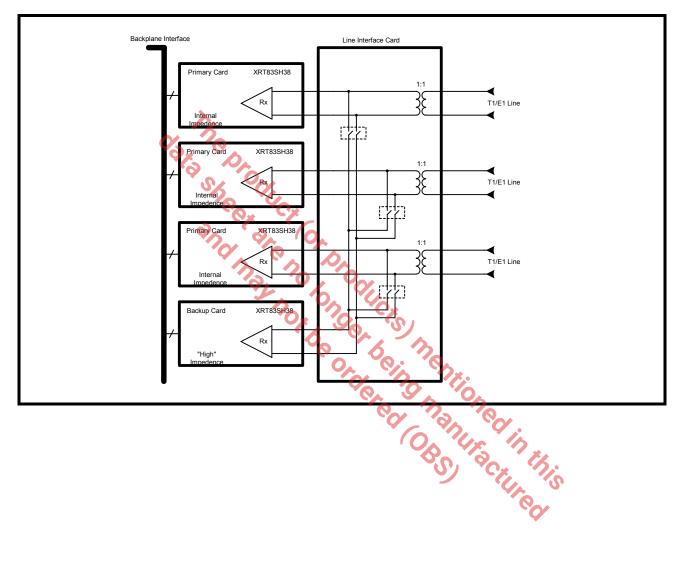


FIGURE 30. SIMPLIFIED BLOCK DIAGRAM OF THE RECEIVE INTERFACE FOR N+1 REDUNDANCY



Power Failure Protection 5.3

For 1:1 or 1+1 line card redundancy in T1/E1 applications, power failure could cause a line card to change the characteristics of the line impedance, causing a degradation in system performance. The XRT83SH38 was designed to ensure reliability during power failures. The LIU has patented high impedance circuits that allow the receiver inputs and the transmitter outputs to be in "High" impedance when the LIU experiences a power failure or when the LIU is powered off.

NOTE: For power failure protection, a transformer must be used to couple to the line interface. See the TAN-56 application note for more details.

5.4 **Overvoltage and Overcurrent Protection**

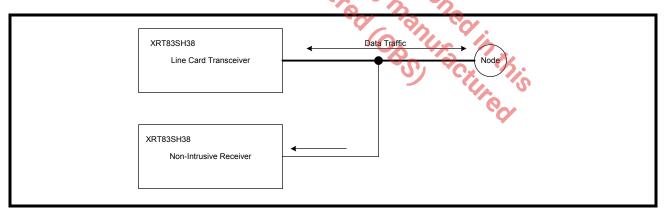
Physical layer devices such as LIUs that interface to telecommunications lines are exposed to overvoltage transients posed by environmental threats. An Overvoltage transient is a pulse of energy concentrated over a small period of time, usually under a few milliseconds. These pulses are random and exceed the operating conditions of CMOS transceiver ICs. Electronic equipment connecting to data lines are susceptible to many forms of overvoltage transients such as lightning, AC power faults and electrostatic discharge (ESD). There are three important standards when designing a telecommunications system to withstand overvoltage transients.

- UL1950 and FCC Part 68
- Telcordia (Bellcore) GR-1089
- ITU-T K.20, K.21 and K.4

5.5 Non-Intrusive Monitoring

duct or t In non-intrusive monitoring applications, the transmitters are shut off by setting TxON "Low". The receivers must be actively receiving data without interfering with the line impedance. The XRT83SH38's internal termination ensures that the line termination meets T1/E1 specifications for 75 Ω , 100 Ω or 120 Ω while monitoring the data stream. System integrity is maintained by placing the non-intrusive receiver in "High" impedance, equivalent to that of a 1+1 redundancy application A simplified block diagram of non-intrusive monitoring is shown in Figure 31.

FIGURE 31. SIMPLIFIED BLOCK DIAGRAM OF A NON-INTRUSIVE MONITORING APPLICATION



8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

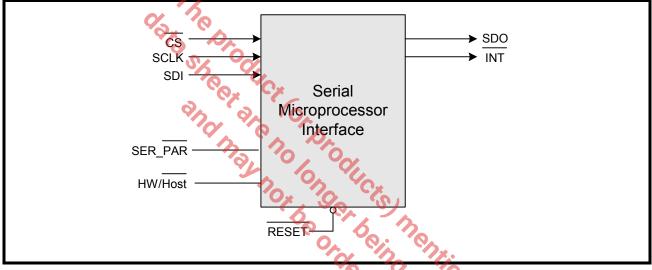
6.0 MICROPROCESSOR INTERFACE

The microprocessor interface can be accessed through a standard serial interface (BGA Package Only) or a standard parallel microprocessor interface. The SER_PAR pin is used to select between the two. By default, the chip is configured in the Parallel Microprocessor interace. For Serial communication, this pin must be pulled "High".

6.1 Serial Microprocessor Interface Block

The serial microprocessor uses a standard 3-pin serial port with \overline{CS} , SCLK, and SDI for programming the LIU. Optional pins such as SDO, INT, and RESET allow the ability to read back contents of the registers, monitor the LIU via an interrupt pin, and reset the LIU to its default configuration by pulling reset "Low" for more than 10 μ S. A simplified block diagram of the Serial Microprocessor is shown in Figure 32.

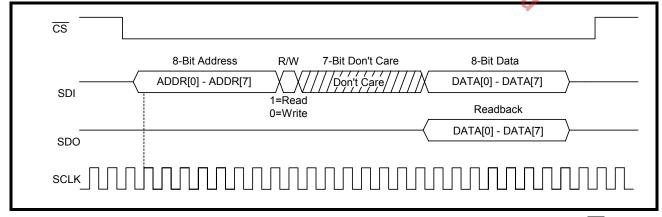
FIGURE 32. SIMPLIFIED BLOCK DIAGRAM OF THE SERIAL MICROPROCESSOR INTERFACE



6.1.1 Serial Timing Information

The serial port requires 24 bits of data applied to the SDI (Serial Data Input) pin. The Serial Microprocessor samples SDI on the rising edge of SCLK (Serial Clock Input). The data is not latched into the device until all 24 bits of serial data have been sampled. A timing diagram of the Serial Microprocessor is shown in Figure 33.





Note: For applications without a free running SCLK, a minimum of 1 SCLK pulse must be applied when \overline{CS} is "High", befrore pulling \overline{CS} "Low".





6.1.2 24-Bit Serial Data Input Descritption

The serial data input is sampled on the rising edge of SCLK. In readback mode, the serial data output is updated on the falling edge of SCLK. The serial data must be applied to the LIU LSB first. The 24 bits of serial data are described below.

6.1.3 ADDR[7:0] (SCLK1 - SCLK8)

The first 8 SCLK cycles are used to provide the address to which a Read or Write operation will occur. ADDR[0] (LSB) must be sent to the LIU first followed by ADDR[1] and so forth until all 8 address bits have been sampled by SCLK.

6.1.4 R/W (SCLK9)

The next serial bit applied to the LIU informs the microprocessor that a Read or Write operation is desired. If the R/W bit is set to "0", the microprocessor is configured for a Write operation. If the R/W bit is set to "1", the microprocessor is configured for a Read operation.

6.1.5 Dummy Bits (SCLK10 - SCLK16)

The next 7 SCLK cycles are used as dummy bits. Seven bits were chosen so that the serial interface can easily be divided into three 8-bit words to be compliant with standard serial interface devices. The state of these bits are ignored and can hold either "0" or "1" during both Read and Write operations.

6.1.6 DATA[7:0] (SCLK17 - SCLK24)

The next 8 SCLK cycles are used to provide the data to be written into the internal register chosen by the address bits. DATA[0] (LSB) must be sent to the LIU first followed by DATA[1] and so forth until all 8 data bits have been sampled by SCLK. Once 24 SCLK cycles have been completed, the LIU holds the data until \overline{CS} is pulled "High" whereby, the serial microprocessor latches the data into the selected internal register.

6.1.7 8-Bit Serial Data Output Description

The serial data output is updated on the falling edge of SCLK17 - SCLK24 if R/W is set to "1". DATA[0] (LSB) is provided on SCLK17 to the SDO pin first followed by DATA[1] and so forth until all 8 data bits have been updated. The SDO pin allows the user to read the contents stored in individual registers by providing the desired address on the SDI pin during the Read cycle.

42



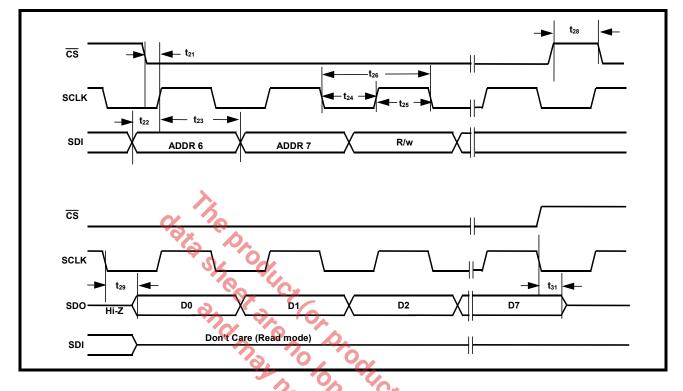


FIGURE 34. TIMING DIAGRAM FOR THE MICROPROCESSOR SERIAL INTERFACE

TABLE 13: MICROPROCESSOR SERIAL INTERFACE TIMINGS ($T_A = 25^{\circ}C$, $V_{DD} = 3.3V \pm 5\%$ and load = 10PF)

SYMBOL	PARAMETER	Min.	Typ.	Мах	UNITS
t ₂₁	CS Low to Rising Edge of SCIk	5			ns
t ₂₂	SDI to Rising Edge of SClk	Q 75	200		ns
t ₂₃	SDI to Rising Edge of SClk Hold Time	5	s in		ns
t ₂₄	SClk "Low" Time	20	QC,	h:	ns
t ₂₅	SClk "High" Time	20	Vre	0	ns
t ₂₆	SClk Period	40			ns
t ₂₈	CS Inactive Time	40			ns
t ₂₉	Falling Edge of SCIk to SDO Valid Time			5	ns
t ₃₁	Rising edge of \overline{CS} to High Z			5	ns



6.2 Parallel Microprocessor Interface Block

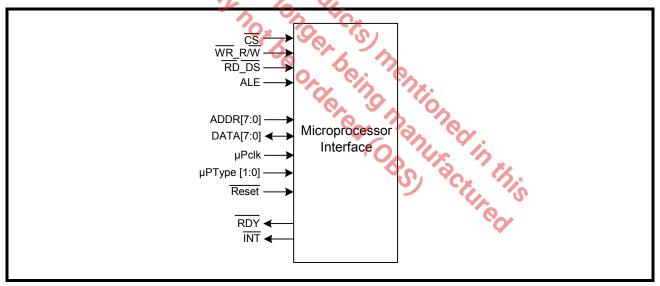
The Parallel Microprocessor Interface section supports communication between the local microprocessor (μ P) and the LIU. The XRT83SH38 supports an Intel asynchronous interface, Motorola 68K asynchronous, and an Intel/Motorola interface. The microprocessor interface is selected by the state of the μ PTS[1:0] input pins. Selecting the microprocessor interface is shown in Table 14.

µPTS[1:0]	MICROPROCESSOR MODE
0h (00)	Intel 68HC11, 8051, 80C188 (Asynchronous)
1h (01)	Motorola 68K (Asynchronous)
2h (10)	Intel x86 (Synchronous)
3h (11)	860 Motorola (Synchronous)

TABLE 14: SELECTING THE MICROPROCESSOR II	NTERFACE MODE
-------------------------------------------	---------------

The XRT83SH38 uses multipurpose pins to configure the device appropriately. The local µP configures the LIU by writing data into specific addressable, on-chip Read/Write registers. The microprocessor interface provides the signals which are required for a general purpose microprocessor to read or write data into these registers. The microprocessor interface also supports polled and interrupt driven environments. A simplified block diagram of the microprocessor is shown in Figure 35.

FIGURE 35. SIMPLIFIED BLOCK DIAGRAM OF THE MICROPROCESSOR INTERFACE BLOCK



8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT



6.3 The Microprocessor Interface Block Signals

The LIU may be configured into different operating modes and have its performance monitored by software through a standard microprocessor using data, address and control signals. These interface signals are described below in Table 15, Table 16, and Table 17. The microprocessor interface can be configured to operate in Intel mode or Motorola mode. When the microprocessor interface is operating in Intel mode, some of the control signals function in a manner required by the Intel 80xx family of microprocessors. Likewise, when the microprocessor interface is operating in Motorola mode, then these control signals function in a manner as required by the Motorola microprocessors. (For using a Motorola 68K asynchronous processor, see Figure 37 and Table 19) Table 15 lists and describes those microprocessor interface signals whose role is constant across the two modes. Table 16 describes the role of some of these signals when the microprocessor interface is operating in the Intel mode. Likewise, Table 17 describes the role of these signals when the microprocessor interface is operating in the Motorola Power PC mode.

TABLE 15: XRT83SH38 MICROPROCESSOR INTERFACE SIGNALS THAT EXHIBIT CONSTANT ROLES IN BOTH INTEL AND MOTOROLA MODES

PIN NAME	Түре	DESCRIPTION
μPTS[1:0]	I	Microprocessor Interface Mode Select Input pins These three pins are used to specify the microprocessor interface mode. The relationship between the state of these three input pins, and the corresponding microprocessor mode is presented in Table 14.
DATA[7:0]	I/O	Bi-Directional Data Bus for register "Read" or "Write" Operations.
ADDR[7:0]	I	Eight-Bit Address Bus Inputs The XRT83SH38 LIU microprocessor interface uses a direct address bus. This address bus is provided to permit the user to select an on-chip register for Read/Write access.
CS	I	Chip Select Input This active low signal selects the microprocessor interface of the XRT83SH38 LIU and enables Read/Write operations with the on-chip register locations.

XRT83SH38 Pin Name	INTEL Equivalent Pin	Түре	DESCRIPTION
ALE	ALE	I	Address-Latch Enable: This active high signal is used to latch the contents on the address bus ADDR[7:0]. The contents of the address bus are latched into the ADDR[7:0] inputs on the falling edge of ALE.
RD_DS	RD	I	Read Signal: This active low input functions as the read signal from the local μ P. When this pin is pulled "Low" (if \overline{CS} is "Low") the LIU is informed that a read operation has been requested and begins the process of the read cycle.
WR_R/W	WR	I	Write Signal: This active low input functions as the write signal from the local μ P. When this pin is pulled "Low" (if \overline{CS} is "Low") the LIU is informed that a write operation has been requested and begins the process of the write cycle.
RDY	RDY	0	Ready Output: This active low signal is provided by the LIU device. It indicates that the current read or write cycle is complete, and the LIU is waiting for the next command.

TABLE 16: INTEL MODE: MICROPROCESSOR INTERFACE SIGNALS



TABLE 17: MOTOROLA MODE: MICROPROCESSOR INTERFACE SIGNALS

XRT83SH38 Pin Name	Motorola Equivalent Pin	Түре	DESCRIPTION
ALE	AS	I	Address Strobe: This active high signal is used to latch the contents on the address bus ADDR[7:0]. The contents of the address bus are latched into the ADDR[7:0] inputs on the falling edge of TS.
WR_R/W	R/W	I	Read/Write: This input pin from the local μ P is used to inform the LIU whether a Read or Write operation has been requested. When this pin is pulled "High", DS will initiate a read operation. When this pin is pulled "Low", DS will initiate a write operation.
RD_DS	DS		Data Strobe: This active low input functions as the read or write signal from the local μ P dependent on the state of R/W. When DS is pulled "Low" (If CS is "Low") the LIU begins the read or write operation.
RDY	DTACK	0	Data Transfer Acknowledge: This active low signal is provided by the LIU device. It indicates that the current read or write cycle is complete, and the LIU is waiting for the next command.

Data Transfer Acknowleus device. It indicates that the current is: writing for the next command.

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT



6.4 Intel Mode Programmed I/O Access (Asynchronous)

If the LIU is interfaced to an Intel type μ P, then it should be configured to operate in the Intel mode. Intel type Read and Write operations are described below.

Intel Mode Read Cycle

Whenever an Intel-type μP wishes to read the contents of a register, it should do the following.

- 1. Place the address of the target register on the address bus input pins ADDR[7:0].
- 2. While the μP is placing this address value on the address bus, the address decoding circuitry should assert the CS pin of the LIU, by toggling it "Low". This action enables further communication between the μP and the LIU microprocessor interface block.
- **3.** Toggle the ALE input pin "High". This step enables the address bus input drivers, within the microprocessor interface block of the LIU.
- **4.** The μP should then toggle the ALE pin "Low". This step causes the LIU to latch the contents of the address bus into its internal circuitry. At this point, the address of the register has now been selected.
- **5.** Next, the μP should indicate that this current bus cycle is a Read operation by toggling the RD input pin "Low". This action also enables the bi-directional data bus output drivers of the LIU.
- 6. After the μP toggles the Read signal Low, the LIU will toggle the RDY output pin Low. The LIU does this in order to inform the μP that the data is available to be read by the μP, and that it is ready for the next command.
- **7.** After the μP detects the RDY signal and has read the data, it can terminate the Read Cycle by toggling the RD input pin "High".

NOTE: ALE can be tied "High" if this signal is not available.

The Intel Mode Write Cycle

Whenever an Intel type μ P wishes to write a byte or word of data into a register within the LIU, it should do the following.

- 1. Place the address of the target register on the address bus input pins ADDR[7:0].
- 2. While the μ P is placing this address value on the address bus, the address decoding circuitry should assert the CS pin of the LIU, by toggling it "Low". This action enables further communication between the μ P and the LIU microprocessor interface block.
- **3.** Toggle the ALE input pin "High". This step enables the address bus input drivers, within the microprocessor interface block of the LIU.
- **4.** The μP should then toggle the ALE pin "Low". This step causes the LIU to latch the contents of the address bus into its internal circuitry. At this point, the address of the register has now been selected.
- **5.** The μP should then place the byte or word that it intends to write into the target register, on the bi-directional data bus DATA[7:0].
- **6.** Next, the μP should indicate that this current bus cycle is a Write operation by toggling the WR input pin "Low". This action also enables the bi-directional data bus input drivers of the LIU.
- 7. After the μP toggles the Write signal "Low", the LIU will toggle the RDY output pin "Low". The LIU does this in order to inform the μP that the data has been written into the internal register location, and that it is ready for the next command.

NOTE: ALE can be tied "High" if this signal is not available.

The Intel Read and Write timing diagram is shown in Figure 36. The timing specifications are shown in Table 18.

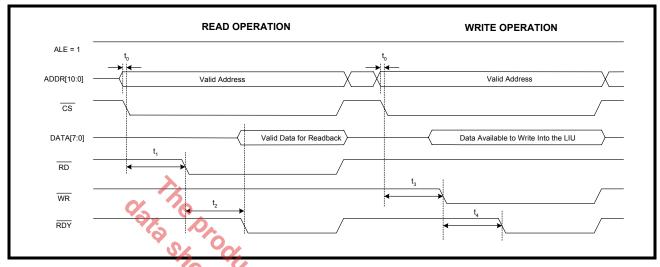


FIGURE 36. INTEL µP INTERFACE SIGNALS DURING PROGRAMMED I/O READ AND WRITE OPERATIONS

TABLE 18: INTEL MICROPROCESSOR INTERFACE TIMING SPECIFICATIONS

SYMBOL	PARAMETER	MIN	Мах	Units
t ₀	Valid Address to CS Falling Edge	0	-	ns
t ₁	CS Falling Edge to RD Assert	65	-	ns
t ₂	RD Assert to RDY Assert	-	90	ns
NA	RD Pulse Width (t ₂)	90	-	ns
t ₃	CS Falling Edge to WR Assert	65	-	ns
t ₄	WR Assert to RDY Assert	1- no	90	ns
NA	WR Pulse Width (t ₄)	90	-	ns
			this the	

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT



6.5 Motorola Mode Programmed I/O Access (Asynchronous)

If the LIU is interfaced to a Motorola type µP, it should be configured to operate in the Motorola mode. Motorola type programmed I/O Read and Write operations are described below.

Motorola Mode Read Cycle

Whenever a Motorola type μP wishes to read the contents of a register, it should do the following.

- 1. Place the address of the target register on the address bus input pins ADDR[7:0].
- 2. While the μP is placing this address value on the address bus, the address decoding circuitry should assert the CS pin of the LIU, by toggling it "Low". This action enables further communication between the μP and the LIU microprocessor interface block.
- **3.** The μP should then toggle the AS pin "Low". This step causes the LIU to latch the contents of the address bus into its internal circuitry. At this point, the address of the register has now been selected.
- Next, the μP should indicate that this current bus cycle is a Read operation by pulling the R/W input pin "High".
- 5. Toggle the DS input pin "Low" This action enables the bi-directional data bus output drivers of the LIU.
- **6.** After the μP toggles the DS signal "Low", the LIU will toggle the DTACK output pin "Low". The LIU does this in order to inform the μP that the data is available to be read by the μP, and that it is ready for the next command.
- After the µP detects the DTACK signal and has read the data, it can terminate the Read Cycle by toggling the DS input pin "High".

Motorola Mode Write Cycle

Whenever a motorola type μ P wishes to write a byte or word of data into a register within the LIU, it should do the following.

- 1. Place the address of the target register on the address bus input pins ADDR[7:0].
- 2. While the μ P is placing this address value on the address bus, the address decoding circuitry should assert the CS pin of the LIU, by toggling it "Low". This action enables further communication between the μ P and the LIU microprocessor interface block.
- **3.** The μP should then toggle the AS pin "Low". This step causes the LIU to latch the contents of the address bus into its internal circuitry. At this point, the address of the register has now been selected.
- Next, the μP should indicate that this current bus cycle is a Write operation by pulling the R/W input pin "Low".
- 5. Toggle the DS input pin "Low". This action enables the bi-directional data bus output drivers of the LIU.
- 6. After the μP toggles the DS signal "Low", the LIU will toggle the DTACK output pin "Low". The LIU does this in order to inform the μP that the data has been written into the internal register location, and that it is ready for the next command.
- After the μP detects the DTACK signal and has read the data, it can terminate the Read Cycle by toggling the DS input pin "High".

The Motorola Read and Write timing diagram is shown in **Figure 37**. The timing specifications are shown in **Table 19**.

FIGURE 37. MOTOROLA 68K μ P INTERFACE SIGNALS DURING PROGRAMMED I/O READ AND WRITE OPERATIONS

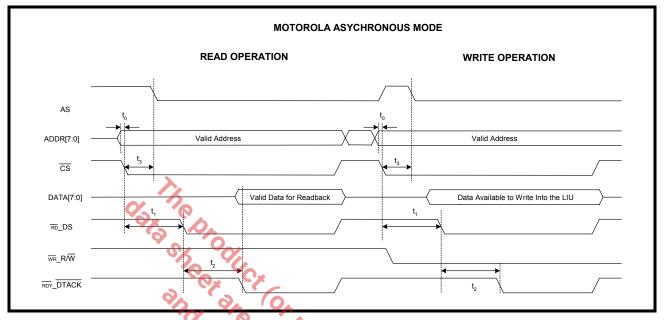


TABLE 19: MOTOROLA 68K MICROPROCESSOR INTERFACE TIMING SPECIFICATIONS

SYMBOL	PARAMETER	Min	ΜΑΧ	Units
t ₀	Valid Address to CS Falling Edge	0	-	ns
t ₁	CS Falling Edge to DS (Pin RD_DS) Assert	65	-	ns
t ₂	DS Assert to DTACK Assert	ny.	90	ns
NA	DS Pulse Width (t ₂)	90	-	ns
t ₃	CS Falling Edge to AS (Pin ALE) Falling Edge	80	· -	ns
			this tured	



REGISTER INFORMATION

Register Number	Address (Hex)	FUNCTION
0 - 15	0x00 - 0x0F	Channel 0 Control Registers
16 - 31	0x10 - 0x1F	Channel 1 Control Registers
32 - 47	0x20 - 0x2F	Channel 2 Control Registers
48 - 63	0x30 - 0x3F	Channel 3 Control Registers
64 - 79	0x40 - 0x4F	Channel 4 Control Registers
80 - 95	0x50 - 0x5F	Channel 5 Control Registers
96 - 111	0x60 - 0x6F	Channel 6 Control Registers
112 - 127	0x70 - 0x7F	Channel 7 Control Registers
128 - 142	0x80 - 0x8E 📀	Global Control Registers Applied to All 8 Channels
192	0xC0	Global Control Register Applied to All 8 Channels
143 - 253	0x8F - 0xFD	R/W Registers Reserved for Testing (Except 0xC0h)
254	0xFE	Device "ID"
255	0xFF	Device "Revision ID"

TABLE 20: MICROPROCESSOR REGISTER ADDRESS (ADDR[7:0])

TABLE 21: MICROPROCESSOR REGISTER CHANNEL DESCRIPTION

Reg	ADDR	Түре	D7	D6	D5	D4	D3	D2	D1	D0
Chan	nel 0 Co	ntrol F	Registers (0	x00 - 0x0F)		~ Q	290	· .		
0	0x00	R/W	QRSS/PRBS	PRBS_Rx/Tx	RxON	EQC4	EQC3	EQC2	EQC1	EQC0
1	0x01	R/W	RxTSEL	TxTSEL	TERSEL1	TERSEL0	JASEL1	JASEL0	JABW	FIFOS
2	0x02	R/W	INVQRSS	TxTEST2	TxTEST1	TxTEST0	TxON	LOOP2	LOOP1	LOOP0
3	0x03	R/W	Reserved	Reserved	CODES	RxRES1	RxRES0	INSBPV	INSBER	Reserved
4	0x04	R/W	Reserved	DMOIE	FLSIE	LCVI/OFE	Reserved	AISDIE	RLOSIE	QRPDIE
5	0x05	RO	Reserved	DMO	FLS	LCV/OF	Reserved	AIS	RLOS	QRPD
6	0x06	RUR	Reserved	DMOIS	FLSIS	LCV/OFIS	Reserved	AISIS	RLOSIS	QRPDIS
7	0x07	RO	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved
8	0x08	R/W	Reserved	1SEG6	1SEG5	1SEG4	1SEG3	1SEG2	1SEG1	1SEG0
9	0x09	R/W	Reserved	2SEG6	2SEG5	2SEG4	2SEG3	2SEG2	2SEG1	2SEG0
10	0x0A	R/W	Reserved	3SEG6	3SEG5	3SEG4	3SEG3	3SEG2	3SEG1	3SEG0
11	0x0B	R/W	Reserved	4SEG6	4SEG5	4SEG4	4SEG3	4SEG2	4SEG1	4SEG0
12	0x0C	R/W	Reserved	5SEG6	5SEG5	5SEG4	5SEG3	5SEG2	5SEG1	5SEG0
13	0x0D	R/W	Reserved	6SEG6	6SEG5	6SEG4	6SEG3	6SEG2	6SEG1	6SEG0
14	0x0E	R/W	Reserved	7SEG6	7SEG5	7SEG4	7SEG3	7SEG2	7SEG1	7SEG0



8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

TABLE 21: MICROPROCESSOR REGISTER CHANNEL DESCRIPTION

Reg	ADDR	Түре	D7	D6	D5	D4	D3	D2	D1	D0	
15	0x0F	R/W	Reserved	8SEG6	8SEG5	8SEG4	8SEG3	8SEG2	8SEG1	8SEG0	
Chan	Channel (1 - 7) Control Registers (0x10 - 0x7F) See Channel 0										
Globa	al Contro	ol Reg	isters for Al	l 8 Channels	6						
128	0x80	R/W	SR/DR	ATAOS	RCLKE	TCLKE	DATAP	Reserved	GIE	SRESET	
129	0x81	R/W	OVFLO/LCV	CLKSEL2	CLKSEL1	CLKSEL0	MCLKrate	RxMUTE	EXLOS	ICT	
130	0x82	R/W	TxONCNTL	TERCNTL	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	
140	0x8C	R/W	Reserved	Reserved	Reserved	Reserved	LCVCH3	LCVCH2	LCVCH1	LCVCH0	
141	0x8D	R/W	Reserved	Reserved	Reserved	allRST	allUPDATE	BYTEsel	chUPDATE	chRST	
142	0x8E	RO	LCVCNT7	LCVCNT6	LCVCNT5	LCVCNT4	LCVCNT3	LCVCNT2	LCVCNT1	LCVCNT0	
192	0xC0	R/W	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	Reserved	E1arben	
R/W F	R/W Registers Reserved for Testing (0x8F - 0xFD) Except 0xC0h										
254	0xFE	RO	Device "ID"	0.0	*						
255	0xFF	RO	Device "Revisi	ion ID"	6						

ID"

EXAR Experience Our Connectivity. REV. 1.0.7

XRT83SH38 8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

		Channel 0-7 (0х00н-0х70н)									
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)							
D7	QRSS/ PRBS	QRSS/PRBS Select Bits These bits are used to select between QRSS and PRBS. 1 = QRSS 0 = PRBS	R/W	0							
D6	PRBS_Rx/ Tx	PRBS Receive/Transmit Select: This bit is used to select where the output of the PRBS Generator is directed if PRBS generation is enabled. 0 = Normal Operation - PRBS generator is output on TTIP and TRING if PRBS generator is output on RPOS; RNEG is internally grounded, if PRBS generation is enabled. Bit 6 = "0" TTIP PBRS Generator Bit 6 = "0" TTIP TRING Bit 6 = "1" RPOS Generator TRING TRING REG NoTE: If PRBS generation is disabled, user should set this bit to '0' for normal operation.	R/W	0							
D5	RxON	Receiver ON/OFF Upon power up, the receiver is powered OFF. RxON is used to turn the receiver ON or OFF if the hardware pin RxON is pulled "High". If the hardware pin is pulled "Low", all receivers are turned off. 0 = Receiver is Powered Off 1 = Receiver is Powered On	RAV	0							
D4 D3 D2 D1 D0	EQC4 EQC3 EQC2 EQC1 EQC0	Equalizer Control Bits The equalizer control bits are shown in Table 23 below.	R/W	0 0 0 0 0							

TABLE 22: MICROPROCESSOR REGISTER 0x00H BIT DESCRIPTION



EQC[4:0]	T1/E1 MODE/RECEIVE SENSITIVITY	TRANSMIT LBO	CABLE	CODING
0x08h	T1 Short Haul/15dB	0 to 133 feet (0.6dB)	100Ω TP	B8ZS
0x09h	T1 Short Haul/15dB	133 to 266 feet (1.2dB)	100Ω TP	B8ZS
0x0Ah	T1 Short Haul/15dB	266 to 399 feet (1.8dB)	100Ω TP	B8ZS
0x0Bh	T1 Short Haul/15dB	399 to 533 feet (2.4dB)	100Ω TP	B8ZS
0x0Ch	T1 Short Haul/15dB	533 to 655 feet (3.0dB)	100Ω TP	B8ZS
0x0Dh	T1 Short Haul/15dB	Arbitrary Pulse	100Ω TP	B8ZS
0x1Ch	E1 Short Haul/15dB	ITU G.703	75Ω Coax	HDB3
0x1Dh	E1 Short Haul/15dB	ITU G.703	120Ω TP	HDB3

TABLE 23: EQUALIZER CONTROL AND TRANSMIT LINE BUILD OUT

TABLE 24: MICROPROCESSOR REGISTER 0x01H BIT DESCRIPTION

	CHANNEL 0-7 (0x01H-0x71H)					
Віт	NAME	Function	Register Type	Default Value (HW reset)		
D7	RxTSEL	Receive Termination Select Upon power up, the receiver is in "High" impedance. RxTSEL is used to switch between the internal termination and "High" imped- ance. 0 = "High" Impedance 1 = Internal Termination	R/W	0		
D6	TxTSEL	Transmit Termination Select Upon power up, the transmitter is in "High" impedance. TXTSEL is used to switch between the internal termination and "High" imped- ance. 0 = "High" Impedance 1 = Internal Termination	R/W	0		
D5 D4	TERSEL1 TERSEL0	Receive Line Impedance Select TERSEL[1:0] are used to select the line impedance for T1/J1/E1. $00 = 100\Omega$ $01 = 110\Omega$ $10 = 75\Omega$ $11 = 120\Omega$	R/W	0 0		
D[3:2]	JASEL[1:0]	Jitter Attenuator Select JASEL[1:0] are used to select the jitter attenuator in the transmit or receive path. 00 = Disabled 01 = Transmit Path 10 = Receive Path 11 = Receive Path	R/W	0		

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT



TABLE 24: MICROPROCESSOR REGISTER 0x01H BIT DESCRIPTION

	CHANNEL 0-7 (0x01H-0x71H)					
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)		
D1	JABW	Jitter Bandwidth (E1 Mode Only, T1 is permanently set to 3Hz) The jitter bandwidth is a global setting that is applied to both the receiver and transmitter jitter attenuator. 0 = 10Hz 1 = 1.5Hz	R/W	0		
D0	FIFOS	FIFO Depth Select The FIFO depth select is used to configure the part for a 32-bit or 64-bit FIFO (within the jitter attenuator blocks). The delay of the FIFO is equal to $\frac{1}{2}$ the FIFO depth. This is a global setting that is applied to both the receiver and transmitter FIFO. 0 = 32-Bit 1 = 64-Bit	R/W	0		

TABLE 25: MICROPROCESSOR REGISTER 0x02H BIT DESCRIPTION

	CHANNEL 0-7 (0x02H-0x72H)					
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)		
D7	INVQRSS	QRSS inversion INVQRSS is used to invert the transmit QRSS pattern set by the TxTEST[2:0] bits. By default, INVQRSS is disabled and the QRSS will be transmitted with normal polarity. 0 = Disabled 1 = Enabled	R/W	0		
D6	TxTEST2	Test Code Pattern	R/W	0		
D5	TxTEST1	TxTEST[2:0] are used to select a diagnostic test pattern to the line	S	0		
D4	TxTEST0	(transmit outputs). 0XX = No Pattern 100 = Tx QRSS 101 = Tx TAOS 110 = Reserved 111 = Reserved	e G	0		



TABLE 25: MICROPROCESSOR REGISTER 0x02H BIT DESCRIPTION

	CHANNEL 0-7 (0x02H-0x72H)					
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)		
D3	TxOn	Transmit ON/OFF Upon power up, the transmitters are powered off. This bit is used to turn the transmitter for this channel On or Off if the TxON pin is pulled "High". If the TxON pin is pulled "Low", all 8 transmitters are powered off. 0 = Transmitter is Powered OFF 1 = Transmitter is Powered ON	R/W	0		
D2	LOOP2	Loopback Diagnostic Select	R/W	0		
D1	LOOP1	LOOP[2:0] are used to select the loopback mode.		0		
D0	LOOPO	0XX = No Loopback 100 = Dual Loopback 101 = Analog Loopback 110 = Remote Loopback 111 = Digital Loopback		0		

TABLE 26: MICROPROCESSOR REGISTER 0x03h BIT DESCRIPTION

	CHANNEL 0-7 (0x03H-0x73H)					
Віт	Nаме	FUNCTION	Register Type	Default Value (HW reset)		
D[7:6]	Reserved	This Register Bit is Not Used.				
D5	CODES	Encoding/Decoding Select (Single Rail Mode Only) 0 = HDB3 (E1), B8ZS (T1) 1 = AMI Coding	R/W	0		
D4	RxRES1	Receive External Fixed Resistor	S R/W	0		
D3	RxRES0	RxRES[1:0] are used to select the value for a high precision exter- nal resistor to improve return loss. 00 = None $01 = 240\Omega$ $10 = 210\Omega$ $11 = 150\Omega$	•	0		
D2	INSBPV	Insert Bipolar Violation When this bit transitions from a "0" to a "1", a bipolar violation will be inserted in the transmitted QRSS/PRBS pattern. The state of this bit will be sampled on the rising edge of TCLK. To ensure proper operation, it is recommended to write a "0" to this bit before writing a "1".	R/W	0		



TABLE 26: MICROPROCESSOR REGISTER 0x03H BIT DESCRIPTION

	CHANNEL 0-7 (0x03H-0x73H)						
Віт	Nаме	FUNCTION	Register Type	Default Value (HW reset)			
D1	INSBER	Insert Bit Error When this bit transitions from a "0" to a "1", a bit error will be inserted in the transmitted QRSS/PRBS pattern. The state of this bit will be sampled on the rising edge of TCLK. To ensure proper operation, it is recommended to write a "0" to this bit before writing a "1".	R/W	0			
D0	Resereved						

TABLE 27: MICROPROCESSOR REGISTER 0x04H BIT DESCRIPTION 0

-

	CHANNEL 0-7(0x04H-0x74H)					
Віт	Nаме	FUNCTION	Register Type	Default Value (HW reset)		
D7	Reserved	This Register Bit is Not Used				
D6	DMOIE	Digital Monitor Output Interrupt Enable 0 = Masks the DMO function 1 = Enables Interrupt Generation	R/W	0		
D5	FLSIE	FIFO Limit Status Interrupt Enable 0 = Masks the FLS function 1 = Enables Interrupt Generation	R/W	0		
D4	LCV/OFIE	Line Code Violation / Counter Overflow Interrupt Enable 0 = Masks the LCV/OF function 1 = Enables Interrupt Generation	R/W	0		
D3	Reserved	This Register Bit is Not Used.	6 07			
D2	AISIE	Alarm Indication Signal Interrupt Enable 0 = Masks the AIS function 1 = Enables Interrupt Generation	R/W	0		
D1	RLOSIE	Receiver Loss of Signal Interrupt Enable 0 = Masks the RLOS function 1 = Enables Interrupt Generation	R/W	0		
D0	QRPDIE	Quasi Random Signal Source Interrupt Enable 0 = Masks the QRPD function 1 = Enables Interrupt Generation	R/W	0		



Note: The GIE bit in the global register 0x80h must be set to "1" in addition to the individual register bits to enable the interrupt pin.

TABLE 28: MICROPROCESSOR REGISTER 0x05H BIT DESCRIPTION

CHANNEL 0-7 (0x05h-0x75h)					
Віт	Nаме	FUNCTION	Register Type	Default Value (HW reset)	
D7	Reserved	This Register Bit is Not Used.			
D6	DMO	Digital Monitor Output The digital monitor output is always active regardless if the inter- rupt generation is disabled. This bit indicates the DMO activity. An interrupt will not occur unless the DMOIE is set to "1" in the chan- nel register 0x04h and GIE is set to "1" in the global register 0x80h. 0 = No Alarm 1 = Transmit output driver has failures	RO	0	
D5	FLS	FIFO Limit Status The FIFO limit status is always active regardless if the interrupt generation is disabled. This bit indicates whether the RD/WR pointers are within 3-Bits. An interrupt will not occur unless the FLSIE is set to "1" in the channel register 0x04h and GIE is set to "1" in the global register 0x80h. 0 = No Alarm 1 = RD/WR FIFO pointers are within ±3-Bits	RO	0	
D4	LCV/OF	Line Code Violation / Counter Overflow This bit serves a dual purpose. By default, this bit monitors the line code violation activity. However, if bit 7 in register 0x81h is set to a "1", this bit monitors the overflow status of the internal LCV counter. An interrupt will not occur unless the LCV/OFIE is set to "1" in the channel register 0x04h and GIE is set to "1" in the global register 0x80h. 0 = No Alarm 1 = A line code violation, bipolar violation, or excessive zeros has occurred	RO	0	
D3	Reserved	This Register Bit is Not Used.	S		
D2	AISD	Alarm Indication Signal The alarm indication signal detection is always active regardless if the interrupt generation is disabled. This bit indicates the AIS activity. An interrupt will not occur unless the AISIE is set to "1" in the channel register 0x04h and GIE is set to "1" in the global regis- ter 0x80h. 0 = No Alarm 1 = An all ones signal is detected	RO	0	

8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

Note: The GIE bit in the global register 0x80h must be set to "1" in addition to the individual register bits to enable the interrupt pin.

	CHANNEL 0-7 (0x05H-0x75H)						
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)			
D1	RLOS	Receiver Loss of Signal The receiver loss of signal detection is always active regardless if the interrupt generation is disabled. This bit indicates the RLOS activity. An interrupt will not occur unless the RLOSIE is set to "1" in the channel register 0x04h and GIE is set to "1" in the global register 0x80h. 0 = No Alarm 1 = An RLOS condition is present	RO	0			
D0	QRPD	Quasi Random Pattern Detection The quasi random pattern detection is always active regardless if the interrupt generation is disabled. This bit indicates that a QRPD has been detected. An interrupt will not occur unless the QRPDIE is set to "1" in the channel register 0x04h and GIE is set to "1" in the global register 0x80h. 0 = No Alarm 1 = A QRP is detected	RO	0			

TABLE 28: MICROPROCESSOR REGISTER 0x05H BIT DESCRIPTION

TABLE 29: MICROPROCESSOR REGISTER 0x06H BIT DESCRIPTION

	CHANNEL 0-7 (0x06H-0x76H)						
Віт	Name	FUNCTION	Register Type	Default Value (HW reset)			
D7	Reserved	This Register Bit is Not Used.	Ü.				
D6	DMOIS	Digital Monitor Output Status 0 = No change 1 = Change in status occurred	RUR	0			
D5	FLSIS	FIFO Limit Status 0 = No change 1 = Change in status occurred	RUR	0			
D4	LCV/OFIS	Line Code Violation / Overflow Status 0 = No change 1 = Change in status occurred	RUR	0			
D3	Reserved	This Register Bit is Not Used.					
D2	AISDIS	Alarm Indication Signal Status 0 = No change 1 = Change in status occurred	RUR	0			





TABLE 29: MICROPROCESSOR REGISTER 0x06H BIT DESCRIPTION

	CHANNEL 0-7 (0x06H-0x76H)					
Віт	Nаме	FUNCTION	Register Type	Default Value (HW reset)		
D1	RLOSIS	Receiver Loss of Signal Status 0 = No change 1 = Change in status occurred	RUR	0		
D0	QRPDIS	Quasi Random Pattern Detection Status 0 = No change 1 = Change in status occurred	RUR	0		

NOTE: Any change in status will generate an interrupt (if enabled in channel register 0x04h and GIE is set to "1" in the global register 0x80h). The status registers are reset upon read (RUR).

TABLE 30: MICROPROCESSOR REGISTER 0x08H BIT DESCRIPTION

	CHANNEL 0-7 (0x08h-0x78h)					
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)		
D7	Reserved	This Register Bit is Not Used	Х	0		
D6	1SEG6	Arbitrary Pulse Generation	R/W	0		
D5	1SEG5	The transmit output pulse is divided into 8 individual segments.		0		
D4	1SEG4	This register is used to program the first segment which corre-		0		
D3	1SEG3	sponds to the overshoot of the pulse amplitude. There are four		0		
D2	1SEG2	segments for the top portion of the pulse and four segments for the bottom portion of the pulse. Segment number 5 corresponds to		0		
D1	1SEG1	the undershoot of the pulse. The MSB of each segment is the sign		0		
D0	1SEG0	bit.	S	0		
		Bit 6 = 0 = Negative Direction				
		Bit 6 = 1 = Positive Direction				

TABLE 31: MICROPROCESSOR REGISTER 0x09H BIT DESCRIPTION

	CHANNEL 0-7 (0x09H-0x79H)				
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)	
D7	Reserved	This Register Bit is Not Used	Х	0	
D[6:0]	2SEG[6:0]	Segment Number Two, Same Description as Register 0x08h	R/W		



TABLE 32: MICROPROCESSOR REGISTER 0x0AH BIT DESCRIPTION

	CHANNEL 0-7 (0x0AH-0x7AH)				
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)	
D7	Reserved	This Register Bit is Not Used	Х	0	
D[6:0]	3SEG[6:0]	Segment Number Three, Same Description as Register 0x08h	R/W		

TABLE 33: MICROPROCESSOR REGISTER 0x0BH BIT DESCRIPTION

	CHANNEL 0-7 (0x0BH-0x7BH)				
Віт	NAME		Register Type	Default Value (HW reset)	
D7	Reserved	This Register Bit is Not Used	Х	0	
D[6:0]	4SEG[6:0]	Segment Number Four, Same Description as Register 0x08h	R/W		

TABLE 34: MICROPROCESSOR REGISTER 0x0CH BIT DESCRIPTION

0

	CHANNEL 0-7 (0x0CH-0x7CH)				
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)	
D7	Reserved	This Register Bit is Not Used	Х	0	
D[6:0]	5SEG[6:0]	Segment Number Five, Same Description as Register 0x08h	R/W		

TABLE 35: MICROPROCESSOR REGISTER 0x0DH BIT DESCRIPTION

		CHANNEL 0-7 (0x0DH-0x7DH)	S. S.	
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)
D7	Reserved	This Register Bit is Not Used	Х	0
D[6:0]	6SEG[6:0]	Segment Number Six, Same Description as Register 0x08h	R/W	



TABLE 36: MICROPROCESSOR REGISTER 0x0EH BIT DESCRIPTION

		CHANNEL 0-7 (0x0EH-0x7EH)		
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)
D7	Reserved	This Register Bit is Not Used	Х	0
D[6:0]	7SEG[6:0]	Segment Number Seven, Same Description as Register 0x08h	R/W	

TABLE 37: MICROPROCESSOR REGISTER 0x0FH BIT DESCRIPTION

	CHANNEL 0-7 (0x0FH-0x7FH)				
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)	
D7	Reserved	This Register Bit is Not Used	Х	0	
D[6:0]	8SEG[6:0]	Segment Number Fight, Same Description as Register 0x08h	R/W		

manon	<i>o</i> ,
norpo	
may no pro	ducis mentioned in this dered (OBS) actual this
	ered maned
	OBS PROMITINE
	- CUT S



REGISTER ADDRESS 0x80H Bit #	NAME	FUNCTION	Register Type	Reset Value
D7	SR/DR	Single-rail/Dual-rail Select: Writing a "1" to this bit configures all 8 channels in the XRT83SH38 to operate in the Single-rail mode. Writing a "0" configures the XRT83SH38 to operate in Dual-rail mode.	R/W	0
D6	ATAOS	Automatic Transmit All Ones Upon RLOS: Writing a "1" to this bit enables the automatic transmission of All "Ones" data to the line for the channel that detects an RLOS condition. Writing a "0" disables this feature.	R/W	0
D5	RCLKE	Receive Clock Edge: Writing a "1" to this bit selects receive output data of all channels to be updated on the negative edge of RCLK. Wring a "0" selects data to be updated on the positive edge of RCLK.	R/W	0
D4	TCLKE	Transmit Clock Edge: Writing a "0" to this bit selects transmit data at TPOS_n/TDATA_n and TNEG_n/CODES_n of all channels to be sampled on the falling edge of TCLK_n. Writing a "1" selects the rising edge of the TCLK_n for sampling.	R/W	0
D3	DATAP	DATA Polarity: Writing a "0" to this bit selects transmit input and receive output data of all channels to be active "High". Writing a "1" selects an active "Low" state.	R/W	0
D2	Reserved			0
D1	GIE	Global Interrupt Enable: Writing a "1" to this bit globally enables interrupt generation for all channels. Writing a "0" disables interrupt generation	R/W	0
D0	SRESET	Software Reset μ P Registers: Writing a "1" to this bit longer than 10 μ s initiates a device reset through the microprocessor interface. All internal circuits are placed in the reset state with this bit set to a "1" except the microprocessor register bits.	& R/W	0

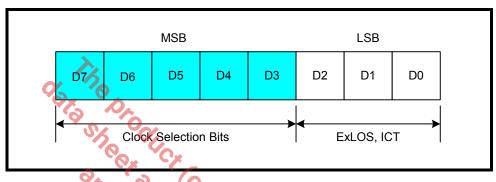
TABLE 38: MICROPROCESSOR REGISTER 0x80H, BIT DESCRIPTION



CLOCK SELECT REGISTER

The input clock source is used to generate all the necessary clock references internally to the LIU. The microprocessor timing is derived from a PLL output which is chosen by programming the Clock Select Bits and the Master Clock Rate in register 0x81h. Therefore, if the clock selection bits or the MCLRATE bit are being programmed, the frequency of the PLL output will be adjusted accordingly. During this adjustment, it is important to "Not" write to any other bit location within the same register while selecting the input/output clock frequency. For best results, register 0x81h can be broken down into two sub-registers with the MSB being bits D[7:3] and the LSB being bits D[2:0] as shown in Figure 38. Note: Bit D[7] is a reserved bit.

FIGURE 38. REGISTER 0x81H SUB REGISTERS



Programming Examples:

Example 1: Changing bits D[7:3]

If bits D[7:3] are the only values within the register that will change in a WRITE process, the microprocessor only needs to initiate ONE write operation

Example 2: Changing bits D[2:0]

If bits D[2:0] are the only values within the register that will change in a WRITE process, the microprocessor only needs to initiate ONE write operation.

Example 3: Changing bits within the MSB and LSB

In this scenario, one must initiate TWO write operations such that the MSB and LSB do not change within ONE write cycle. It is recommended that the MSB and LSB be treated as two independent sub-registers. One can either change the clock selection (MSB) and then change bits D[2:0] (LSB) on the SECOND write, or vice-versa. No order or sequence is necessary.



REGISTER ADDRESS 0x81H BIT #	NAME	FUNCTION	Register Type	Reset Value
D7	Reserved		R/W	0
D6	CLKSEL2	Clock Select Inputs for Master Clock Synthesizer bit 2: In Host mode, CLKSEL[2:0] are input signals to a programma- ble frequency synthesizer that can be used to generate a mas- ter clock from an external accurate clock source according to the following table; MCLKE1 MCLKT1 CLKSEL2 CLKSEL1 CLKSEL0 MCLKRATE CLKOUT/ kHz CLKSEL2 CLKSEL1 CLKSEL0 MCLKRATE CLKOUT/ kHz		0
	0	2048 2048 0 0 0 0 2048		
		2048 2048 0 0 0 1 1544		
	6	2048 1544 0 0 0 0 2048		
	Č.			
		1544 1544 0 0 1 0 2048		
		2048 1544 0 0 1 1 1544		
	Q	8 0 X 0 0 1 0 0 2048		
		16 X 0 1 1 0 2048		
		16 X 0 1 1 1 1544		
		56 X 1 0 0 0 2048		
		56 X 1 0 0 1 1544		
		64 X 1 0 0 2048		
		64 X 01 0 1 1 1544		
		128 X 10 0 2048		
		128 X 1 1 0 1 1544		
		256 X 1 1 0 2048		
		256 X 1 1 1 1544 In Hardware mode, the state of these signals are ignored and the master frequency PLL is controlled by the corresponding Hardware pins. Hardware pins.		
D5	CLKSEL1	Clock Select inputs for Master Clock Synthesizer bit 1.	NW	0
D4	CLKSEL0	Clock Select inputs for Master Clock Synthesizer bit 0: See description of bit D6 for function of this bit.	R/W	0
D3	MCLKRATE	Master clock Rate Select: The state of this bit programs the Master Clock Synthesizer to generate the T1/J1 or E1 clock. The Master Clock Synthesizer will generate the E1 clock when MCLKRATE = "0", and the T1/J1 clock when MCLKRATE = "1".	R/W	0
D2	RXMUTE	Receive Output Mute: Writing a "1" to this bit, mutes receive outputs at RPOS/RDATA and RNEG/LCV pins to a "0" state for any channel that detects an RLOS condition. <i>Note:</i> RCLK is not muted.	R/W	0

TABLE 39: MICROPROCESSOR REGISTER 0x81H, BIT DESCRIPTION



TABLE 39: MICROPROCESSOR REGISTER 0x81H, BIT DESCRIPTION

D1	EXLOS	Extended LOS: Writing a "1" to this bit extends the number of zeros at the receive input of each channel before RLOS is declared to 4096 bits. Writing a "0" reverts to the normal mode (175+75 bits for T1 and 32 bits for E1).	R/W	0
D0	ICT	In-Circuit-Testing: Writing a "1" to this bit configures all the output pins of the chip in high impedance mode for In-Circuit-Testing. Setting the ICT bit to "1" is equivalent to connecting the Hardware ICT pin 88 to ground.	R/W	0

TABLE 40: MICROPROCESSOR REGISTER 0x82H BIT DESCRIPTION

GLOBAL REGISTER (0x82h)						
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)		
D7	TxONCNTL	Transmit On Control 0 = Control of receive termination is set; if in Hardware mode, by RxTSEL Pins If in Host mode by the RxTsel bit 0 = Control of Transmitter is set ; if Hardware mode, by TxON pin if Host mode, by TxON bit 1 = Control of transmitter on, is determined by the individual chan- nel TxOn bits	R/W	0		
D6	TERCNTL	Receive Termination Select Control This bit sets the LIU to control the RxTSEL function with either the individual channel register bit or the global hardware pin. 0 = Control of the receive termination is set tby Hardware-Host bit or Hardware pin and individual software 1 = Control of the receive termination is set to the hardware pin	R/W	0		
D[5:0]	Reserved	These Register Bits are Not Used	6			

FXAR Experience Our Connectivity... REV. 1.0.7

XRT83SH38 8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

		GLOBAL REGISTER (0x8CH)		
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)
D[7:4]	Reserved	Tese Register Bits are Not Used	R/W	0
D3 D2 D1 D0	LCVCH3 LCVCH2 LCVCH1 LCVCH0	Line Code Violation Counter Select These bits are used to select which channel is to be addressed for reading the contents in register 0x8Eh. It is also used to address the counter for a given channel when performing an update or reset on a per channel basis. By default, Channel 0 is selected. 0000 = None 0001 = Channel 0 0010 = Channel 1 0011 = Channel 2 0100 = Channel 3 0101 = Channel 4 0110 = Channel 5 0111 = Channel 6 1000 = Channel 7	R/W	0 0 0

TABLE 41: MICROPROCESSOR REGISTER 0x8CH BIT DESCRIPTION

10 TABLE 42: MICROPROCESSOR REGISTER 0x8DH BIT DESCRIPTION

1

	GLOBAL REGISTER (0x8DH)								
Віт	NAME	NAME FUNCTION Register Type							
D7	Reserved	This Register Bit is Not Used	R/W	0					
D6	Reserved	This Register Bit is Not Used	R/W	0					
D5	Reserved	This Register Bit is Not Used	R/W	0					
D4	allRST	LCV Counter Reset for All Channels This bit is used to reset all internal LCV counters to their default state 0000h. This bit must be set to "1" for 1µS. 0 = Normal Operation 1 = Resets all Counters	R/W	0					
D3	allUPDATE	LCV Counter Update for All Channels This bit is used to latch the contents of all 8 counters into holding registers so that the value of each counter can be read. The chan- nel is addressed by using bits D[3:0] in register 0x8Ch. 0 = Normal Operation 1 = Updates all Counters	R/W	0					



8-CHANNEL T1/E1/J1 SHORT-HAUL LINE INTERFACE UNIT

TABLE 42: MICROPROCESSOR REGISTER 0x8DH BIT DESCRIPTION

	GLOBAL REGISTER (0x8DH)							
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)				
D2	BYTEsel	LCV Counter Byte Select This bit is used to select the MSB or LSB for Reading the contents of the LCV counter for a given channel. The channel is addressed by using bits D[3:0] in register 0x8Ch. By default, the LSB byte is selected. 0 = Low Byte 1 = High Byte	R/W	0				
D1	chUPDATE	LCV Counter Update Per Channel This bit is used to latch the contents of the counter for a given channel into a holding register so that the value of the counter can be read. The channel is addressed by using bits D[3:0] in register 0x8Ch. 0 = Normal Operation 1 = Updates the Selected Channel	R/W	0				
D0	chRESET	LCV Counter Reset Per Channel This bit is used to reset the LCV counter of a given channel to its default state 0000h. The channel is addressed by using bits D[3:0] in register 0x8Ch. This bit must be set to "1" for 1μ S. 0 = Normal Operation. 1 = Resets the Selected Channel.	R/W	0				

TABLE 43: MICROPROCESSOR REGISTER 0x8EH BIT DESCRIPTION

	GLOBAL REGISTER (0x8EH)								
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)					
D7	LCVCNT7	Line Code Violation Byte Contents	R/W	0					
D6	LCVCNT6	These bits contain the LCV counter contents of the Byte selected	•	0					
D5	LCVCNT5	by bit D2 in register 0x8Dh for a given channel. The channel is		0					
D4	LCVCNT4	addressed by using bits D[3:0] in register 0x8Ch. By default, the	0						
D3	LCVCNT3	contents contain the LSB, however no channel is selected		0					
D2	LCVCNT2			0					
D1	LCVCNT1			0					
D0	LCVCNT0			0					



TABLE 44: MICROPROCESSOR REGISTER 0xC0H BIT DESCRIPTION

	GLOBAL REGISTER (0xC0H)						
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)			
D[7:1]	Reserved	These register bits are not used.	R/W	0			
D0	E1Arben	E1 Arbitrary Pulse Enable This bit is used to enable the Arbitrary Pulse Generators for shap- ing the transmit pulse shape when E1 mode is selected. If this bit is set to "1", all 8 channels will be configured for the Arbitrary Mode. However, each channel is individually controlled by pro- gramming the channel registers 0xn8 through 0xnF, where n is the number of the channel. "0" = Disabled (Normal E1 Pulse Shape ITU G.703) "1" = Arbitrary Pulse Enabled	R/W	0			

TABLE 45: MICROPROCESSOR REGISTER 0XFEH BIT DESCRIPTION

Віт	NAME	FUNCTION	Register Type	Default Value (HW rese
D7	Device "ID"	The device "ID" of the XRT83SH38 short haul LIU is 0xF5h. Along	RO	1
D6		with the revision "ID", the device "ID" is used to enable software to		1
D5		identify the silicon adding flexibility for system control and debug.		1
D4				1
D3				0
D2		Con la Con		1
D1				0
D0			**	1

TABLE 46: MICROPROCESSOR REGISTER 0xFFH BIT DESCRIPTION

	REVISION "ID" REGISTER (0xFFH)							
Віт	NAME	FUNCTION	Register Type	Default Value (HW reset)				
D7 D6 D5 D4 D3 D2	Revision "ID"	The revision "ID" of the XRT83SH38 LIU is used to enable soft- ware to identify which revision of silicon is currently being tested. The revision "ID" for the first revision of silicon will be 0x01h.	RO	0 0 0 0 0				
D1 D0				0 1				



ELECTRICAL CHARACTERISTICS

TABLE 47: ABSOLUTE MAXIMUM RATINGS

Storage Temperature	-65°C to +150°C
Operating Temperature	-40°C to +85°C
Supply Voltage	-0.5V to +3.8V
Vin	-0.5V to +5.5V

TABLE 48: DC DIGITAL INPUT AND OUTPUT ELECTRICAL CHARACTERISTICS

VDD=3.3V ±5%, T _A =25°C, UNLESS OTHERWISE SPECIFIED								
	SYMBOL	Min	Түр	Мах	Units			
Power Supply Voltage	VDD	3.13	3.3	3.46	V			
Input High Voltage	ViH	2.0	-	5.0	V			
Input Low Voltage	VIL	-0.5	-	0.8	V			
Output High Voltage IOH=2.0mA	Voн	2.4	-		V			
Output Low Voltage IOL=2.0mA	V _{OL}	0	-	0.4	V			
Input Leakage Current	120	70 - 04	-	±10	μA			
Input Capacitance	C _I		5.0		pF			
Output Lead Capacitance	CL	On - Cin	0,-	25	pF			

NOTE: Input leakage current excludes pins that are internally pulled "Low" or "High"

TABLE 49: AC ELECTRICAL CHARACTERISTICS

VDD=3.3V ±5%, T _A =25°C, UNLESS OTHERWISE SPECIFIED						
PARAMETER	SYMBOL	Min	Түр	MAX	Units	
MCLKin Clock Duty Cycle		40	-	60	%	
MCLKin Clock Tolerance		-	±50	-	ppm	



	VDD=3.3V ±5%, T _A =25°C, UNLESS OTHERWISE SPECIFIED								
Mode	SUPPLY Voltage	IMPEDANCE	Receiver	TRANSMITTER	Түр	ΜΑΧ	Unit	TEST CONDITION	
E1	3.3V	75Ω	1:1	1:2	1.059 1.422	-	W	50% ones 100% ones	
E1	3.3V	120Ω	1:1	1:2	0.974 1.264	-	W	50% ones 100% ones	
T1	3.3V	100Ω	1:1	1:2	1.465 1.904	-	W	50% ones 100% ones	

TABLE 50: POWER CONSUMPTION

VDD=3.3V ±5%, T _A =25°C, UNLESS OTHERWISE SPECIFIED					
PARAMETER	Min	Түр	Мах	Unit	TEST CONDITION
Receiver Loss of Signal	nd are	0,			
Number of consecutive zeros before RLOS is declared	May	32	CHUCES		
Input signal level at RLOS	15	24	0, 5	dB	Cable attenuation @ 1024kHz
RLOS clear	12.5	20	OR.	% ones	ITU-G.775, ETSI 300 233
Receiver Sensitivity (short haul with cable loss)	11	-	dered	dB	With nominal pulse amplitude of $3.0V$ for 120Ω and $2.37V$ for 75Ω with -18dB interference signal added.
Input Impedance	-	13	-	kΩ	in the
Input Jitter Tolerance				9	
1Hz	37	-	-	UI _{p-p}	ITU-G.823
10kHz - 100kHz	0.2	-	-	UI _{p-p}	· Ø
Recovered Clock Jitter					
Transfer Corner Frequency	-	36	-	kHz	ITU-G.736
Peaking Amplitude	-	-	-0.5	dB	
Jitter Attenuator Corner Fre-					
quency	-	10	-	Hz	ITU-G.736
JABW = 0	-	1.5	-	Hz	
JABW = 1					
Return Loss					
51kHz - 102kHz	14	-	-	dB	ITU-G.703
102kHz - 2048kHz	20	-	-	dB	
2048kHz - 3072kHz	16	-	-	dB	



VDD=3.3V ±5%, T _A =25°C, UNLESS OTHERWISE SPECIFIED					
Parameter	Min	Түр	MAX	Unit	TEST CONDITION
Receiver Loss of Signal					
Number of consecutive zeros before RLOS is declared	160	175	190		
Input signal level at RLOS	15	24	-	dB	Cable attenuation @ 772kHz
RLOS clear	12.5	-	-	% ones	ITU-G.775, ETSI 300 233
Receiver Sensitivity (short hauk with cable loss)	12	-	-	dB	With nominal pulse amplitude of 3.0V for 100Ω termination.
Input Impedance	0	13	-	kΩ	
Input Jitter Tolerance 1Hz 10kHz - 100kHz	138 0.4	6	-	UI _{p-p} UI _{p-p}	AT&T Pub 62411
Recovered Clock Jitter Transfer Corner Frequency Peaking Amplitude	nay no	9.8	_ 0.1	kHz dB	TR-TSY-000499
Jitter Attenuator Corner Fre- quency	_ ~	6 6 6	5 3	Hz	AT&T Pub 62411
Return Loss 51kHz - 102kHz 102kHz - 2048kHz 2048kHz - 3072kHz	- - -	20 25 25	eing ne	dB dB dB	
			(OS)	S SCIL	n this tea

TABLE 52: T1 RECEIVER ELECTRICAL CHARACTERISTICS



VDD=3.3V ±5%, T _A =25°C, UNLESS OTHERWISE SPECIFIED					
PARAMETER	Min	Түр	Мах	Unit	TEST CONDITION
AMI Output Pulse Amplitude					
75Ω	2.13	2.37	2.60	V	1:2 Transformer
120Ω	2.70	3.00	3.30	V	
Output Pulse Width	224	244	264	ns	
Output Pulse Width Ratio	0.95	-	1.05		ITU-G.703
Output Pulse Amplitude Ratio	0.95	-	1.05		ITU-G.703
Jitter Added by the Transmitter Output	0	0.025	0.05	UI _{p-p}	Broad Band with jitter free TCLK applied to the input.
Output Return Loss	Nr.				
51kHz - 102kHz	8 0	-	-	dB	ETSI 300 166, CHPTT
102kHz - 2048kHz	014	.	-	dB	
2048kHz - 3072kHz 💦	10		-	dB	
	9.10				

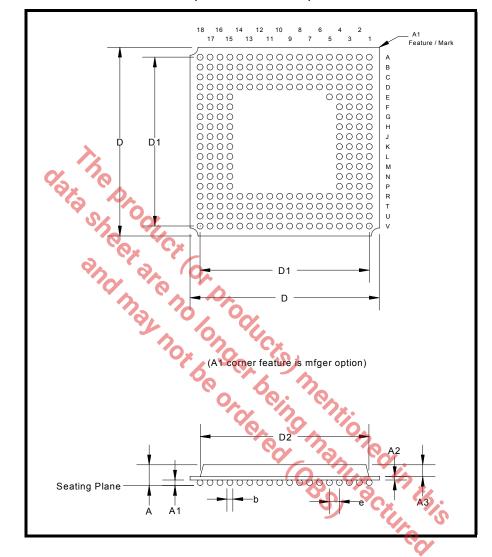
TABLE 53: E1 TRANSMITTER ELECTRICAL CHARACTERISTICS

0 TABLE 54: 11 TRANSMITTER ELECTRICAL CHARACTERISTICS

VDD=3.3V ±5%, T _A =25°C, UNLESS OTHERWISE SPECIFIED					
PARAMETER	Min	Түр	MAX	Unit	TEST CONDITION
AMI Output Pulse Amplitude	2.4	3.00	36	V	1:2 Transformer measured at DSX-1
Output Pulse Width	338	350	362	ns	ANSI T1.102
Output Pulse Width Imbalance	-	-	20	73.7	ANSI T1.102
Output Pulse Amplitude Imbal- ance	-	-	±200	mV	ANSI T1.102
Jitter Added by the Transmitter Output	-	0.025	0.05	UI _{p-p}	Broad Band with jitter free TCLK applied to the input.
Output Return Loss 51kHz - 102kHz	_	15	-	dB	.0
102kHz - 2048kHz 2048kHz - 3072kHz	-	15 15		dB dB	



PACKAGE DIMENSIONS



225 BALL PLASTIC BALL GRID ARRAY (BOTTOM VIEW) (19.0 x 19.0 x 1.0mm)

	INC	HES	MILLIM	LIMETERS	
SYMBOL	MIN	MAX	MIN	MAX	
А	0.049	0.096	1.24	2.45	
A1	0.016	0.024	0.40	0.60	
A2	0.013	0.024	0.32	0.60	
A3	0.020	0.048	0.52	1.22	
D	0.740	0.756	18.80	19.20	
D1	0.669 BSC		17.00	BSC	
D2	0.665	0.669	16.90	17.00	
b	0.020	0.028	0.50	0.70	
е	0.039	BSC	1.00	BSC	

Note [.]	The	control	dimension	is	in	millimeter.
noie.	1110	001101	unnension	13		mmmeter.

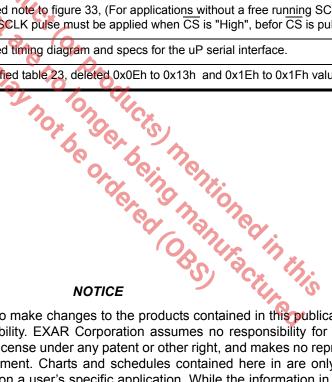


ORDERING INFORMATION

PART NUMBER	Package	OPERATING TEMPERATURE RANGE
XRT83SH38IB	225 Ball BGA	-40 [°] C to +85 [°] C

REVISIONS

REVISION #	DATE	DESCRIPTION
1.0.0	12/15/05	Release to production
1.0.1	01/04/05	Removed TRATiO, Gain control section, text edits.
1.0.2	4/19/06	Corrected referenced hex bits in register 0x05 bit4, LCV/OF. (0xE5h to 0x81h & 0xE0h to 0x80h.) Changed logo format.
1.0.3	5/30/06	Replaced TBD in power consumption table with typical numbers.
1.0.4	7/17/06	Pin number correction, changed SDO pin number from A6 to R7
1.0.5	08/0306	Added note to figure 33, (For applications without a free running SCLK, a minimum of 1 SCLK pulse must be applied when CS is "High", befor CS is pulled "Low".
1.0.6	08/11/06	Added timing diagram and specs for the uP serial interface.
1.0.7	09/08/06	Modified table 23, deleted 0x0Eh to 0x13h and 0x1Eh to 0x1Fh values for EQC[4:0].



EXAR Corporation reserves the right to make changes to the products contained in this publication in order to improve design, performance or reliability. EXAR Corporation assumes no responsibility for the use of any circuits described herein, conveys no license under any patent or other right, and makes no representation that the circuits are free of patent infringement. Charts and schedules contained here in are only for illustration purposes and may vary depending upon a user's specific application. While the information in this publication has been carefully checked; no responsibility, however, is assumed for inaccuracies.

EXAR Corporation does not recommend the use of any of its products in life support applications where the failure or malfunction of the product can reasonably be expected to cause failure of the life support system or to significantly affect its safety or effectiveness. Products are not authorized for use in such applications unless EXAR Corporation receives, in writing, assurances to its satisfaction that: (a) the risk of injury or damage has been minimized; (b) the user assumes all such risks; (c) potential liability of EXAR Corporation is adequately protected under the circumstances.

Copyright 2006 EXAR Corporation

Datasheet September 2006.

Reproduction, in part or whole, without the prior written consent of EXAR Corporation is prohibited.